Generalized finite element approaches for analysis of localized non-linear thermo-mechanical effects

To the memory of Prof. Ted Belytschko

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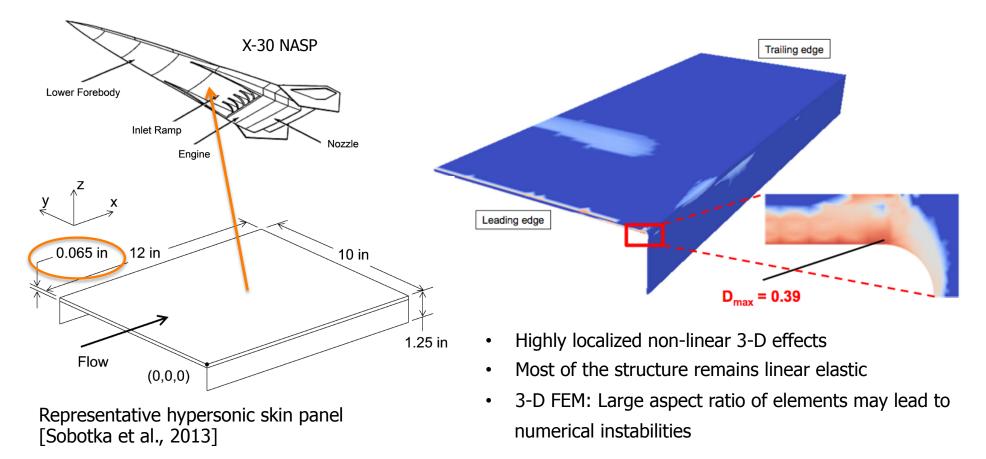
Presented at the 8<sup>th</sup> International Workshop on Meshfree Methods for PDEs Bonn, Germany, September, 2015

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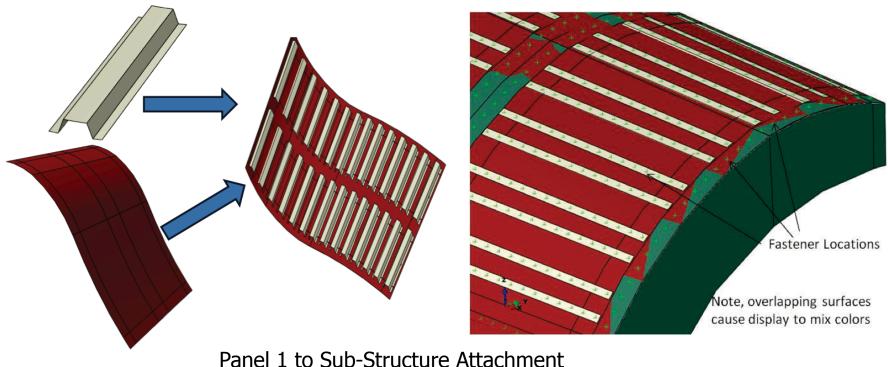
# Motivation: Multiscale Structural Analysis

 Thermo, mechanical and acoustic loads on hypersonic aircrafts lead to highly localized non-linear stress fields: 3-D finite element models with fine meshes are required





- Hypersonic aircraft panels are assembled from sub-components using hundreds of fasteners or spot welds.
- Multiple spatial scales: Skin panel, stiffeners, spot welds.



Panel 1 to Sub-Structure Attachment [AFRL-RB-WP-TR-2012-0280]

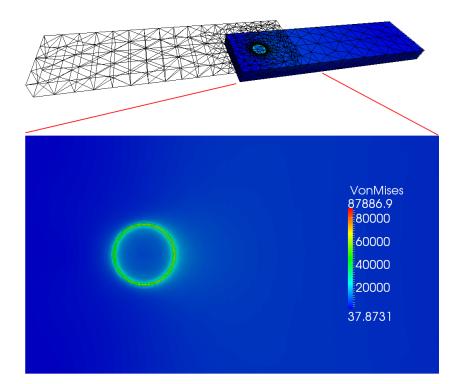


## Motivation: Multiscale Structural Analysis

- Representation of a spot weld in the FEM requires detailed meshing.
- Hundreds of spot welds in one single panel: Not feasible to mesh them all.
- Multi-point constraint is used instead in the industry: This leads to mesh dependent solutions even far from spot welds!

#### Strategy:

- Formulate a two-scale GFEM for this class of problems;
- Keep global mesh *coarse* and resolve spot welds through enrichment functions computed in parallel.



3-D Adaptive FEM mesh and von Mises stress in a lap joint with a spot weld



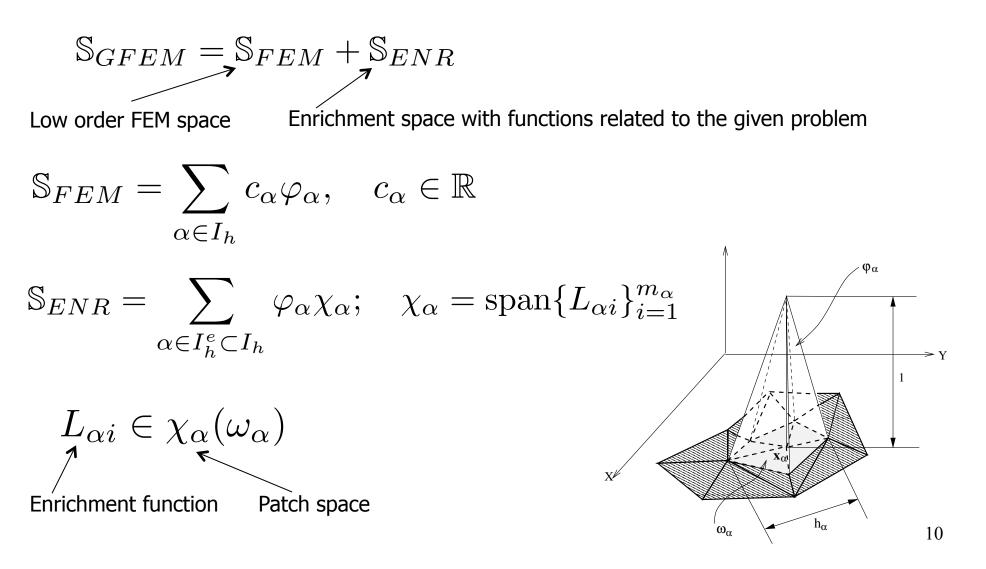
- Motivation
- Generalized finite element methods: Basic ideas
- Bridging scales with GFEM:
  - Global-local enrichments for heat equation and nonlinear thermo-mechanical problems
- Numerical examples
- Conclusions





