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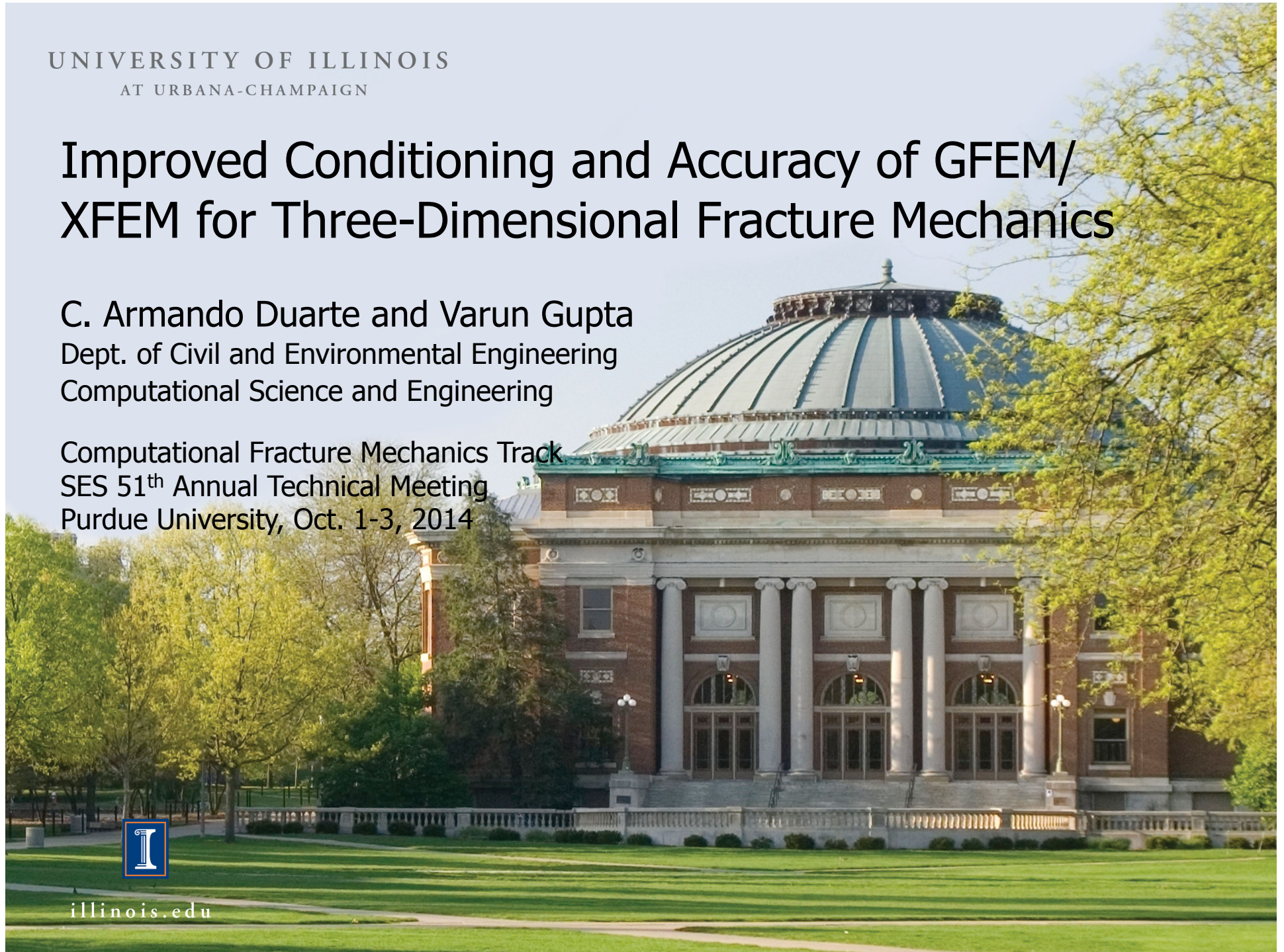
# Improved Conditioning and Accuracy of GFEM/ XFEM for Three-Dimensional Fracture Mechanics

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Computational Fracture Mechanics Track  
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# Acknowledgements

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¶Department of Mathematics, Syracuse University

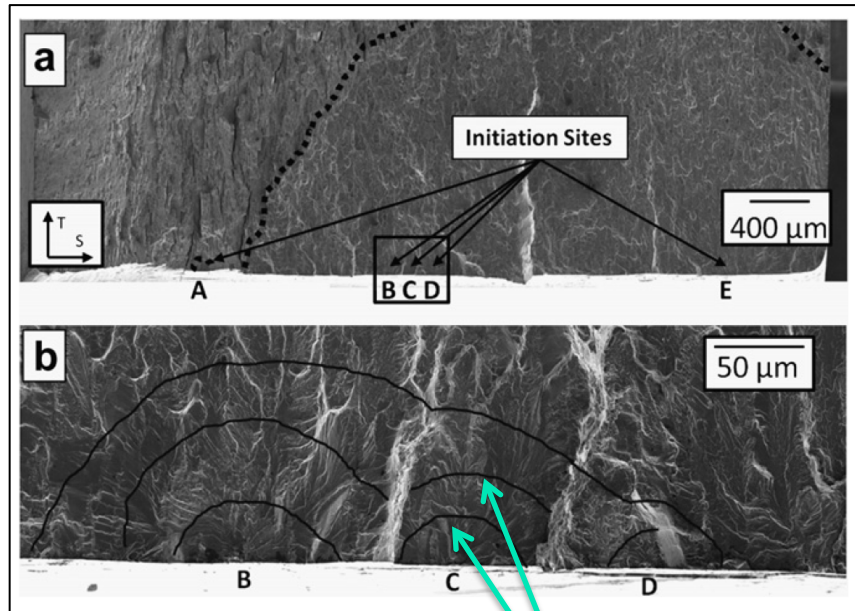




# Motivation: Simulation of 3-D Crack Coalescence

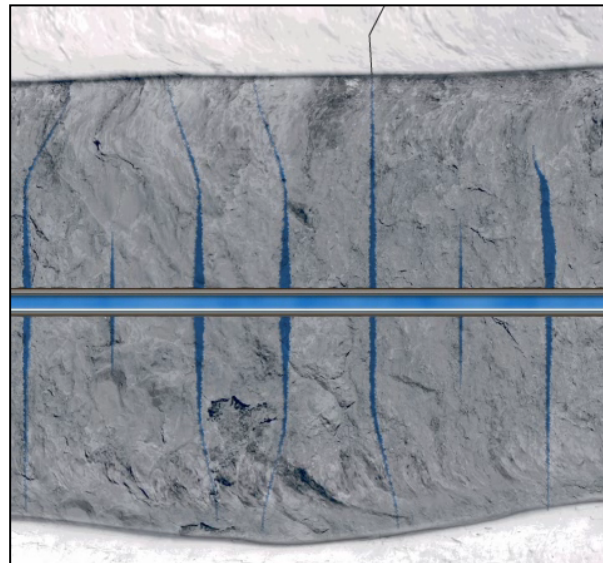
- Modeling and simulation of crack coalescence is of great importance in many applications

Coalescence of fatigue micro-cracks



Crack fronts

Hydraulic fractures from horizontal well



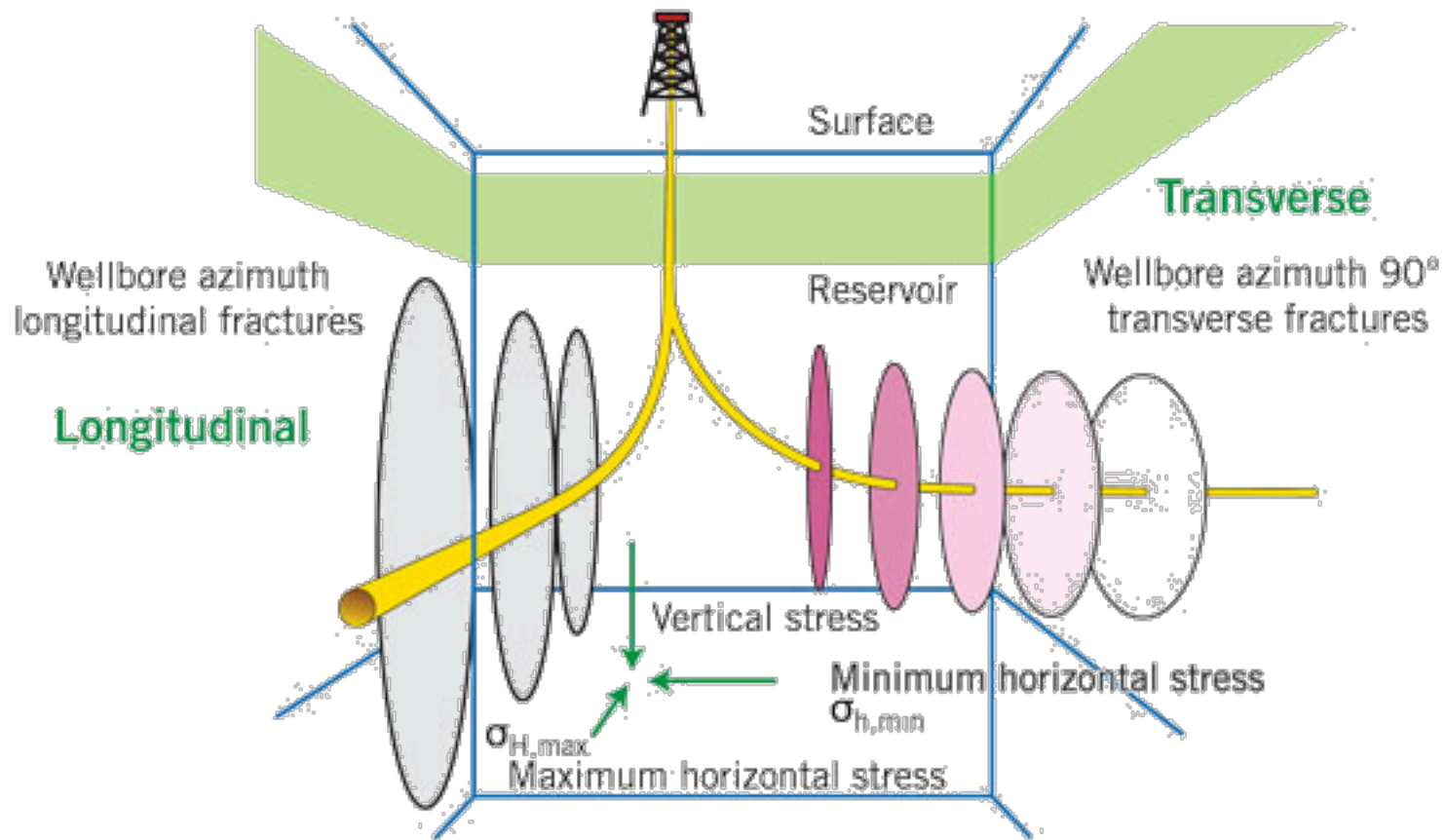
Reflective crack in asphalt overlay





# Coalescence of Hydraulic Fractures

## FRACTURE DEVELOPMENT AS FUNCTION OF WELLBORE ORIENTATION



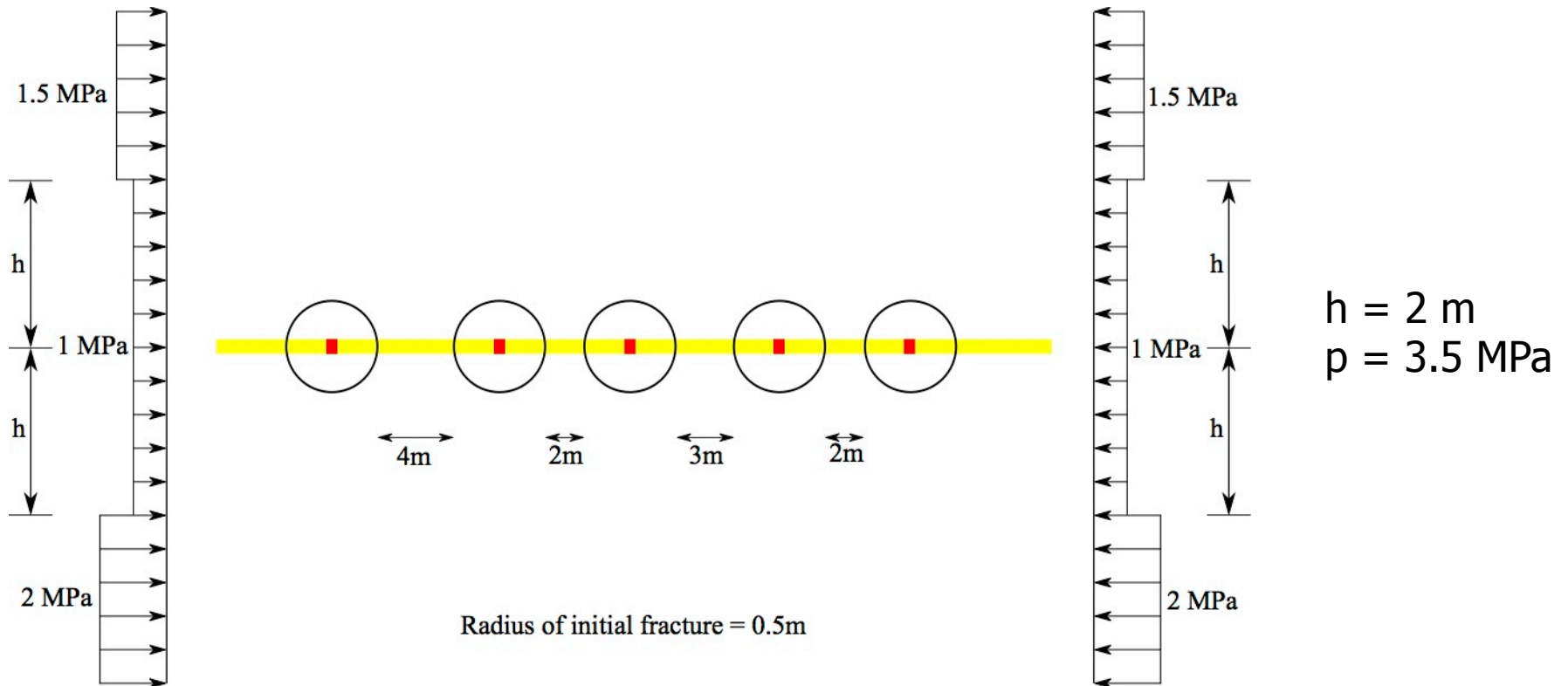
[Z. Rahim et al., 2012]