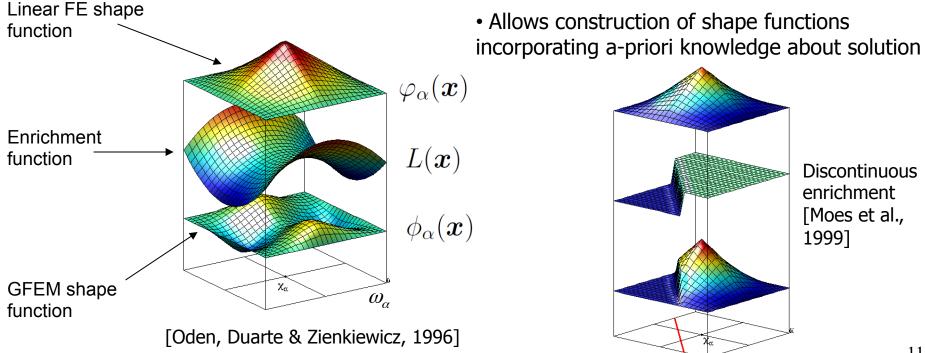
# **Generalized Finite Element Method**

• GFEM is a Galerkin method with special test/trial space given by



# **Generalized Finite Element Method**

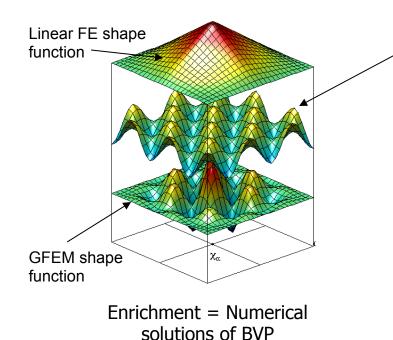
$$S_{ENR} = \sum_{\alpha \in I_h^e \subset I_h} \varphi_\alpha \chi_\alpha; \quad \chi_\alpha = \operatorname{span}\{L_{\alpha i}\}_{i=1}^{m_\alpha}$$
$$\phi_{\alpha i}(x) = \varphi_\alpha(x) L_{\alpha i}(x) \qquad \sum_{\alpha} \varphi_\alpha(x) = 1$$





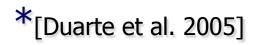
## Bridging Scales with Global-Local Enrichment Functions\*

Enrichment functions computed from solution of local boundary value problems: <u>Global-Local enrichment functions</u>



```
    Idea: Use available numerical solution at a
simulation step to build shape functions for next
step (quasi-static, transient, non-linear, etc.)
```

- Enrichment functions are produced numerically on-the-fly through a global-local analysis
- Use a *coarse* mesh enriched with Global-Local (GL) functions
- GFEM<sup>gl</sup> = GFEM with global-local enrichments





$$\rho c \frac{\partial u}{\partial t} = \nabla (\kappa(\boldsymbol{x}) \nabla u) + Q(\boldsymbol{x}, t) \quad \text{in} \quad \Omega$$

where  $u(\boldsymbol{x},t)$  is the temperature field,  $\rho c$  is the volumetric heat capacity and  $Q(\boldsymbol{x},t)$  is the internal heat source.  $\kappa(\boldsymbol{x})$  may be oscillatory.

$$-\kappa \frac{\partial u}{\partial n} = \eta (\bar{u} - u) \quad \text{on} \quad \Gamma_c$$
  
 $-\kappa \frac{\partial u}{\partial n} = \bar{f} \quad \text{on} \quad \Gamma_f$   
 $u(\boldsymbol{x}, 0) = u^0(\boldsymbol{x}) \quad \text{at} \quad t^0$ 

where  $u^0(\boldsymbol{x})$  is the prescribed temperature field at time  $t = t^0$ 



## Domain Subjected to Sharp Laser Flux

**Goal**: Solve with GFEM<sup>gl</sup> on the mesh shown below Local material heterogeneity:  $\kappa_a = 50 \kappa_b$ GFEM<sup>gl</sup> global mesh Sharp (Gaussian), localized heat flux Laser flux: applied as shown  $\bar{f}(\boldsymbol{x},t) = I_0 * f(t) * \frac{1}{2\pi a^2} * G(\boldsymbol{x},b,a)$ 7  $f(t) = 1 - \exp(-\gamma * t)$  $G(\boldsymbol{x}, b, a) = \exp\left(\frac{-(x-b)^2}{2a^2}\right)$ Angle 4 0.2 0.8

0.4

0.6

Location

0.8

1 0

**Convection BCs applied everywhere else** 

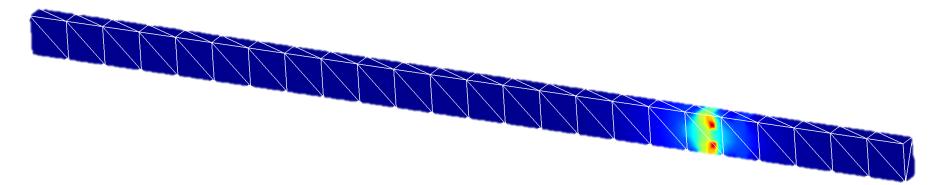
0.6

0.4

0.2



Let  $u_G^n(\boldsymbol{x}) \in \mathbb{S}_G^{GFEM,n}(\Omega)$  be the GFEM solution at time  $t = t^n = n\Delta t$ 

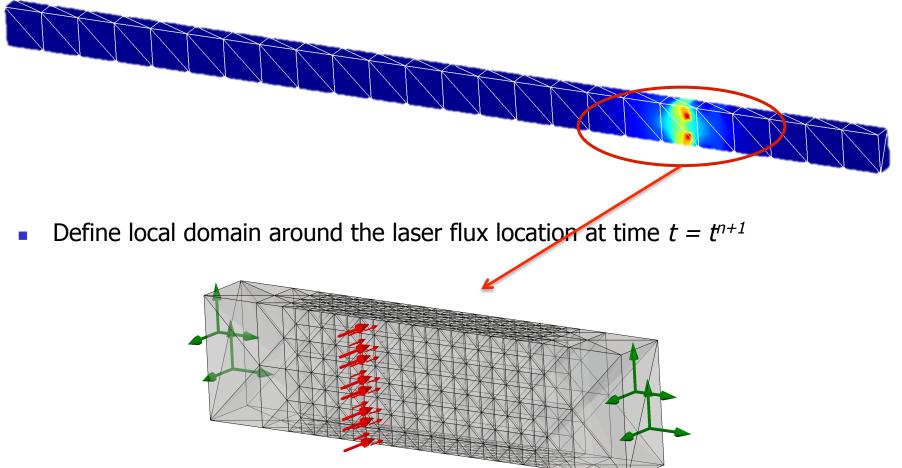


Find  $u_G^n \in \mathbb{S}_G^{\text{GFEM},n}(\Omega_G)$  such that,  $\forall w_G^n \in \mathbb{S}_G^{\text{GFEM},n}(\Omega_G)$ 

$$\frac{\rho c}{\Delta t} \int_{\Omega} w_{G}^{n} u_{G}^{n} d\Omega + \int_{\Omega} \left( \nabla w_{G}^{n} \right)^{T} \kappa \nabla u_{G}^{n} d\Omega + \eta \int_{\Gamma_{c}} w_{G}^{n} u_{G}^{n} d\Gamma = \frac{\rho c}{\Delta t} \int_{\Omega} w_{G}^{n} u_{G}^{n-1} d\Omega + \int_{\Gamma_{f}} \bar{f}^{n} w_{G}^{n} d\Gamma + \eta \int_{\Gamma_{c}} \bar{u}^{n} w_{G}^{n} d\Gamma + \int_{\Omega} Q^{n} w_{G}^{n} d\Omega$$

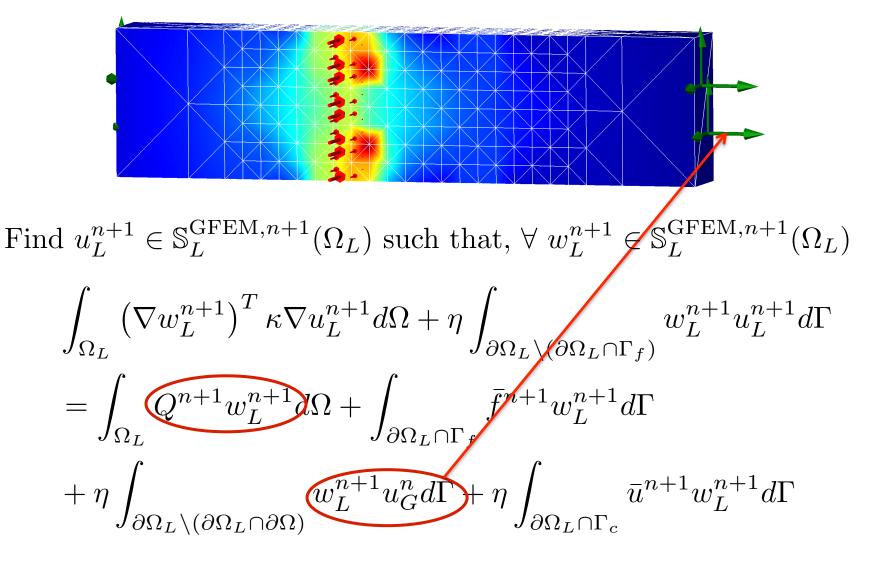


Let  $u_G^n(\boldsymbol{x}) \in \mathbb{S}_G^{GFEM,n}(\Omega)$  be the GFEM solution at time  $t = t^n = n\Delta t$ 



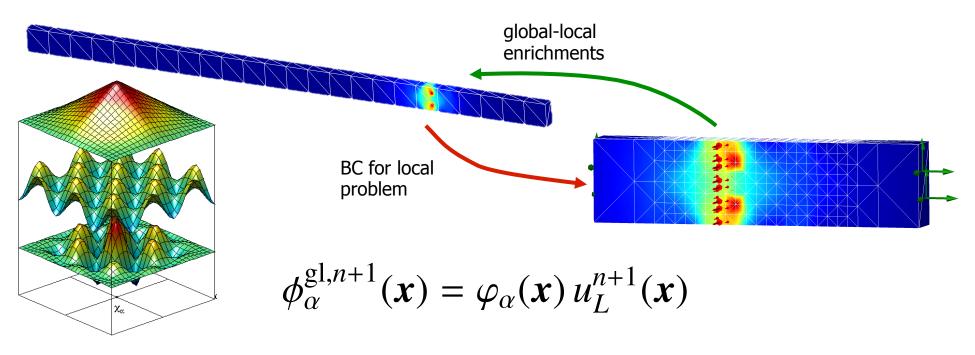


• Solve following *local problem* at time  $t = t^{n+1}$  using, e.g., *hp*-GFEM





• Defining Step: Global space is enriched with local solutions

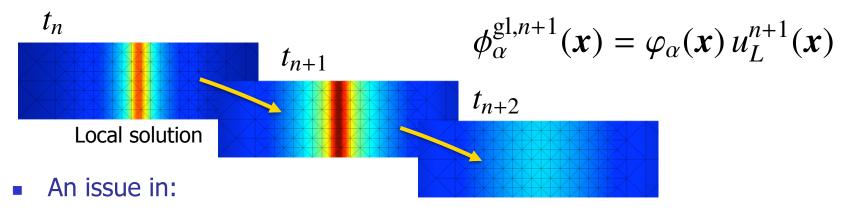


Find 
$$u_G^{n+1}(\boldsymbol{x}) \in \mathbb{S}_G^{\text{GFEM},n+1}(\Omega) = \mathbb{S}_G^{\text{FEM}} + \left\{ \varphi_{\alpha} u_{\alpha}^{\text{gl},n+1}, \ \alpha \in \mathcal{I}^{\text{gl}} \right\}$$
  
where  $u_{\alpha}^{\text{gl},n+1}(\boldsymbol{x}) = \underline{u}_{\alpha} u_L^{n+1}(\boldsymbol{x}) \in \chi_{\alpha}^{n+1}, \ \underline{u}_{\alpha} \in \mathbb{R}$ 

• Discretization spaces updated on-the-fly with global-local enrichment functions



 Updating local solutions at each step leads to time- or load-dependency of global-local enrichments and approximation spaces:



- Transient problems: How to formulate time integration scheme? (O'Hara et al. 2010)
- Nonlinear problems: How to start Newton-Raphson iteration when solution space changes? Solution vector at load step (n) cannot be used with shape functions at load step (n+1)
- This is also an issue in
  - analytically defined enrichment functions if they are added/deleted between time/load steps
  - adaptive FEMs



Nonlinear solution based on incremental load steps: 

$$\mathbf{u}_{n+1} = \mathbf{u}_n + \Delta \mathbf{u}_{n+1} \qquad \sigma(\mathbf{u}_{n+1}) = \sigma(\mathbf{u}_{n+1})$$
Shape functions at previous time step
Shape functions at current time step

$$\mathbf{c}_{\text{current time step}}$$
Shape functions at current time step

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Shape functions at current time step

$$\mathbf{c}_{\text{current time step}} = \mathbf{c}_{\text{current time step}} =$$

$$\boldsymbol{\sigma}(\mathbf{u}_{n+1}) = \boldsymbol{\sigma}(\mathbf{u}_n + \Delta \mathbf{u}_{n+1})$$

unload

**6** 

Elastic reload

εe

3

# Time-dependent GFEM Spaces: Elasto-plastic materials

- Solution vector at load step (n) cannot be used with shape functions at load step (n+1)
- Solve a *linear elastic* "predictor" problem to get the total solution at load step (n+1) using shape functions for step (n+1)