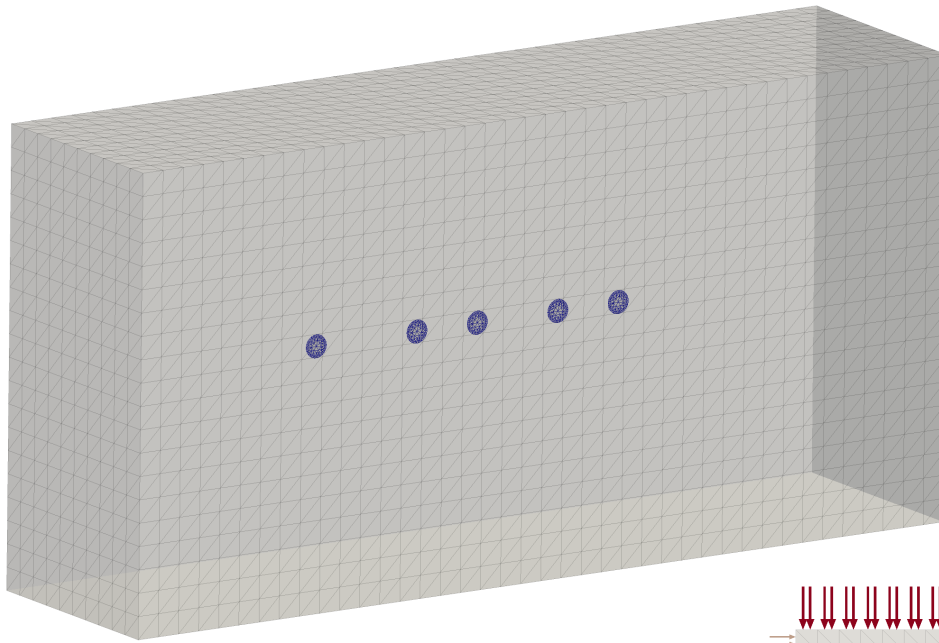
# Coalescence of Longitudinal Fractures

- Propagation and coalescence from a horizontal well

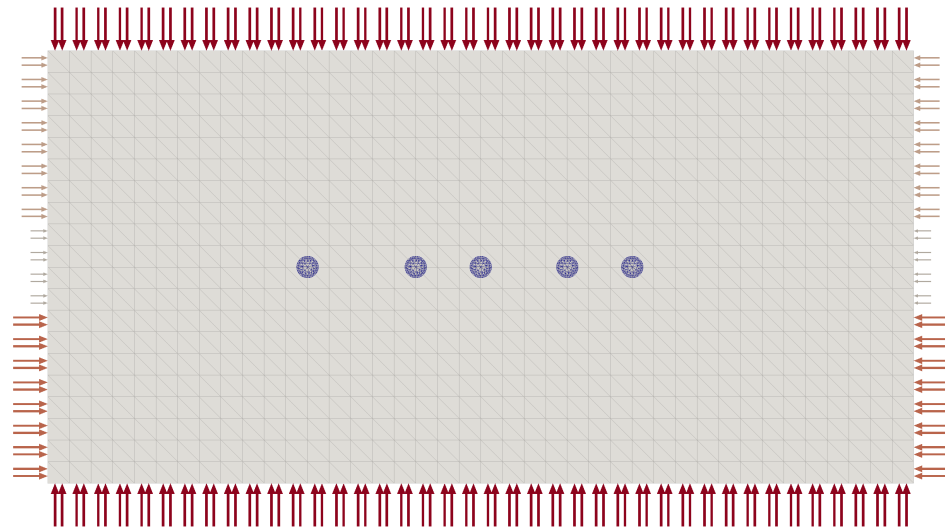




# Coalescence of 3-D Fractures: GFEM Model

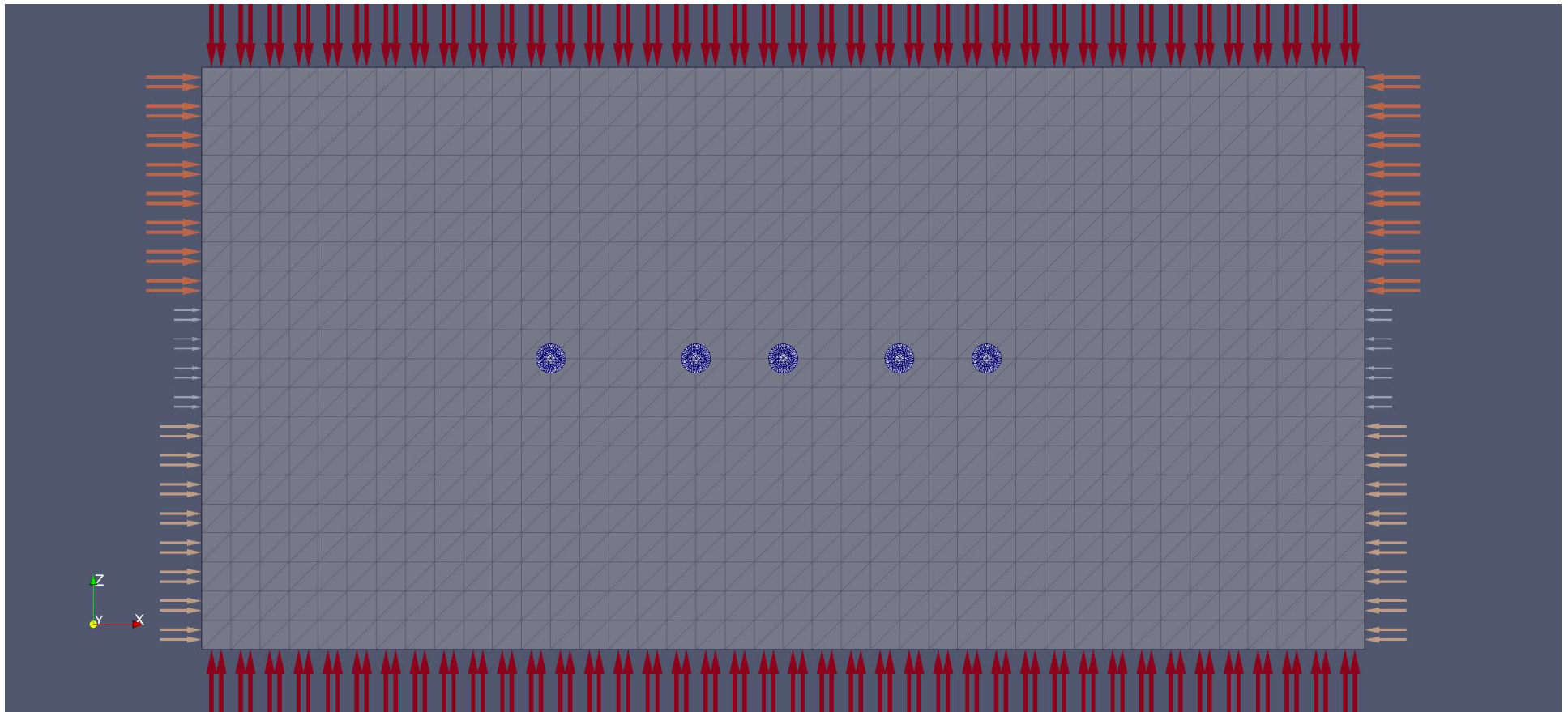


- Input mesh and fracture surfaces for GFEM simulation





# Coalescence of 3-D Fractures

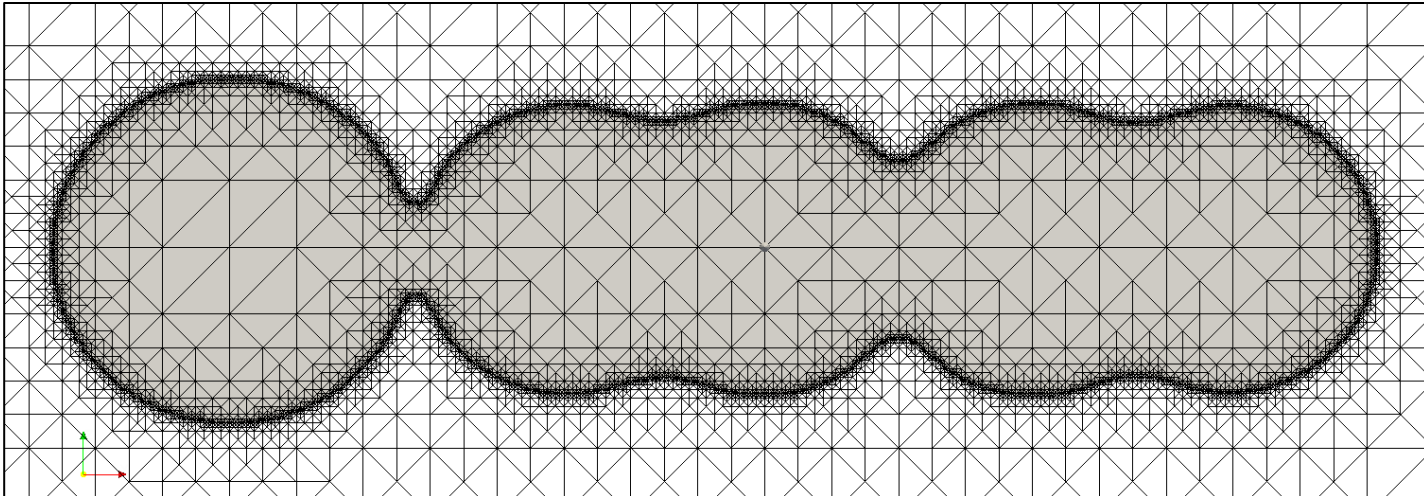
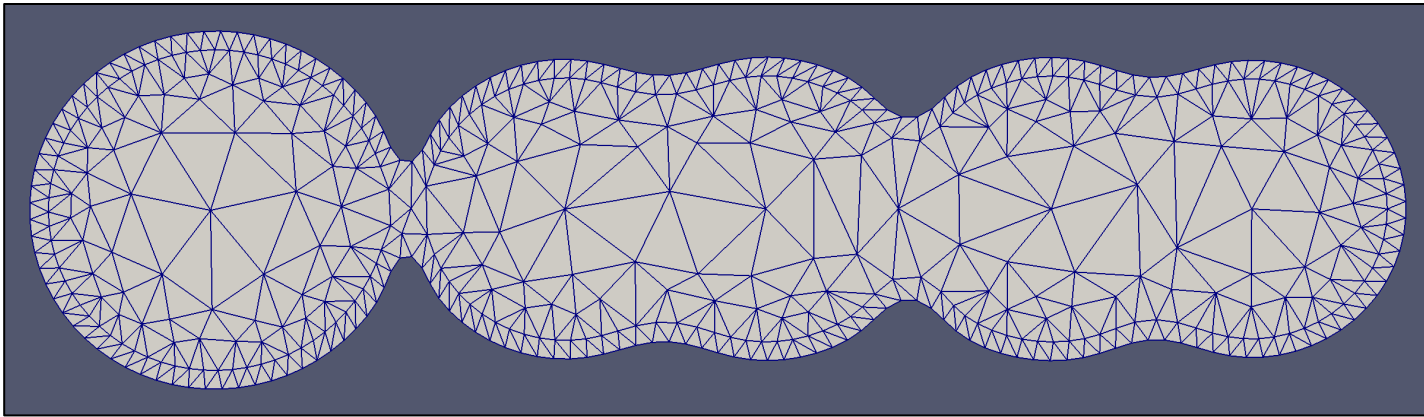






# Coalescence of 3-D Fractures

- A large 3-D model is required even with adaptive refinement along fracture fronts
- Numerical conditioning of the G/XFEM becomes critical





# Outline

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- Motivation
- Basic ideas of G/XFEM
- Stable GFEM for 3D fractures
- Assessment of convergence and numerical conditioning
- Conclusions and future work





# Early Works on Generalized FEMs

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- Babuska, Caloz and Osborn, 1994 (Special FEM).
- Duarte and Oden, 1995 (Hp Clouds).
- Babuska and Melenk, 1995 (PUFEM).
- Oden, Duarte and Zienkiewicz, 1996 (Hp Clouds/GFEM).
- Duarte, Babuska and Oden, 1998 (GFEM).
- Belytschko et al., 1999 (Extended FEM).
- Strouboulis, Babuska and Copps, 2000 (GFEM).
  