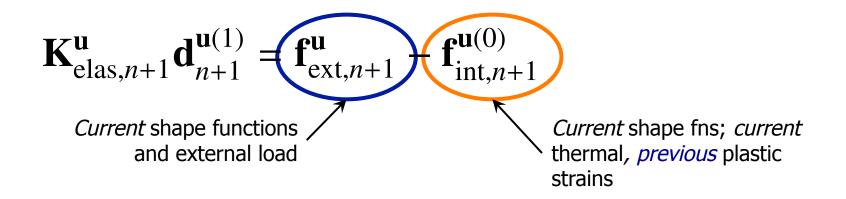
$$\int_{\Omega^{\mathbf{u}}} \boldsymbol{\varepsilon}(\mathbf{u}_{n+1}^{(1)}) \colon \mathbf{C} \colon \boldsymbol{\varepsilon}(\delta\mathbf{u}) \,\mathrm{d}\Omega + \eta \int_{\Gamma^{\mathbf{u}}} \mathbf{u}_{n+1}^{(1)} \cdot \delta\mathbf{u} \,\mathrm{d}\Gamma = \int_{\Gamma^{\mathbf{t}}} \bar{\mathbf{t}}_{n+1} \cdot \delta\mathbf{u} \,\mathrm{d}\Gamma$$
$$+ \eta \int_{\Gamma^{\mathbf{u}}} \bar{\mathbf{u}}_{n+1} \cdot \delta\mathbf{u} \,\mathrm{d}\Gamma + \int_{\Omega^{\mathbf{u}}} (\boldsymbol{\varepsilon}_{n}^{p} + \boldsymbol{\varepsilon}_{n+1}^{\theta}) \colon \mathbf{C} \colon \boldsymbol{\varepsilon}(\delta\mathbf{u}) \,\mathrm{d}\Omega$$

- Discretize using *Current* shape functions: n+1 step
- RHS uses: *Current* external loads and thermal strains, *previous* plastic strains

$$\mathbf{u}_{n+1}^{(1)} = \bar{\mathbf{N}}_{n+1}^{\mathbf{u}} \mathbf{d}_{n+1}^{\mathbf{u}(1)}$$
$$\boldsymbol{\varepsilon}_{n+1}^{(1)} = \bar{\mathbf{B}}_{n+1}^{\mathbf{u}} \mathbf{d}_{n+1}^{\mathbf{u}(1)}$$



 Solve a *linear elastic* "predictor" problem to get the total solution at load step (n+1) using shape functions for step (n+1)

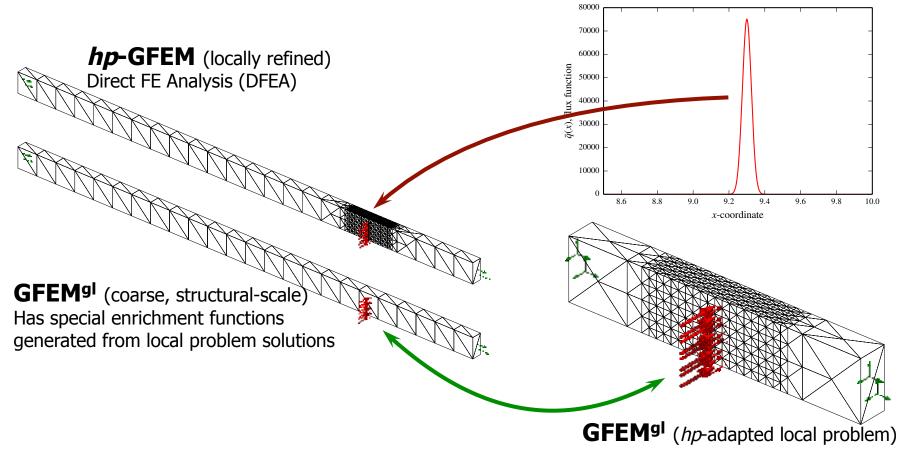


- Yields predictor for total solution at initial Newton iteration
- Solution provides initial guess for Newton-Raphson at step (n+1)
- No interpolation of quantities between meshes like in adaptive FEM
- All information available at integration points which are NOT time-dependent



# Numerical example: Laser-heated beam

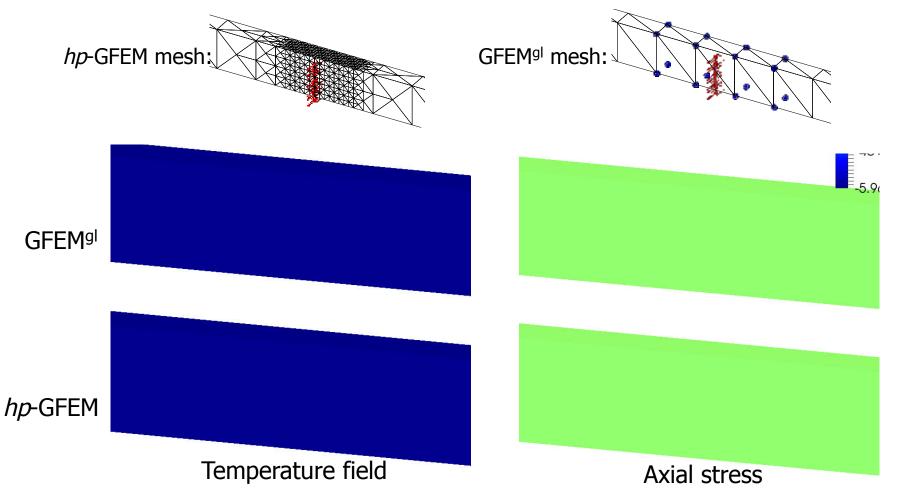
Coupon beam subjected to transient Gaussian laser heating





# Numerical example: Laser-heated beam

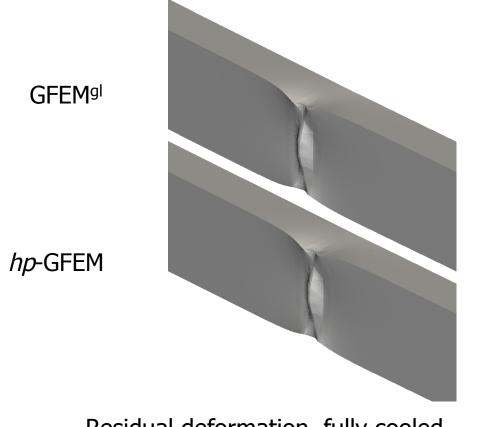
• **Case 1:** Stationary sharp heating, then cooling to room temperature





## Numerical example: Laser-heated beam

• **Case 1:** Stationary sharp heating, then cooling to room temperature



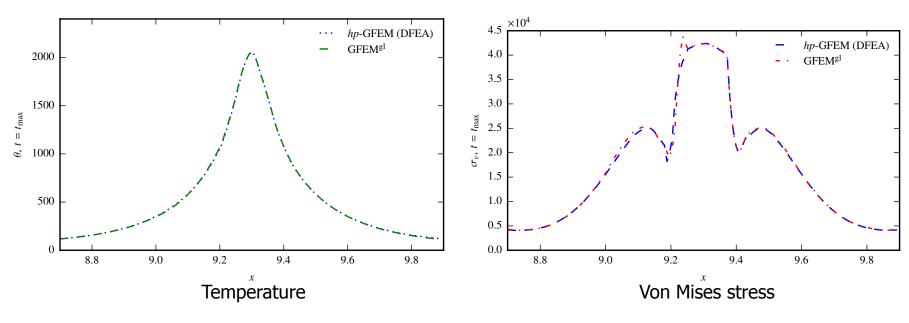
GFEM<sup>gl</sup> mesh

GFEM<sup>gl</sup> captures localized temperature gradients, stresses, and residual deformations on a **coarsescale, uniform mesh**.