- Basic idea:
  - Use a partition of unity to build Finite Element shape functions
  
- Review paper

Belytschko T., Gracie R. and Ventura G. A review of extended/generalized finite element methods for material modeling, *Mod. Simul. Matl. Sci. Eng.*, 2009

“The XFEM and GFEM are basically identical methods: the name generalized finite element method was adopted by the Texas school in 1995–1996 and the name extended finite element method was coined by the Northwestern school in 1999.”





# Generalized Finite Element Method

- GFEM is a Galerkin method with special test/trial space given by

$$S_{GFEM} = S_{FEM} + S_{ENR}$$

Low order FEM space

Enrichment space with functions related to the given problem

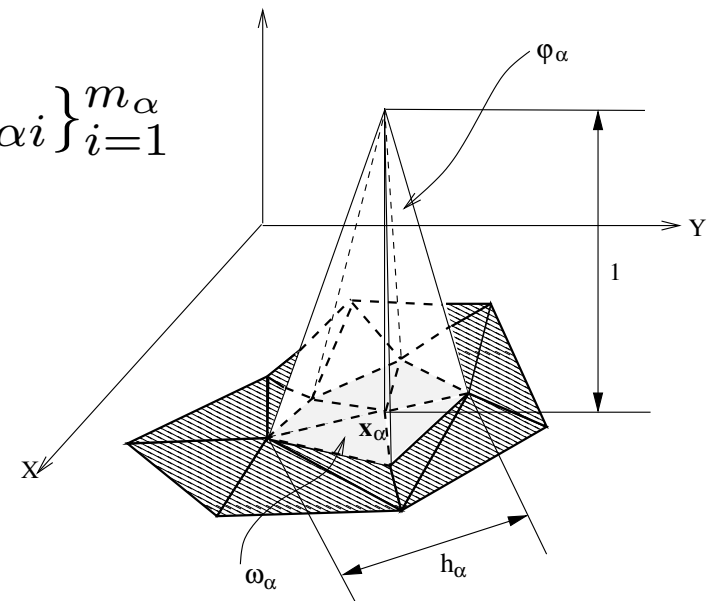
$$S_{FEM} = \sum_{\alpha \in I_h} c_\alpha \varphi_\alpha, \quad c_\alpha \in \mathbb{R}$$

$$S_{ENR} = \sum_{\alpha \in I_h^e \subset I_h} \varphi_\alpha \chi_\alpha; \quad \chi_\alpha = \text{span}\{L_{\alpha i}\}_{i=1}^{m_\alpha}$$

$$L_{\alpha i} \in \chi_\alpha(\omega_\alpha)$$

Enrichment function

Patch space





# Generalized Finite Element Method

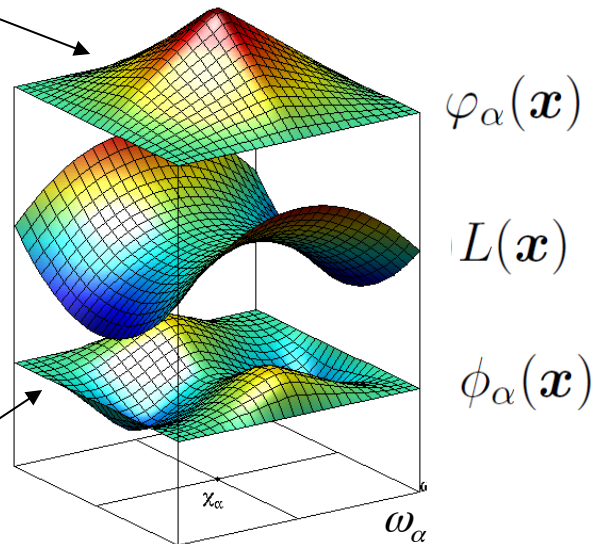
$$S_{ENR} = \sum_{\alpha \in I_h^e \subset I_h} \varphi_\alpha \chi_\alpha; \quad \chi_\alpha = \text{span}\{L_{\alpha i}\}_{i=1}^{m_\alpha}$$

$$\phi_{\alpha i}(x) = \varphi_\alpha(x) L_{\alpha i}(x) \quad \sum_{\alpha} \varphi_\alpha(x) = 1$$

Linear FE shape function

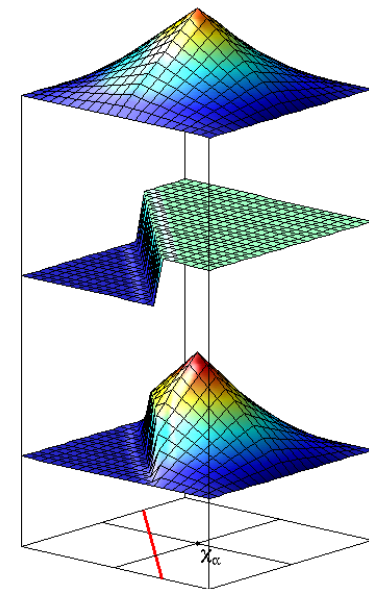
Enrichment function

GFEM shape function



[Oden, Duarte & Zienkiewicz, 1996]

- Allows construction of shape functions incorporating a-priori knowledge about solution

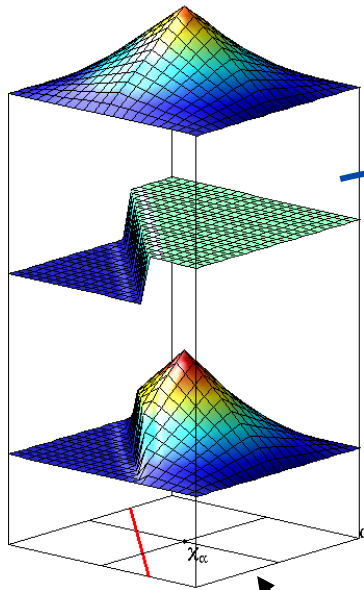


Discontinuous enrichment  
[Moes et al., 1999]



# GFEM Approximation for 3-D Fractures

$$\mathbb{S}_{GFEM}(\Omega) = \left\{ \mathbf{u}^{hp} = \sum_{\alpha \in I_h} \underbrace{\varphi_{\alpha}(\mathbf{x})}_{\text{PoU}} \left[ \underbrace{\hat{\mathbf{u}}_{\alpha}(\mathbf{x})}_{\text{polynomial}} + \underbrace{\mathcal{H}\tilde{\mathbf{u}}_{\alpha}(\mathbf{x})}_{\text{discontinuous}} + \underbrace{\check{\mathbf{u}}_{\alpha}(\mathbf{x})}_{\text{singular}} \right] \right\}$$

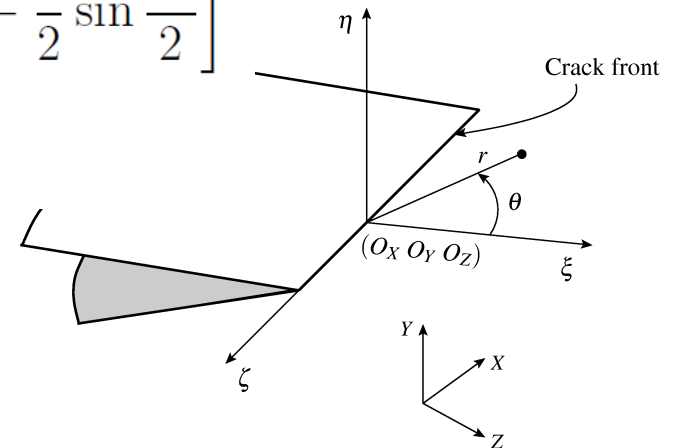


patch  $\omega_{\alpha}$

$$\check{L}_{\alpha 1}^{\xi}(r, \theta) = \sqrt{r} \left[ \left( \kappa - \frac{1}{2} \right) \cos \frac{\theta}{2} - \frac{1}{2} \cos \frac{3\theta}{2} \right] \quad [\text{Duarte \& Oden 1996}]$$

$$\check{L}_{\alpha 1}^{\eta}(r, \theta) = \sqrt{r} \left[ \left( \kappa + \frac{1}{2} \right) \sin \frac{\theta}{2} - \frac{1}{2} \sin \frac{3\theta}{2} \right]$$

$$\check{L}_{\alpha 1}^{\zeta}(r, \theta) = \sqrt{r} \sin \frac{\theta}{2}$$

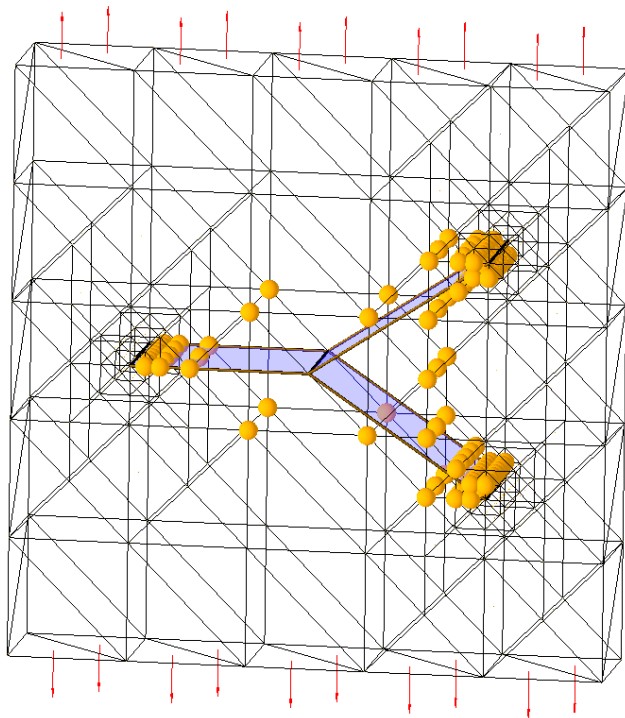






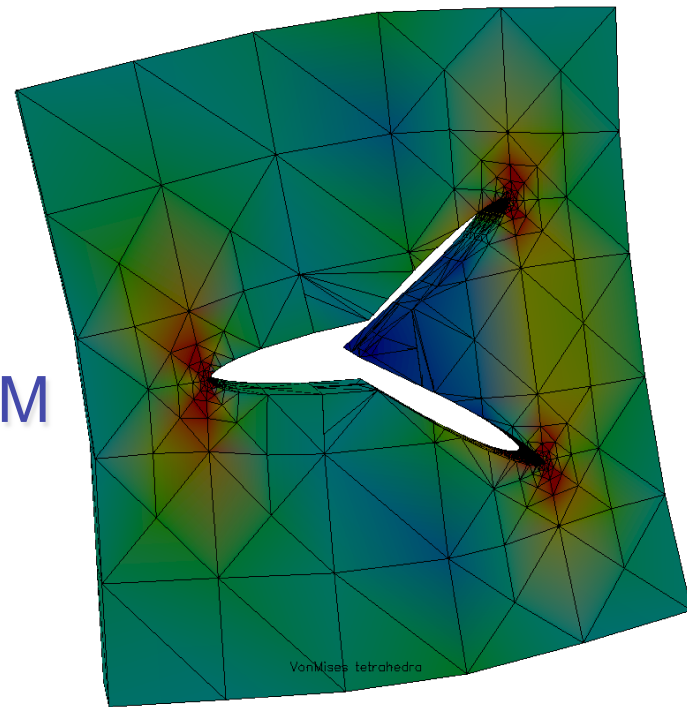
# Modeling Fractures with the GFEM

- Discontinuities modeled via enrichment functions, *not* the FEM mesh
- Mesh refinement *still required* for acceptable accuracy



● = Nodes with discontinuous enrichments

*hp*-GFEM

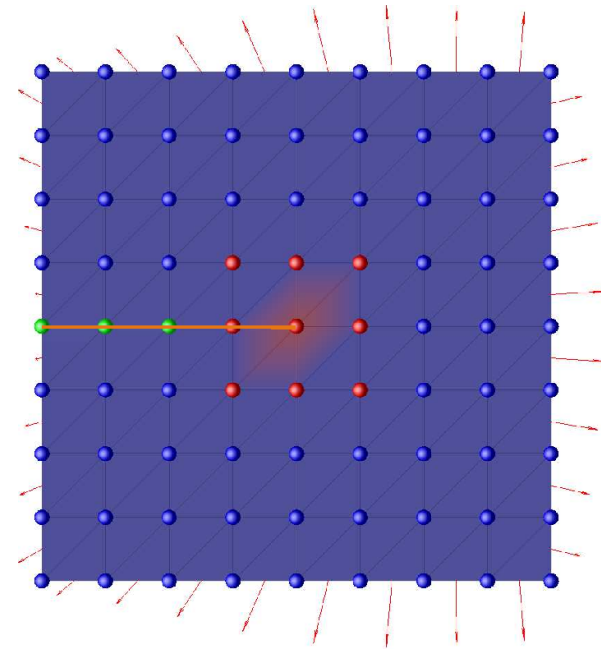
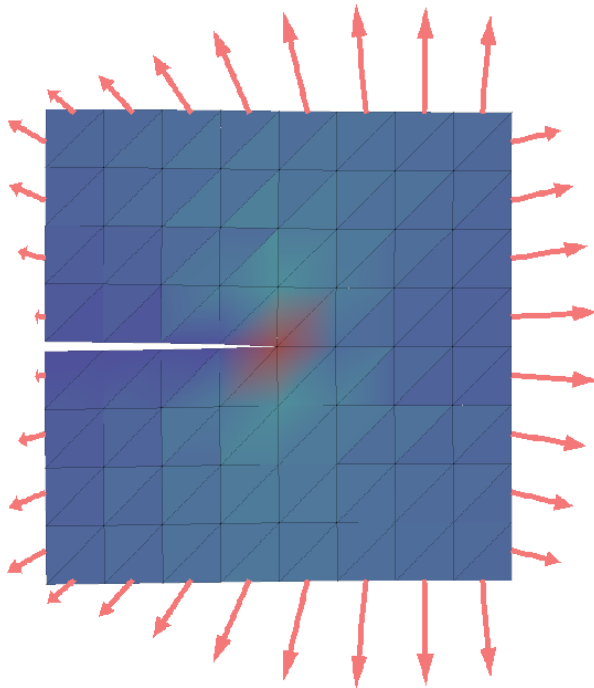


Von Mises stress



# Conditioning of G/XFEM Approximations

- 2-D edge-crack panel loaded with Mode I tractions



Red nodes: Singular enrichments

Green nodes: Heaviside function

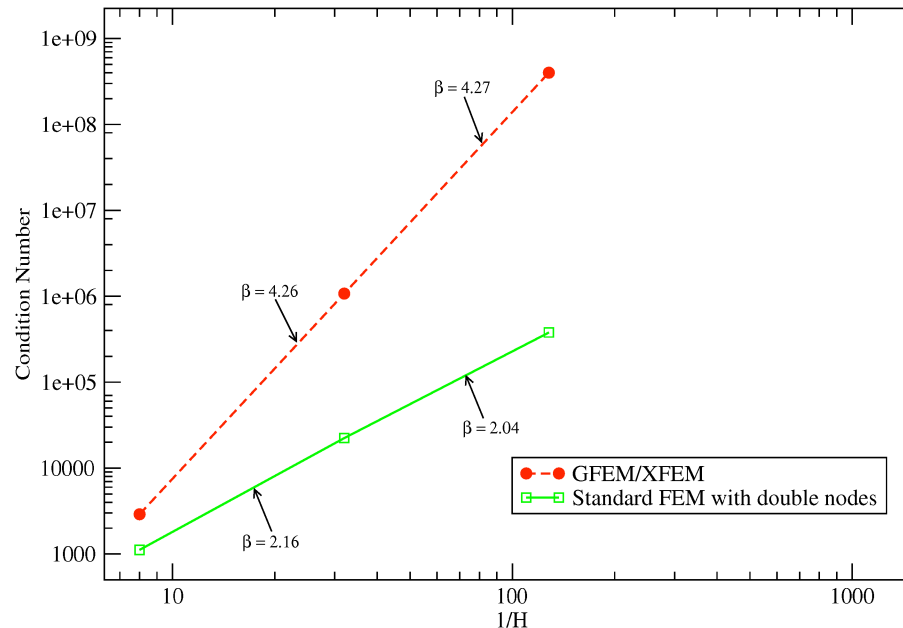
$$\mathbf{u}_I(r, \theta) = \sqrt{r} \begin{Bmatrix} \left(\kappa - \frac{1}{2}\right) \cos \frac{\theta}{2} - \frac{1}{2} \cos \frac{3\theta}{2} \\ \left(\kappa + \frac{1}{2}\right) \sin \frac{\theta}{2} - \frac{1}{2} \sin \frac{3\theta}{2} \end{Bmatrix}$$

where  $\kappa = 3-4\nu$   
 $\nu$  is the Poisson's ratio

$$\mathcal{H}(x, y) = \begin{cases} 1 & \text{if } y \geq 0 \\ 0 & \text{if } y < 0 \end{cases}$$



# Conditioning of G/XFEM Approximations



- The conditioning of the G/XFEM stiffness matrix,  $\mathbf{K}_{GFEM}$ , can be much worse than that of the standard FEM,  $\mathbf{K}_{FEM}$

$$\mathcal{R}(\mathbf{K}_{GFEM}) = \mathcal{O}(h^{-4})$$

while

$$\mathcal{R}(\mathbf{K}_{FEM}) = \mathcal{O}(h^{-2})$$

where  $\mathcal{R}(\cdot)$  is the *scaled condition number*.





# Stable GFEM (SGFEM)\*

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- Goal: Control the conditioning of GFEM/XFEM while preserving approximation properties
- Involves simple modification of enrichment functions
- Performs near-orthogonalization of enrichments w.r.t. Finite Element Partition of Unity
- Straightforward to implement in an existing GFEM/XFEM code
- Bonus: Increased accuracy at no additional cost!

\* I. Babuska and U. Banerjee. Stable Generalized Finite Element Method (SGFEM). *CMAME*, 2012.

\* V. Gupta, C.A. Duarte, I. Babuska and U. Banerjee. A Stable and Optimally Convergent Generalized FEM (SGFEM) for Linear Elastic Fracture Mechanics. *CMAME*, 2013, 2014 (submitted).



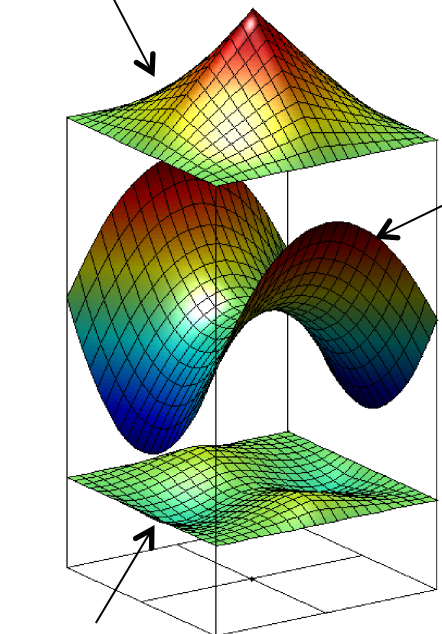
# SGFEM: Stable Generalized FEM

Modification of enrichment functions

$$\tilde{L}_{\alpha i}(\mathbf{x}) = L_{\alpha i}(\mathbf{x}) - \mathbf{I}_{\omega_{\alpha}}(L_{\alpha i})(\mathbf{x})$$

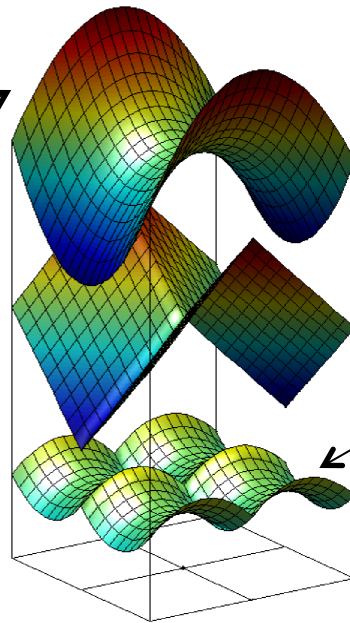
$$\tilde{\phi}_{\alpha i}(\mathbf{x}) = \varphi_{\alpha}(\mathbf{x}) \tilde{L}_{\alpha i}(\mathbf{x})$$

Linear FE Shape Function

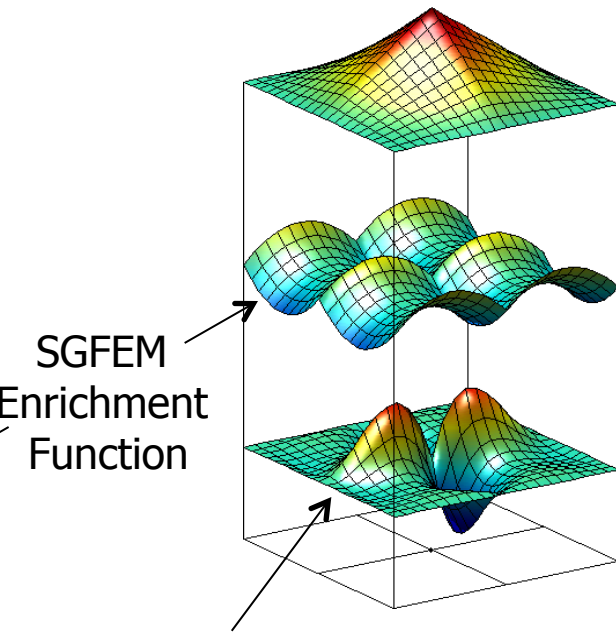


GFEM Shape Function

GFEM  
Enrichment  
Function



SGFEM  
Enrichment  
Function



SGFEM Shape Function



# Stable Generalized Finite Element Method

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$$\mathbb{S}_{SGFEM} = \mathbb{S}_{FEM} + \tilde{\mathbb{S}}_{ENR}$$

$$\mathbb{S}_{FEM} = \sum_{\alpha \in I_h} c_\alpha \varphi_\alpha, \quad c_\alpha \in \mathbb{R}$$

$$\tilde{\mathbb{S}}_{ENR} = \sum_{\alpha \in I_h^e \subset I_h} \varphi_\alpha \tilde{\chi}_\alpha; \quad \tilde{\chi}_\alpha = \text{span}\{\tilde{L}_{\alpha i}\}_{i=1}^{m_\alpha}$$

$$\tilde{L}_{\alpha i} \in \tilde{\chi}_\alpha(\omega_\alpha) \quad \text{Modified enrichment functions}$$

$$\tilde{L}_{\alpha i}(\mathbf{x}) = L_{\alpha i}(\mathbf{x}) - \mathbf{I}_{\omega_\alpha}(L_{\alpha i})(\mathbf{x})$$



# Stable Generalized Finite Element Method

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The conditioning of the SGFEM matrix is of same order as that of standard FEM

$$\mathfrak{K}(\mathbf{K}_{\text{SGFEM}}) = \mathfrak{K}(\mathbf{K}_{\text{FEM}}) = \mathcal{O}(h^{-2})$$

$$\mathbb{S}_{\text{SGFEM}} = \mathbb{S}_{\text{FEM}} + \tilde{\mathbb{S}}_{\text{ENR}}$$