Residual deformation, fully cooled



• GFEM<sup>gl</sup> vs. direct (*hp*-GFEM) analysis:

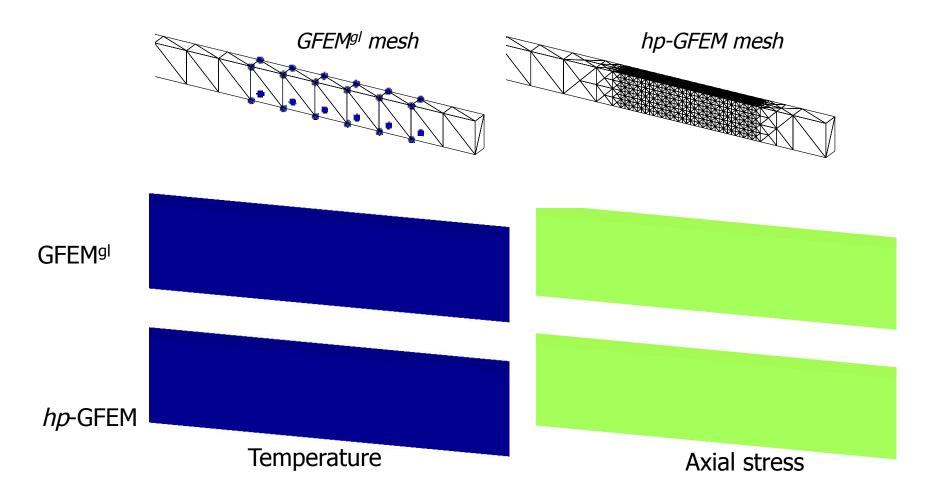


• Pointwise quantities at maximum load/temperature:

<---->

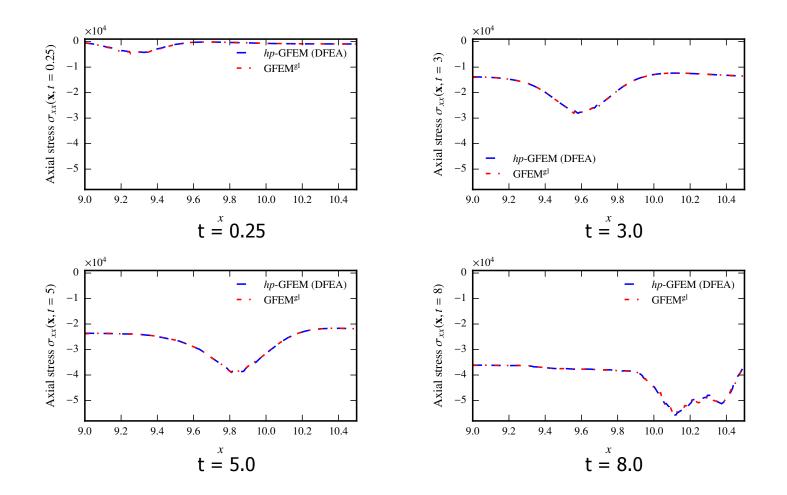


• **Case 2:** Moving sharp flux



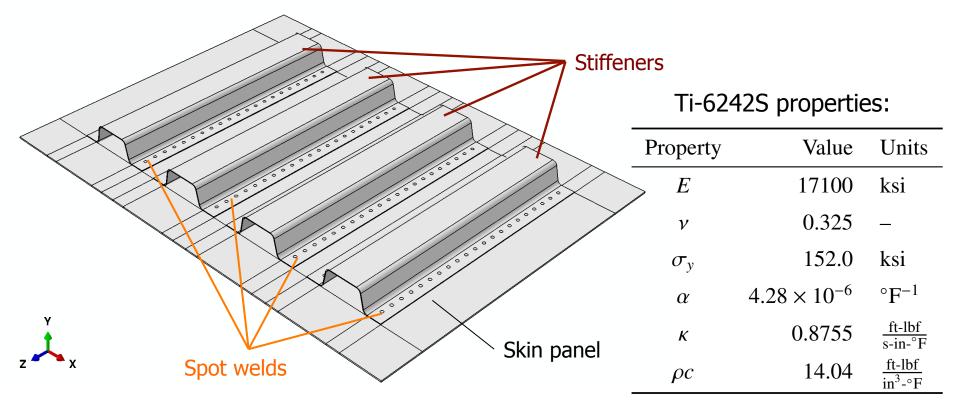


GFEM<sup>gl</sup> vs. *hp*-GFEM solutions in time: Axial stress





• Stiffened panel with 168 spot welds\*



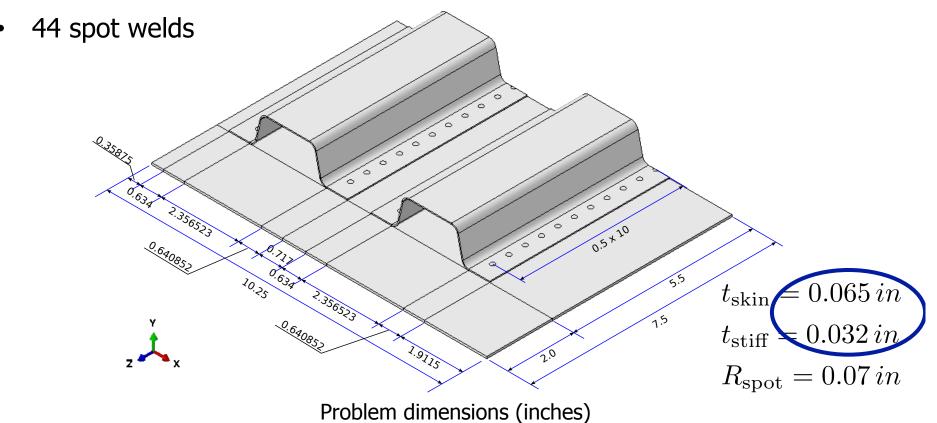
- Represent spot welds using global-local enrichments
- Use a *coarse mesh* at global scale

\*Panel geometry and properties courtesy of Air Force Research Laboratory, OH, USA



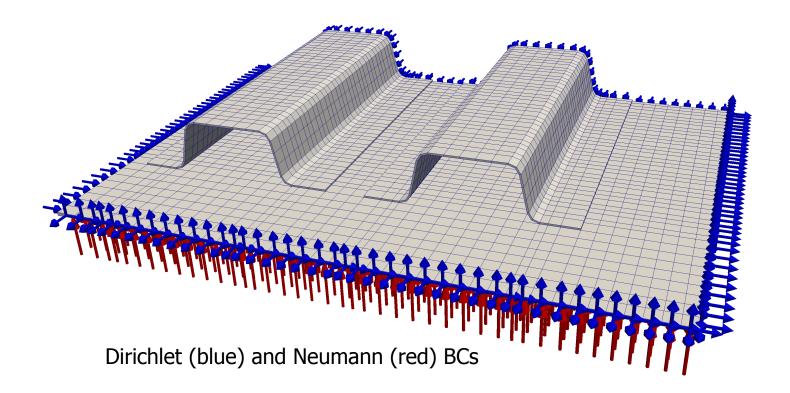
**Case 1:** Mechanical load only: Uniform pressure on skin panel