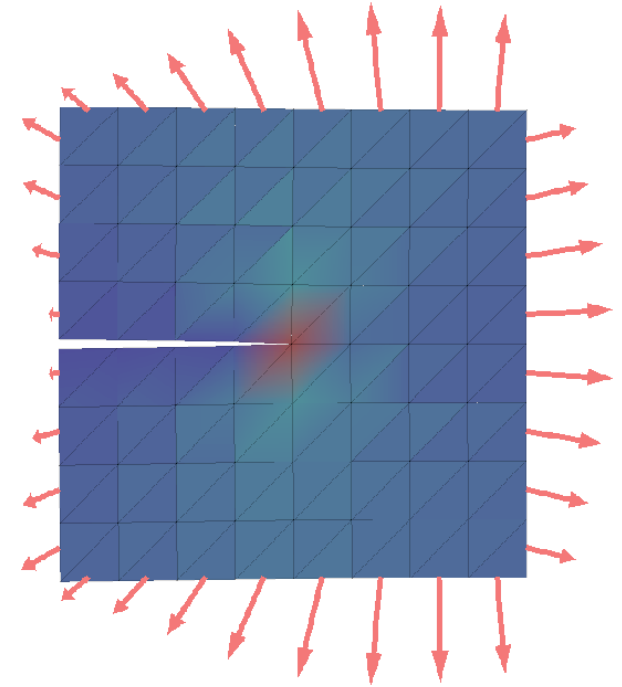
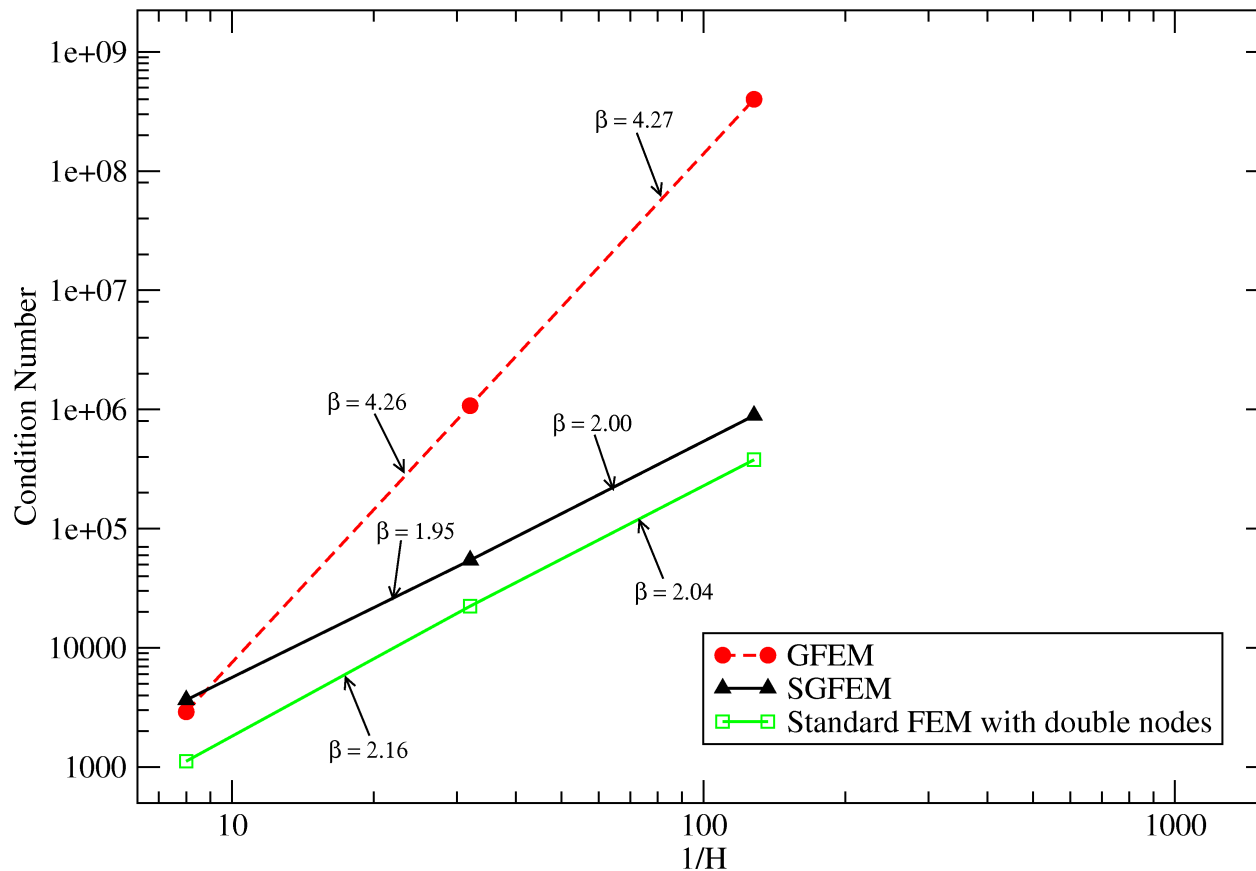
$$\mathbf{K}_{\text{SGFEM}} = \begin{bmatrix} \mathbf{K}_{\text{FEM}} & \mathbf{K}_{12} \\ \mathbf{K}_{21} & \mathbf{K}_{\text{ENR}} \end{bmatrix}$$

**Property 1:** the spaces  $\tilde{\mathbb{S}}_{\text{ENR}}$  and  $\mathbb{S}_{\text{FEM}}$  are *almost orthogonal* with respect to the energy inner product  $B(\cdot, \cdot)$ ;

**Property 2:** the eigenvalues of the diagonally scaled matrix of  $\mathbf{K}_{\text{ENR}}$  are bounded away from 0.



# SGFEM: Stable Generalized FEM



Conditioning of GFEM/XFEM stiffness matrix  $\mathcal{O}(h^{-4})$

Conditioning of SGFEM and FEM stiffness matrix  $\mathcal{O}(h^{-2})$

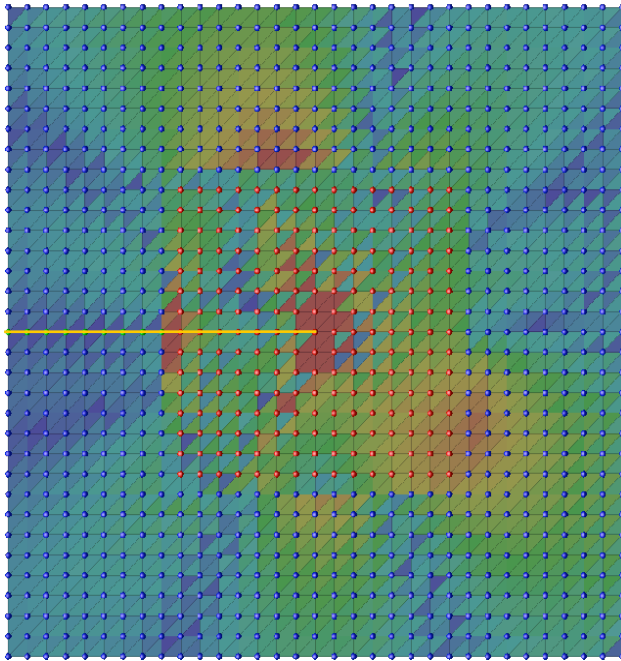
[Gupta, Duarte, Babuska & Banerjee CMAME, 2013]





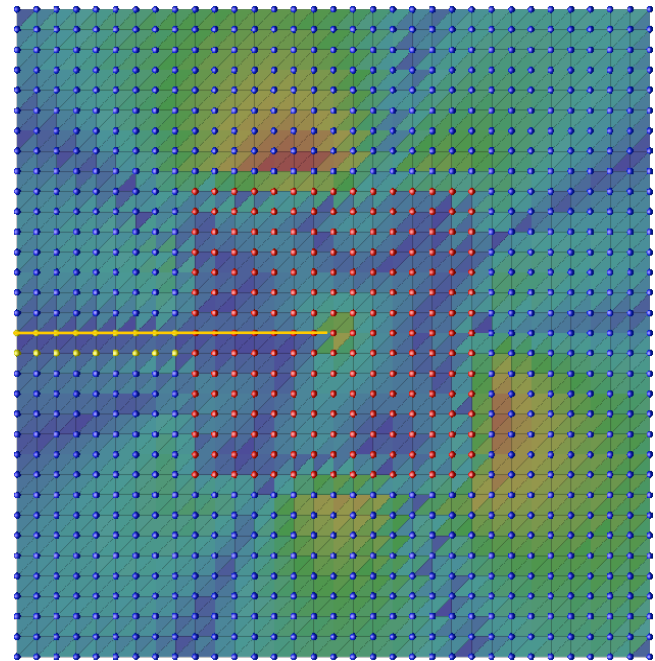
# GFEM/XFEM vs SGFEM: Accuracy

Element-wise error in energy norm



GFEM/XFEM

(Green nodes: Heaviside Enrichment)



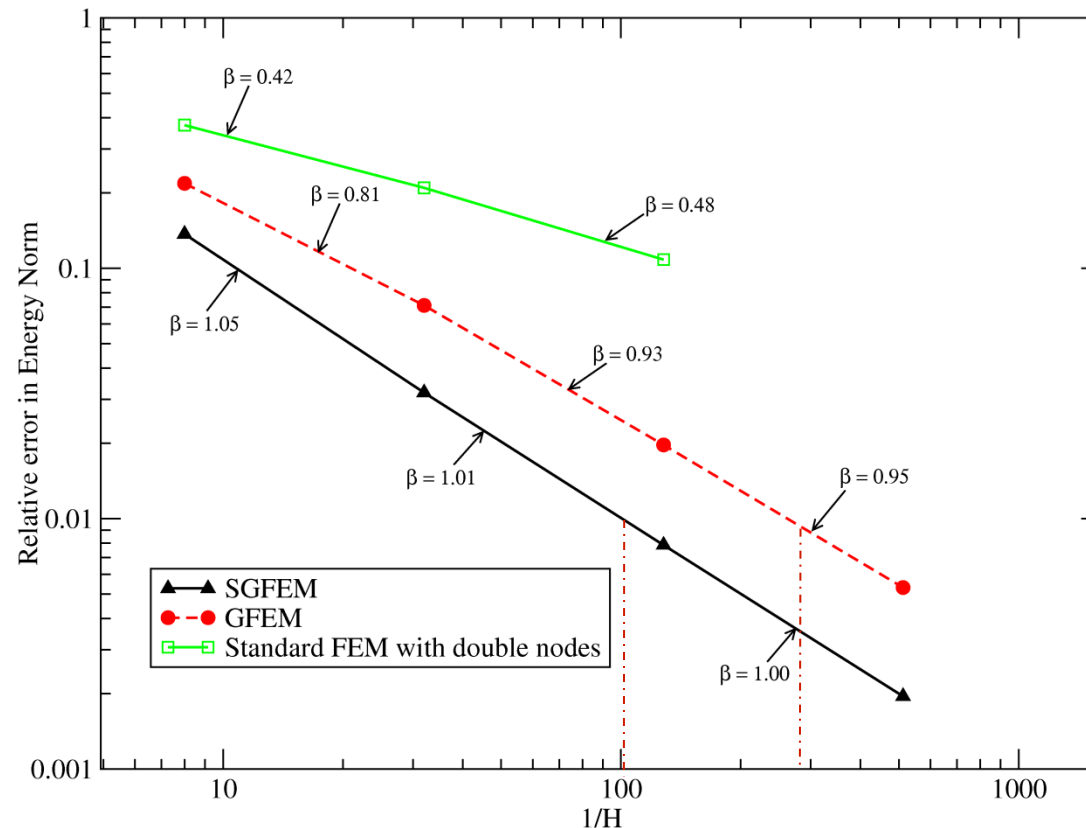
SGFEM

(Yellow nodes: Linear Heaviside Enrichment)

- SGFEM shows lower error in the entire enrichment zone
- GFEM and SGFEM: Optimal  $O(h)$  convergence



# GFEM/XFEM vs SGFEM: Global Convergence



Mesh size for  $\sim 1\%$  Error :

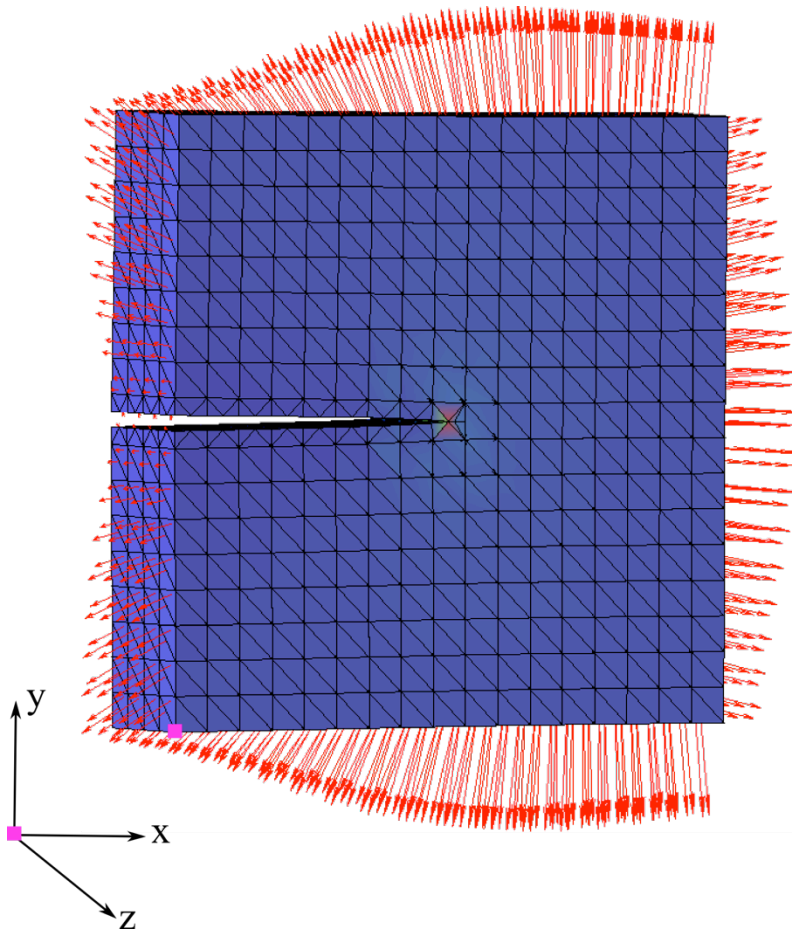
- GFEM\XFEM:  $H = 0.003$
- SGFEM:  $H = 0.01$

- GFEM and SGFEM: Optimal  $O(h)$  convergence
- FEM:  $O(h^{1/2})$  convergence



# SGFEM for 3-D Fracture

- Quasi 3-D edge-crack panel loaded with Mode I tractions

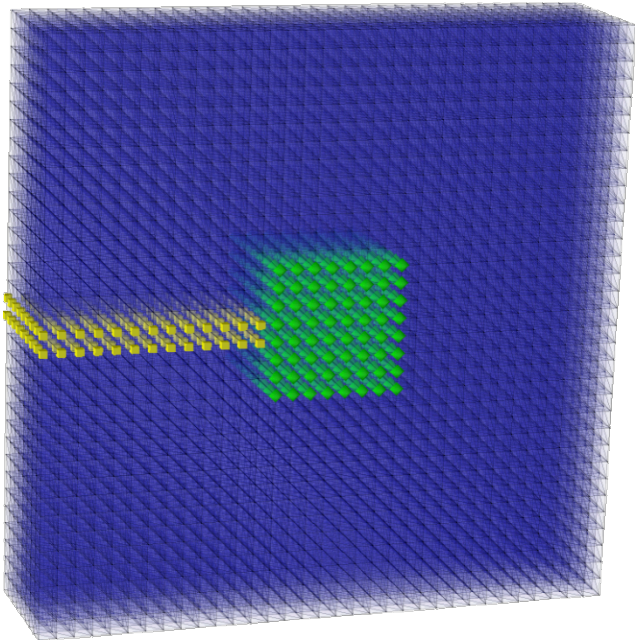


$$\mathbf{u}_I(r, \theta) = \sqrt{r} \begin{Bmatrix} \left(\kappa - \frac{1}{2}\right) \cos \frac{\theta}{2} - \frac{1}{2} \cos \frac{3\theta}{2} \\ \left(\kappa + \frac{1}{2}\right) \sin \frac{\theta}{2} - \frac{1}{2} \sin \frac{3\theta}{2} \\ 0 \end{Bmatrix}$$

➤ Solution is constant in z-direction



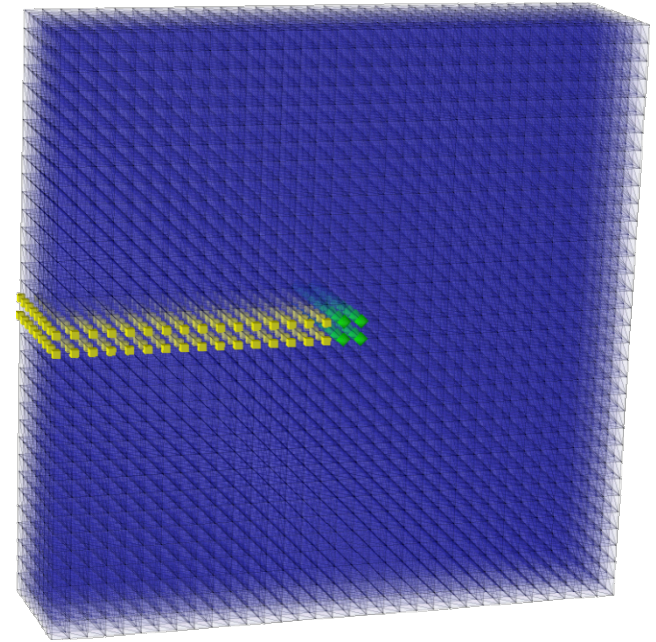
# Geometrical and Topological Enrichments



Geometrical Enrichment

- Enrich all nodes within a fixed sub-domain around crack front
- May lead to large number of dofs if global mesh is fine
- Leads to ill-conditioned system

- Green nodes: Singular fn
- Yellow nodes: Heaviside fn



Topological Enrichment

- Only elements cut/touched by crack front are enriched
- Enrichment domain depends on mesh density
- Leads to sub-optimal convergence



# Singular Enrichments are not Unique

OD Singular basis: Oden and Duarte, 2000

$$\begin{aligned}\mathbf{L}_{\text{front}-\bar{x}}^{\text{OD}} &= \left\{ \sqrt{r} \left[ \left( \kappa - \frac{1}{2} \right) \cos \frac{\theta}{2} - \frac{1}{2} \cos \frac{3\theta}{2} \right], \sqrt{r} \left[ \left( \kappa + \frac{3}{2} \right) \sin \frac{\theta}{2} + \frac{1}{2} \sin \frac{3\theta}{2} \right] \right\} \\ \mathbf{L}_{\text{front}-\bar{y}}^{\text{OD}} &= \left\{ \sqrt{r} \left[ \left( \kappa + \frac{1}{2} \right) \sin \frac{\theta}{2} - \frac{1}{2} \sin \frac{3\theta}{2} \right], \sqrt{r} \left[ \left( \kappa - \frac{3}{2} \right) \cos \frac{\theta}{2} + \frac{1}{2} \cos \frac{3\theta}{2} \right] \right\} \\ \mathbf{L}_{\text{front}-\bar{z}}^{\text{OD}} &= \left\{ \sqrt{r} \left[ \sin \frac{\theta}{2} \right], r^2 [\cos 2\theta] \right\}\end{aligned}$$

- 6 enrichments per node
- Referred to as *vector* enrichments

BB Singular basis: Belytschko and Black, 1999

$$\mathbf{L}_{\text{front}}^{\text{BB}} = \left\{ \sqrt{r} \sin \frac{\theta}{2}, \sqrt{r} \cos \frac{\theta}{2}, \sqrt{r} \sin \frac{\theta}{2} \sin \theta, \sqrt{r} \cos \frac{\theta}{2} \sin \theta \right\} \quad \text{in } x, y, z$$

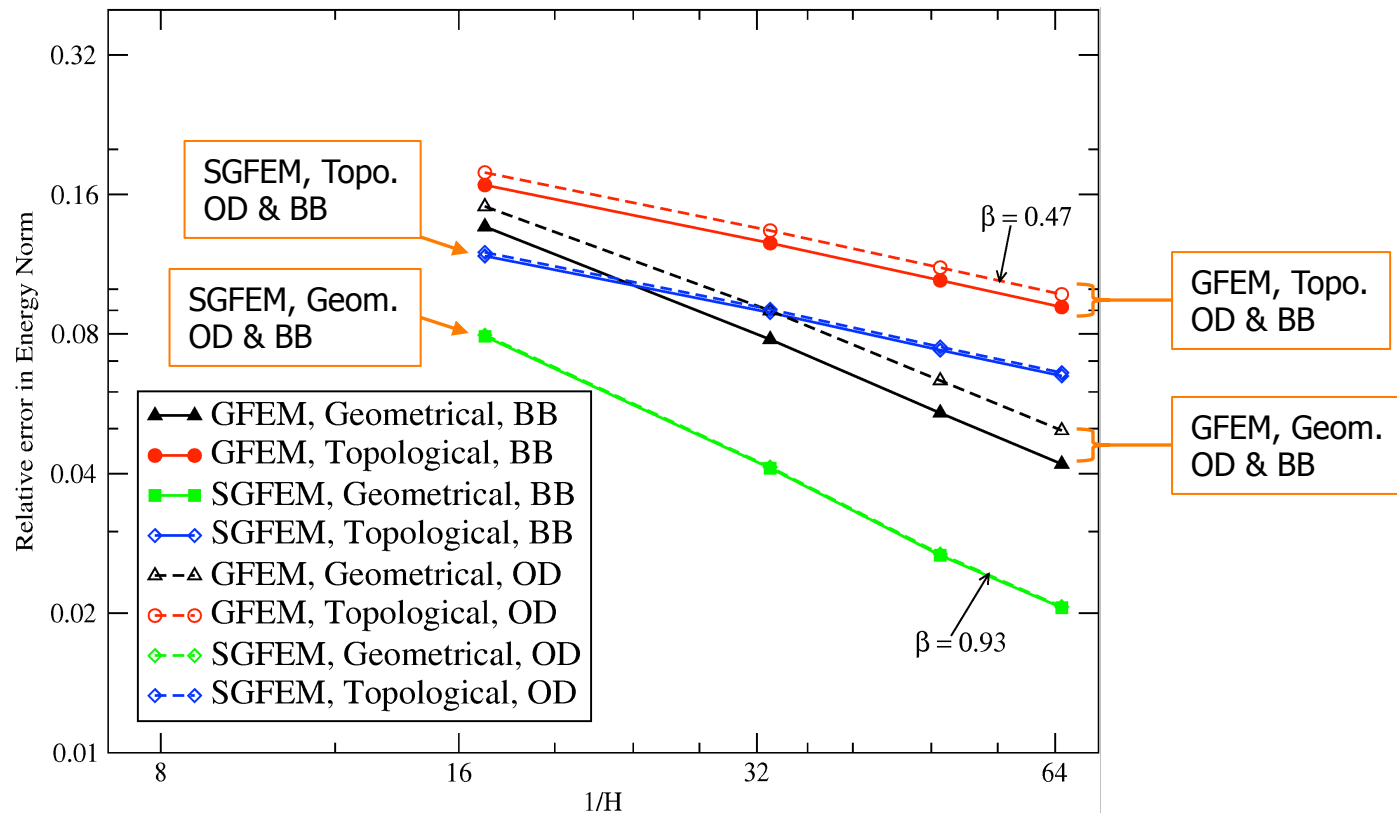
- 12 enrichments per node
- Referred to as *scalar* enrichments

➤ Both bases span a space containing the exact solution





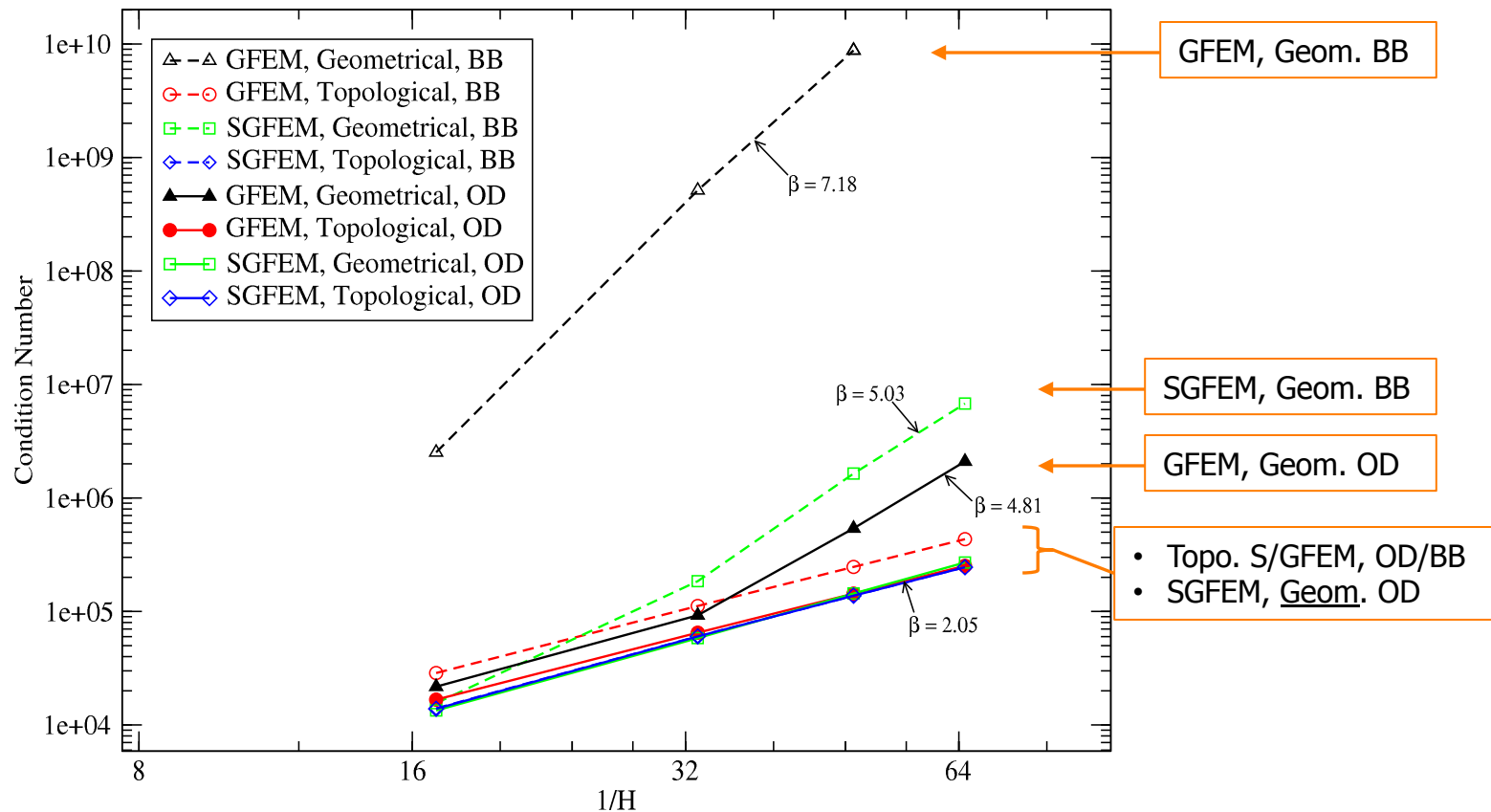
## GFEM/XFEM vs SGFEM: Convergence of OD or BB



- SGFEM yields better accuracy than GFEM even for topological enrichment
- Error of GFEM with OD > Error of GFEM with BB
- Error of SGFEM with OD  $\approx$  Error of SGFEM with BB



# GFEM/XFEM vs SGFEM: Conditioning (OD or BB)



- BB (scalar) enrichments yield much higher growth in conditioning
- SGFEM improves conditioning for both OD and BB enrichments
- SGFEM with OD basis yields similar conditioning as standard FEM:  $\sim O(h^{-2})$