- Linear elastic response
- Use symmetry properties to reduce problem size



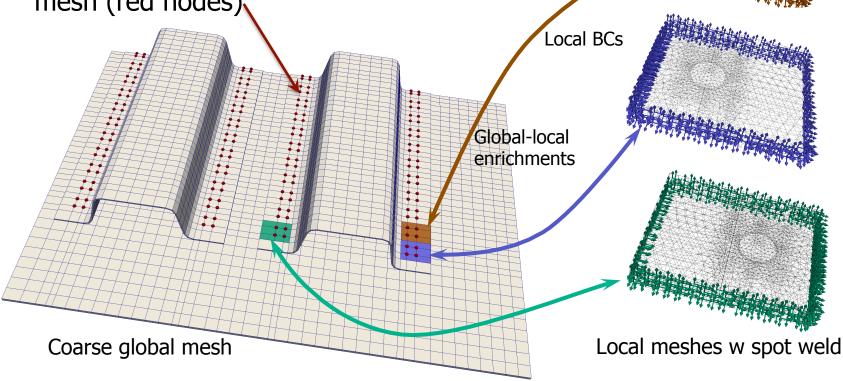


Global mesh with hexahedron elements: Spot welds are *not* discretized at this scale



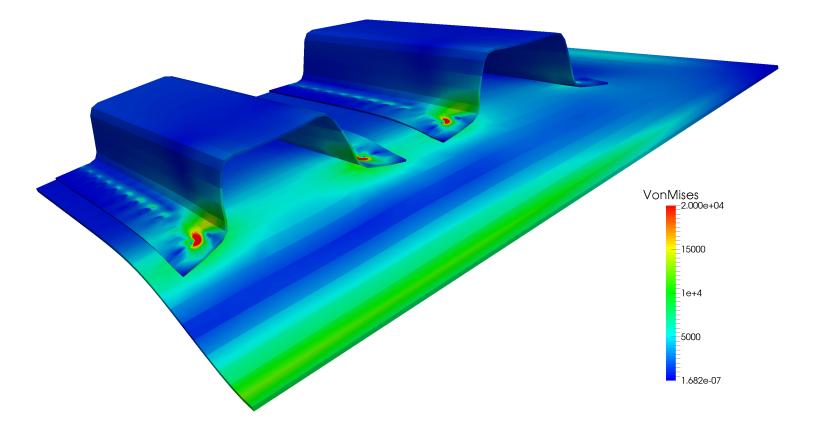


- Global problem provides BCs for local problems
- Define and solve in **parallel**, a local problem for each spot weld
- Use local solutions as enrichments in global mesh (red nodes)





• GFEM<sup>gl</sup> results: Deformed configuration and von Mises stress

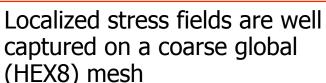


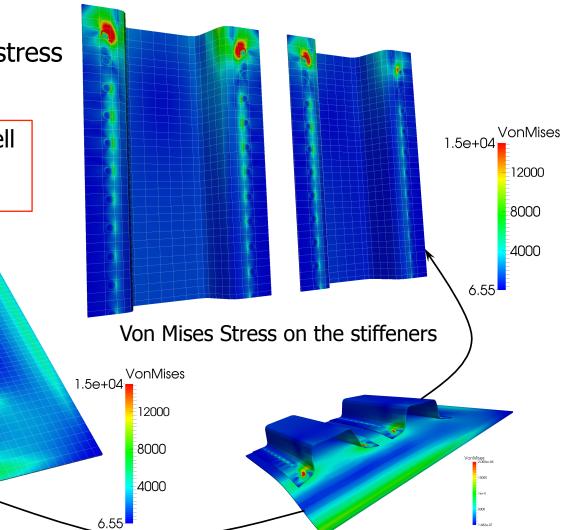
**Enriched** global problem, deformed shape and Von Mises stress