# Fully 3-D Mode-I Expansion (OY)\*

$$\tilde{\mathbf{u}}_I = \begin{Bmatrix} u_r \\ u_\theta \\ u_{\bar{z}} \end{Bmatrix} = A_1 r^{\frac{1}{2}} \begin{Bmatrix} (Q_1 - 1) \sin \frac{\check{\theta}}{2} + \sin \frac{3\check{\theta}}{2} \\ -(Q_1 + 1) \cos \frac{\check{\theta}}{2} - \cos \frac{3\check{\theta}}{2} \\ 0 \end{Bmatrix} + \frac{dA_1}{d\check{z}} r^{\frac{3}{2}} \begin{Bmatrix} 0 \\ 0 \\ 2 \sin \frac{\check{\theta}}{2} + \frac{2}{3} (Q_1 + 1) \sin \frac{3\check{\theta}}{2} \end{Bmatrix} \\ + \frac{d^2 A_1}{d\check{z}^2} r^{\frac{5}{2}} \begin{Bmatrix} Q_2 \sin \frac{\check{\theta}}{2} + Q_3 \sin \frac{3\check{\theta}}{2} \\ \frac{1}{6} (Q_1 + 1) \cos \frac{\check{\theta}}{2} - Q_4 \cos \frac{3\check{\theta}}{2} \\ 0 \end{Bmatrix}$$

where

$$\check{z} = -\bar{z}, \quad \check{\theta} = \pi - \theta, \quad Q_1 = \frac{(2\lambda + 6\mu)}{(\lambda + \mu)}, \quad Q_2 = \frac{(3\lambda - \mu)}{6(\lambda + \mu)}, \\ Q_3 = \frac{(45\lambda^2 + 138\lambda\mu + 61\mu^2)}{90(\lambda + \mu)^2}, \quad Q_4 = \frac{(-15\lambda^2 + 2\lambda\mu + 49\mu^2)}{90(\lambda + \mu)^2}.$$

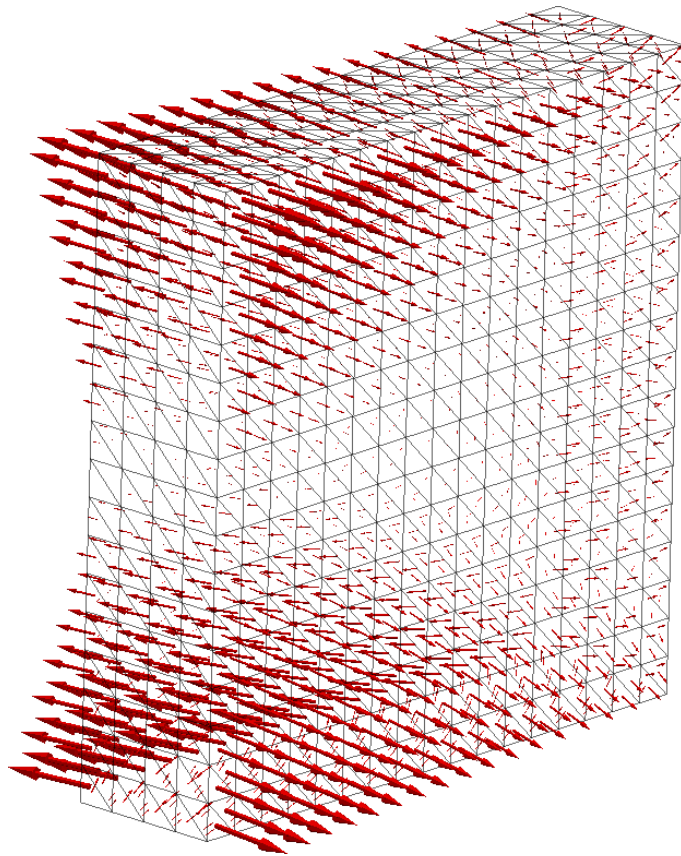
- SIF varies quadratically as

$$K_I = A_1 \sqrt{2\pi} \frac{2E}{1+\nu}; \quad A_1 = (1 - \zeta) * (1 + \zeta); \quad \zeta = \frac{\bar{z}}{t_z/2}$$

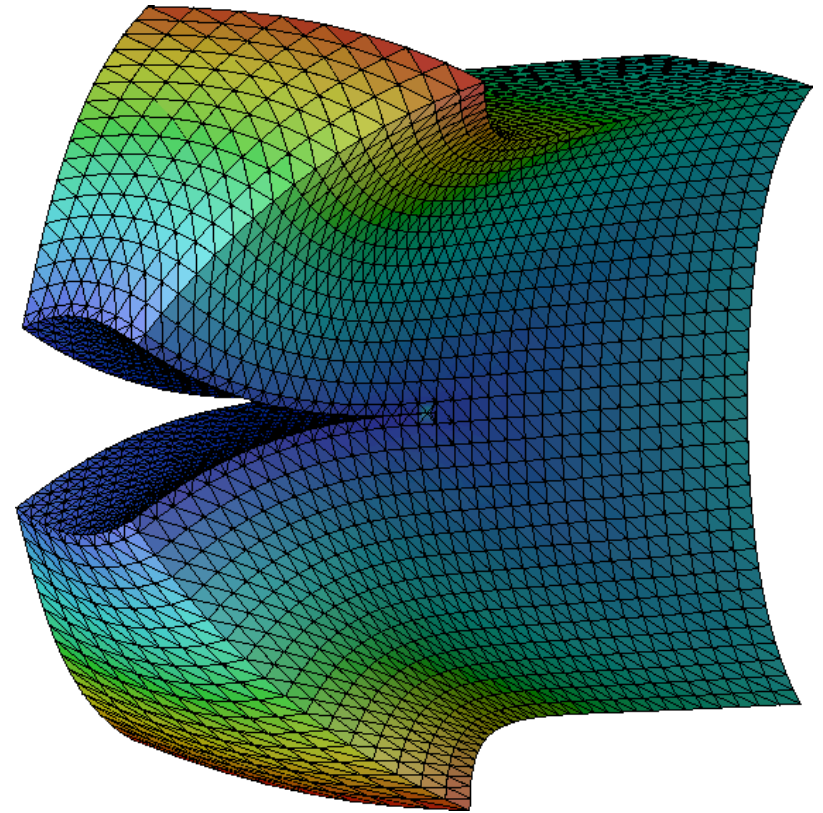
\*[Omer and Yosibash, 2005]



# Fully 3-D Edge-Crack Problem



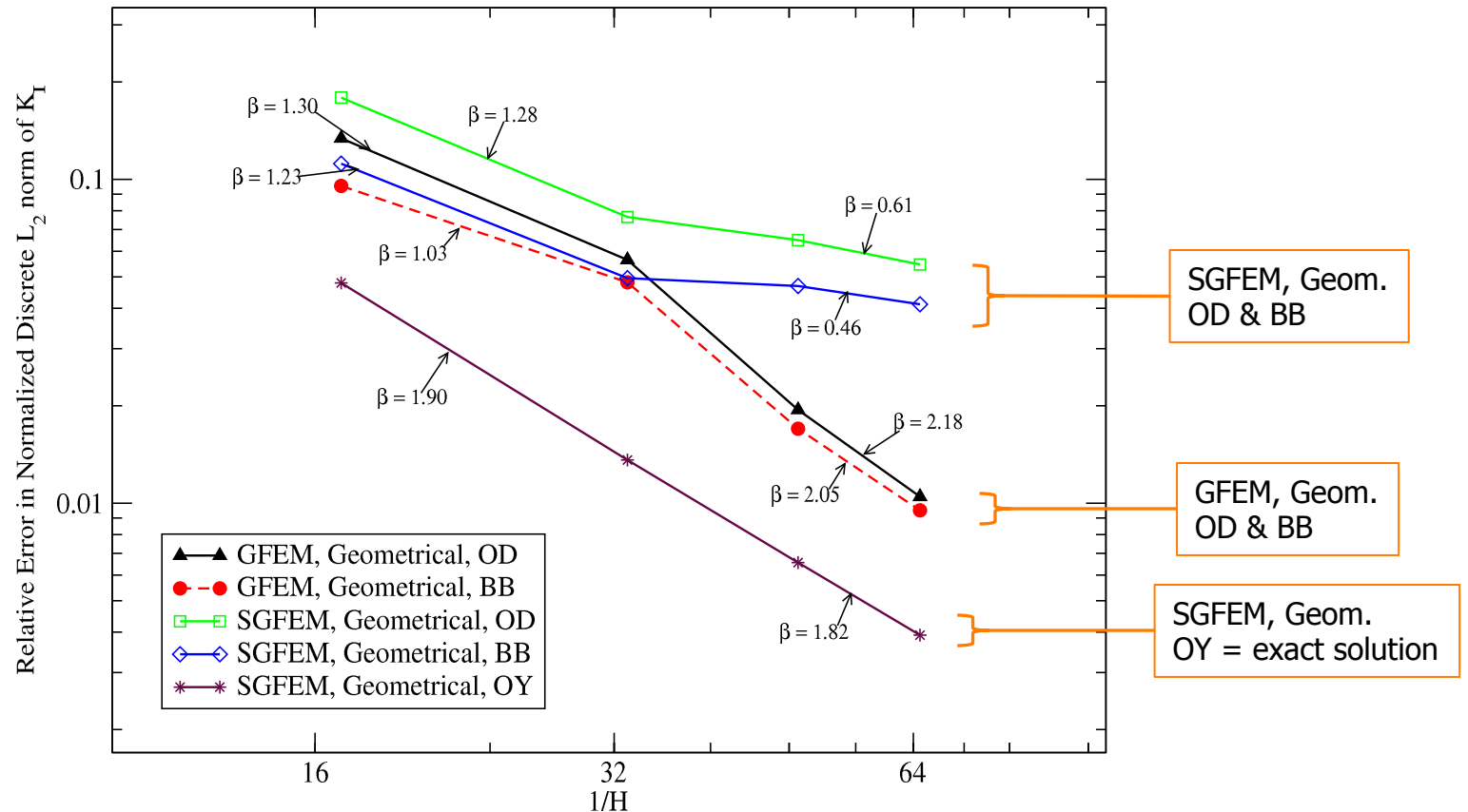
Fully 3-D Mode-I Traction



Deformed configuration  
(von Mises stress distribution)



# Convergence of Mode I SIF



$$e^r(K_I) := \frac{\|e_I\|_{L^2}}{\|K_I\|_{L^2}} = \frac{\sqrt{\sum_{j=1}^{N_{ext}} (\hat{K}_I^j - K_I^j)^2}}{\sqrt{\sum_{j=1}^{N_{ext}} (K_I^j)^2}}$$

- SGFEM with exact solution (OY) as enrichment: Reference
- Straightforward extension of 2-D singular bases leads to sub-optimal convergence of SGFEM in 3-D





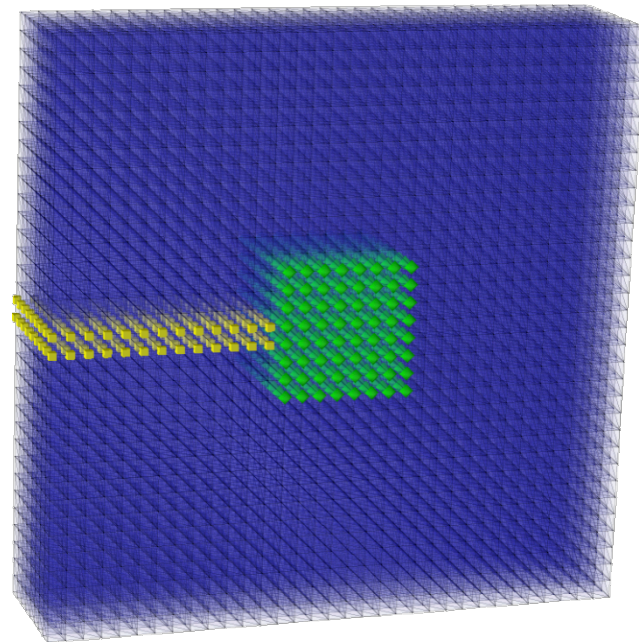
# Recovery of Optimal Convergence of SGFEM

- Exact solution is not constant in z-direction but enrichments (BB & OD) are.
- Exact solution is smooth in z-direction (SIFs are smooth functions of z).
- Add linear enrichments on nodes with singular basis to recover optimal convergence with SGFEM

$$\mathbf{L}_{\alpha}^{\text{lin}} = \left\{ \frac{(x-x_{\alpha})}{h_{\alpha}}, \frac{(y-y_{\alpha})}{h_{\alpha}}, \frac{(z-z_{\alpha})}{h_{\alpha}} \right\}$$