• GFEM<sup>gl</sup> results: Von Mises stress

captured on a coarse global (HEX8) mesh

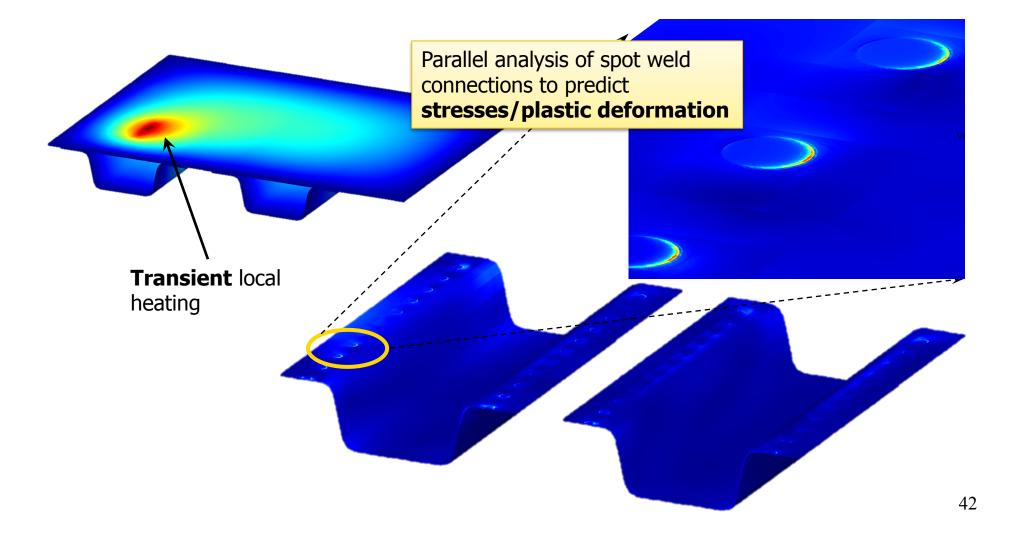




Von Mises Stress on the skin panel

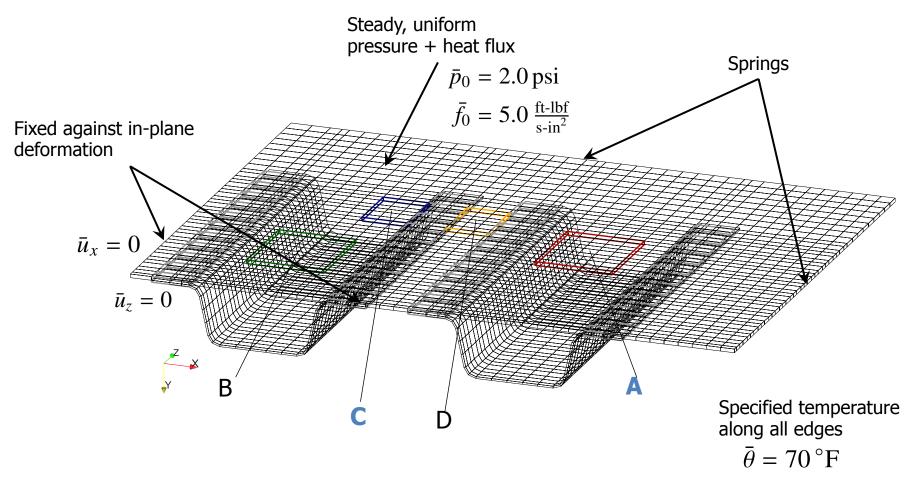


• **Case 2:** Transient nonlinear thermo-mechanical analysis





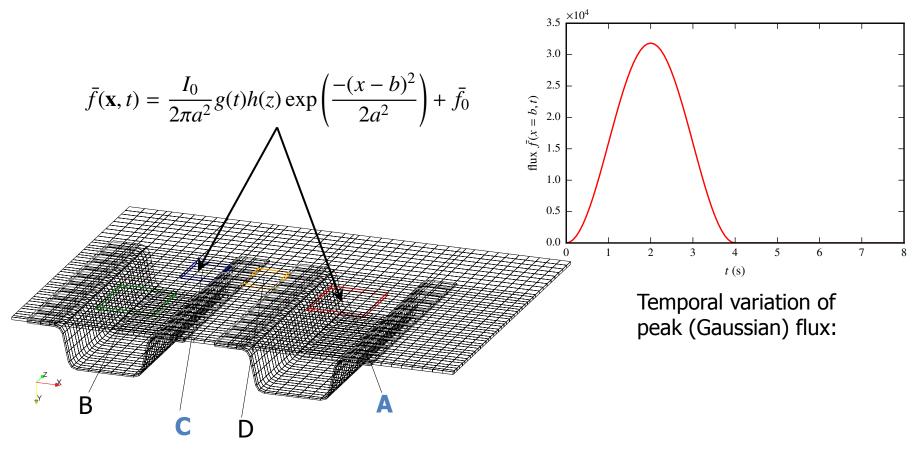
#### • **Case 2:** Boundary conditions





Goal: Find critical location of a localized thermal load

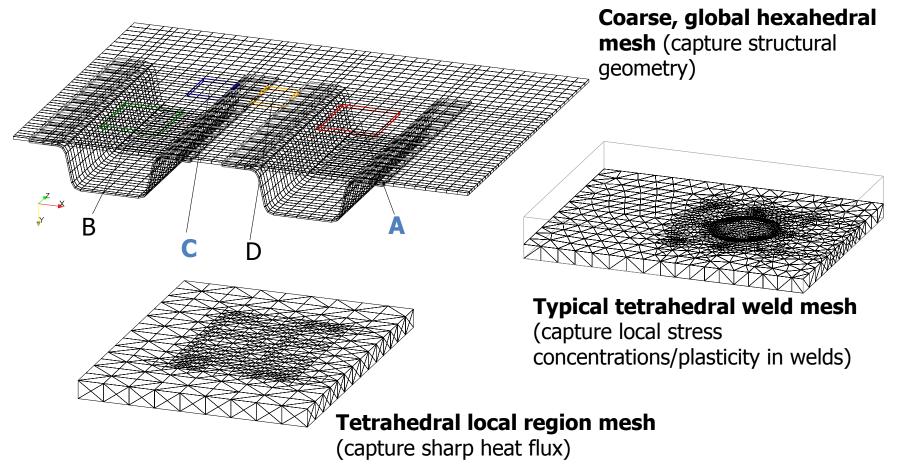
Localized, transient heat flux in Regions A and C:





# GFEM<sup>gl</sup> Solution of a Hat-Stiffened Panel

- GFEM<sup>gl</sup> global + local meshes
- Same global mesh as before





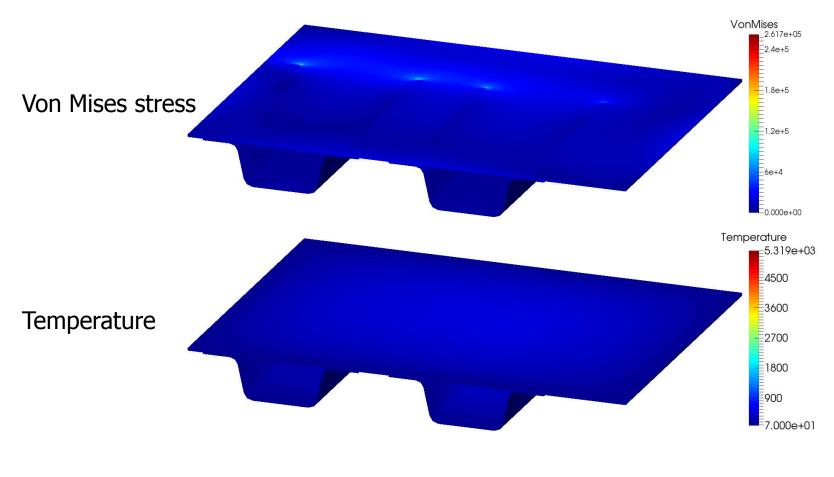
 Panel/stiffeners connected by series of 44 spot welds GFEM<sup>gl</sup> global + local problem sizes

	Problem size (dofs)		-
	Heat transfer	Thermoplasticity	
Initial global	27,888	209,160	Only ~1,000 extra global
Enriched global (A)	28,480	210,936	dofs from global-local
Enriched global (C)	28,436	210,804	enrichments (< 1% increase)
Local Full spot weld	7,966	95,592	
Half-spot weld	4,179	50,148	
Region A	5,807	69,684	
Region C	5,965	71,580	

Estimated *hp*-GFEM/hp-FEM (direct analysis) problem size  $\approx$  4.5 million dofs