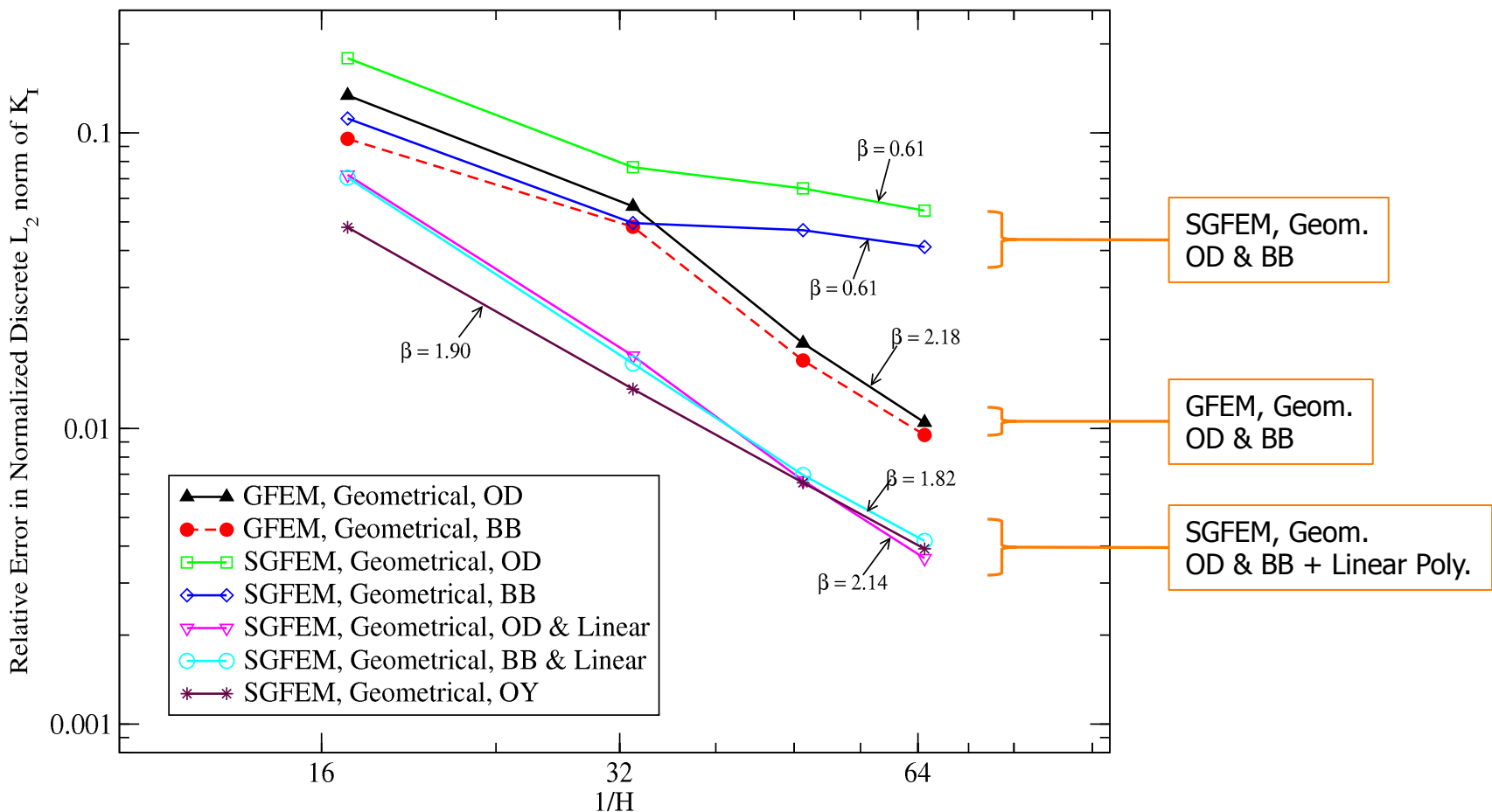
❑ **Green nodes:** Singular fns + linear polynomials

❑ **Yellow nodes:** Heaviside fn





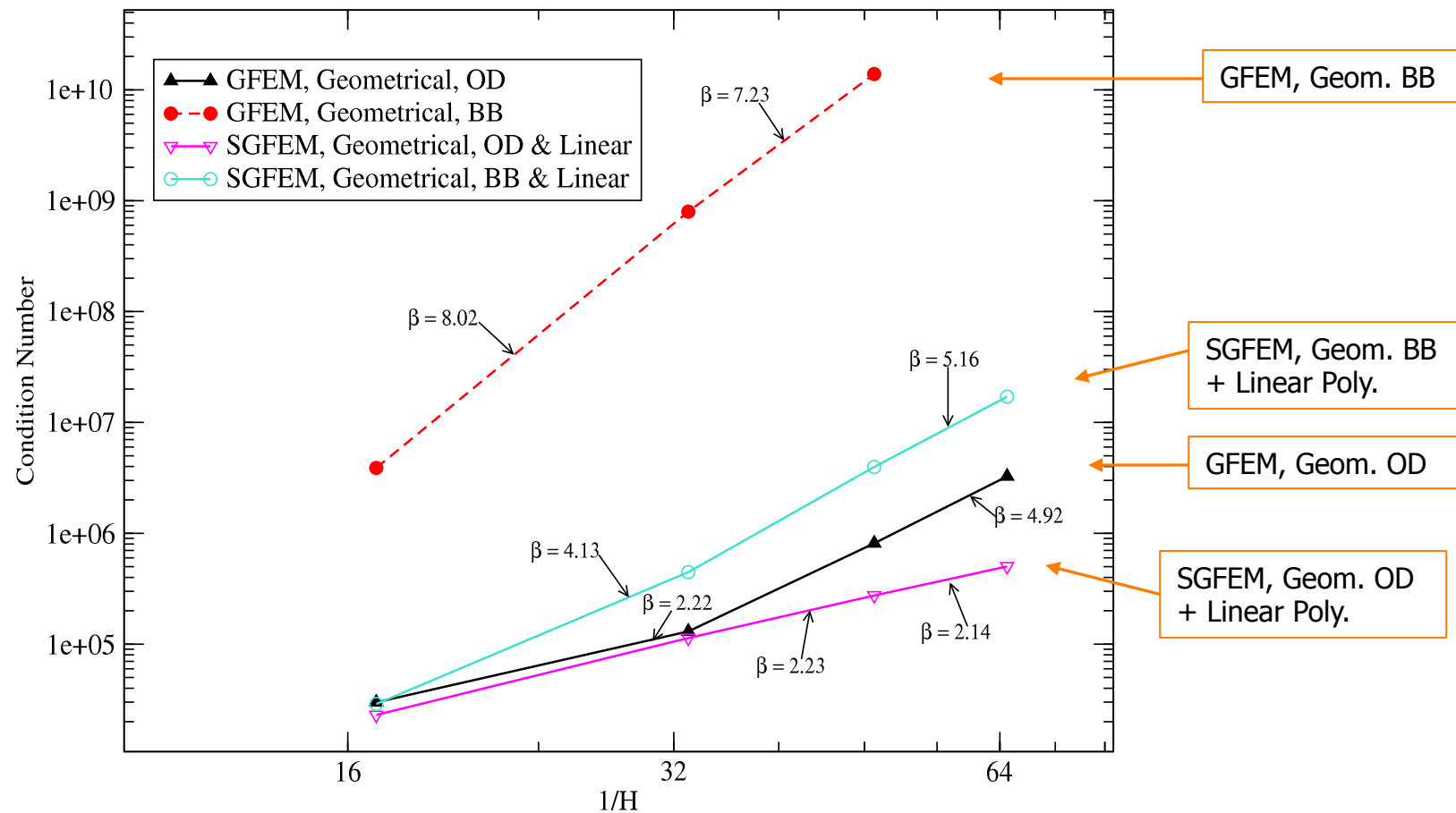
# Recovery of Optimal Convergence of SGFEM



- Adding linear enrichments on nodes with singular basis recover optimal convergence of SGFEM
- What about conditioning?



# SGFEM for 3-D Fracture: Conditioning



- Adding linear enrichments *does not impact growth of conditioning of SGFEM*



# Conclusions

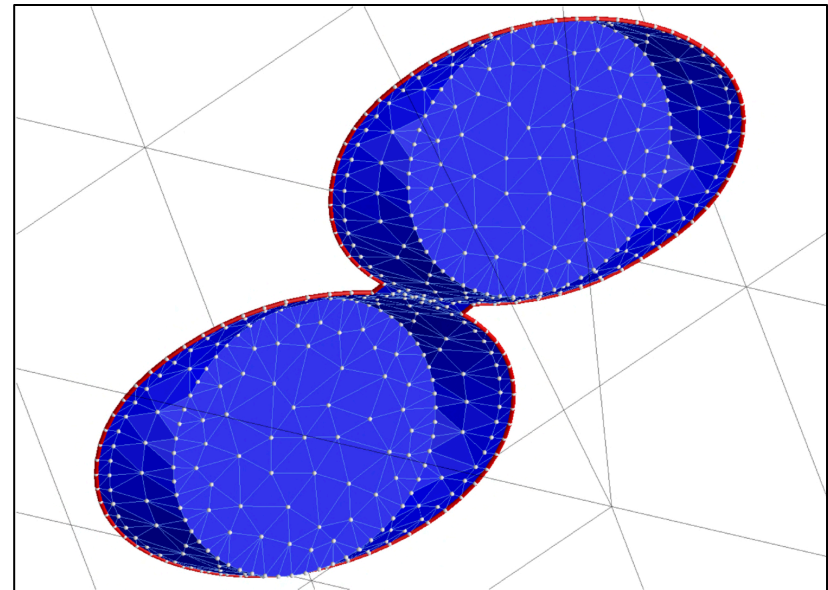
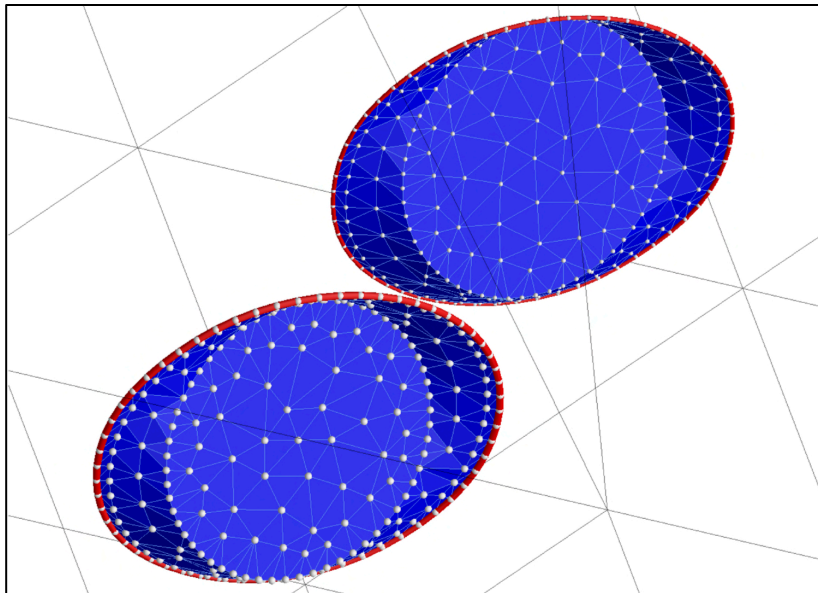
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- Proposed 3-D SGFEM provides significantly better conditioning and accuracy than GFEM/XFEM
- Condition number of the SGFEM is of the same order as in the FEM
- SGFEM is more accurate than GFEM/XFEM for both geometrical and topological enrichments
- Vector-valued singular enrichments yield better conditioning than scalar-valued
- OD is only basis that can deliver optimal convergence *and* good conditioning, simultaneously

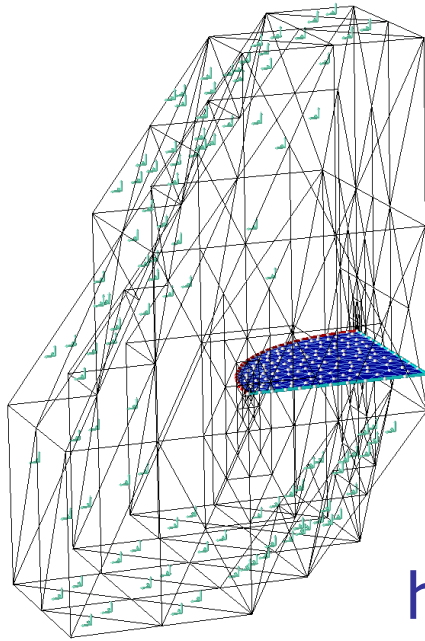


# Ongoing work on the SGFEM

- ❑ Enrichments for non-planar 3-D crack surfaces
- ❑ Enrichments for highly non-convex crack fronts
- ❑ SGFEM for global-local enrichments



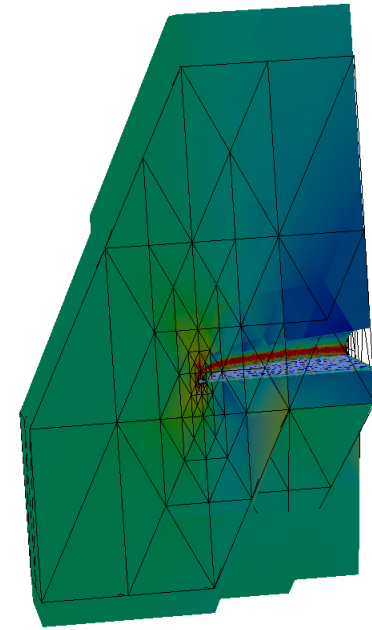




*Questions?*

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VonMises tetrahedra



**ExxonMobil**