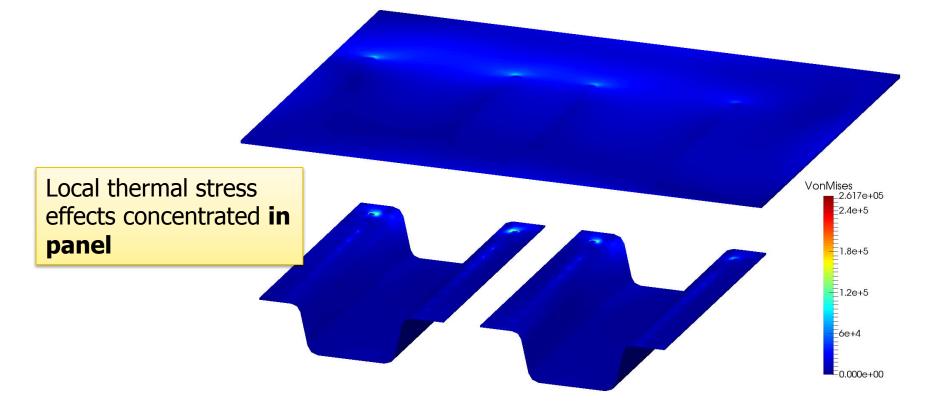
Region A





#### Region A

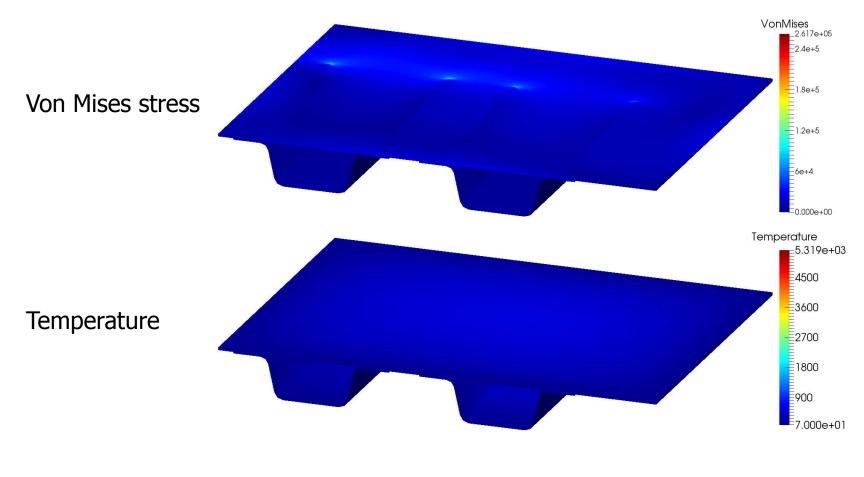
Von Mises stress (panel + stiffeners)



Movie



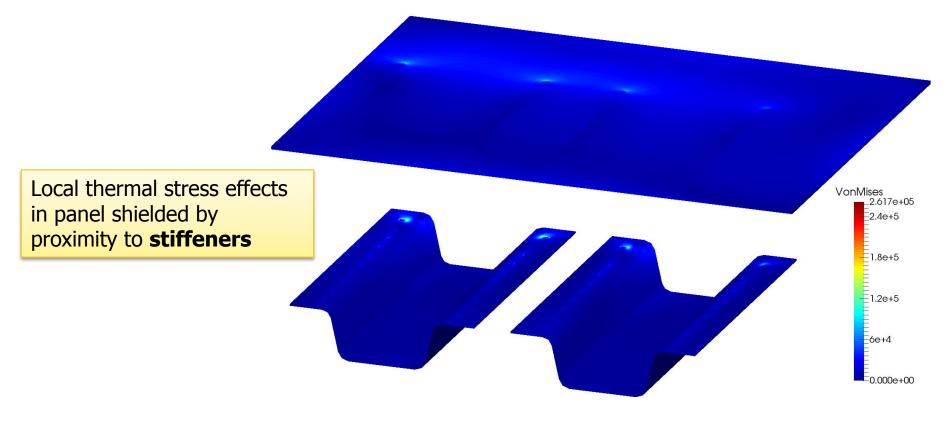
Region C





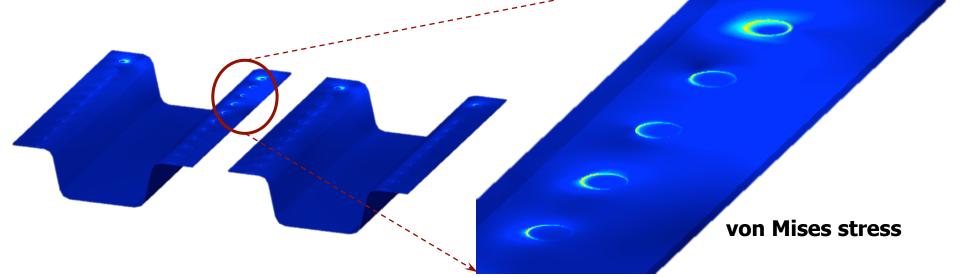
### • Region C

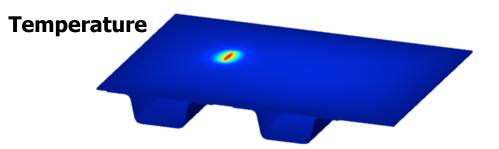
Von Mises stress (panel + stiffeners)





- Region C
  - t = 2.0s (maximum thermal load)



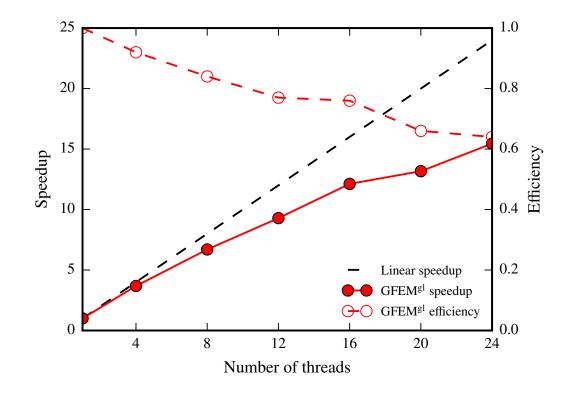


Localized spot weld stresses in vicinity of sharp heating

# GFEM<sup>gl</sup> Solution of a Hat-Stiffened Panel

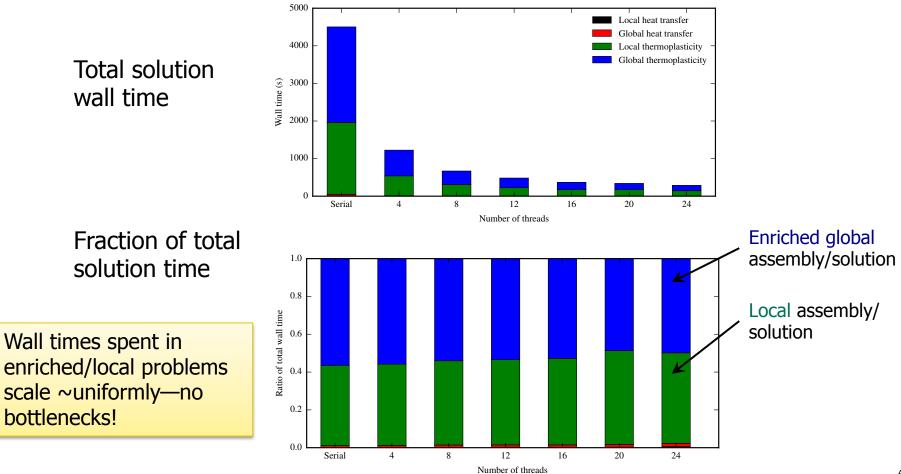
- GFEM<sup>gl</sup> parallel performance
  - Single time/load step—all solution phases (local + enriched global) considered
  - Up to 24 CPUs
  - Good speedup on small number of threads
  - Efficiency deteriorates as number of CPUs increases (expected)

Number of local problems ≈ number of threads difficult to achieve good load balance





- GFEM<sup>gl</sup> parallel performance
  - Time spent in each solution phase vs. number of parallel threads:





- GFEM<sup>gl</sup> for large, nonlinear, coupled thermo-structural problems exhibiting phenomena spanning multiple spatial scales of interest
- Time-dependent global—local enrichments for capturing nonlinear (elasto-plastic) effects at disparate structural scales
- Fine-scale problems parallelizable; efficiently resolve localized plasticity at the fine scale, maintain coarse, global structural mesh

## Acknowledgements

## Jongheon Kim, Haoyang Li and Patrick O'Hara







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http://gfem.cee.illinois.edu/