



Simulation of Non-Planar Three-Dimensional Hydraulic Fracture Propagation

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Hydraulic Fracturing of Gas Shale Reservoirs

Motivation

- Natural gas production in the US has increased significantly in the past few years thanks to advances in hydraulic fracturing of gas shale reservoirs
- Yet there are concerns about the environmental impact of toxic fluids used in this process

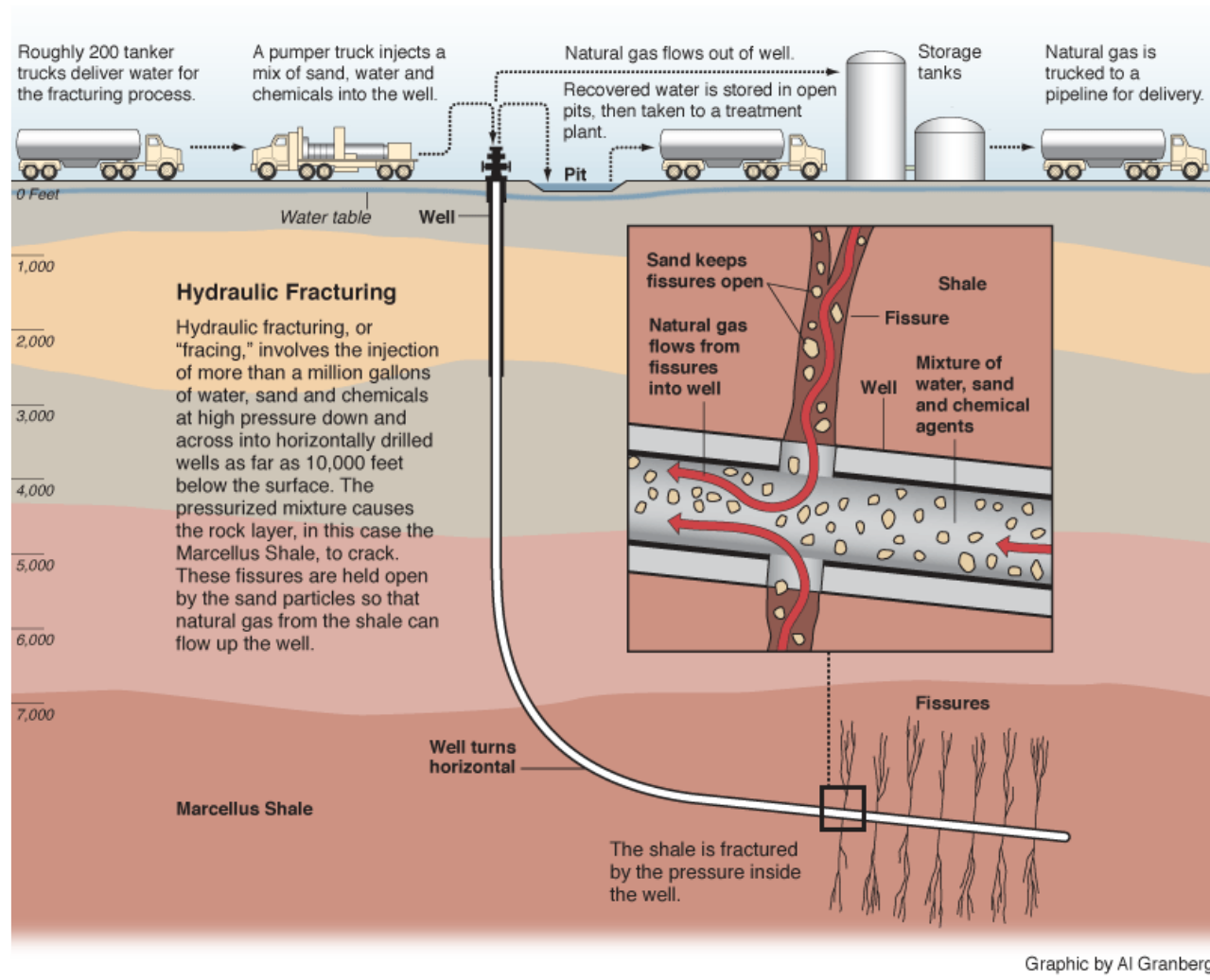


Objectives

- Computational simulations will lead to better designs of hydraulic fracture treatments, thus reducing the amount of toxic fluids used
- Realistic modeling of hydraulic fracturing treatments can evaluate the potential impact of interactions between hydraulic fractures and naturally existing fractures in shale reservoirs



What is Hydraulic Fracturing Anyway?



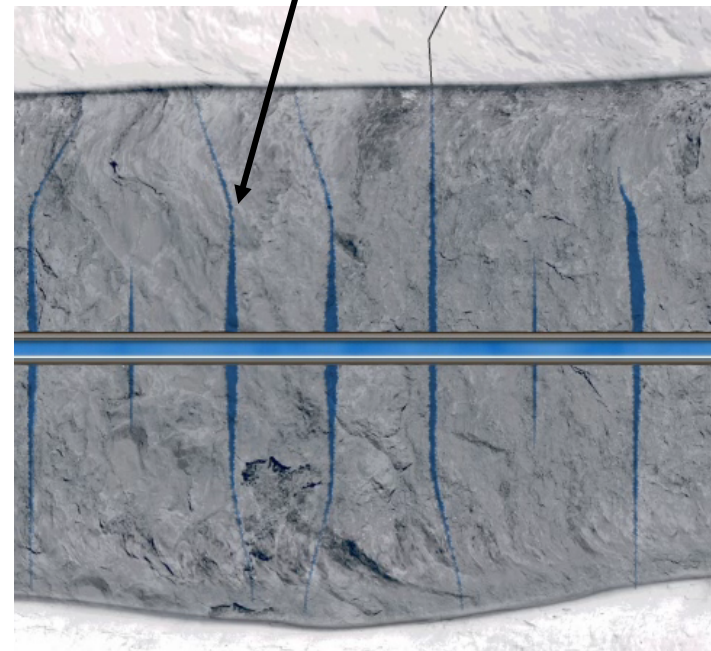
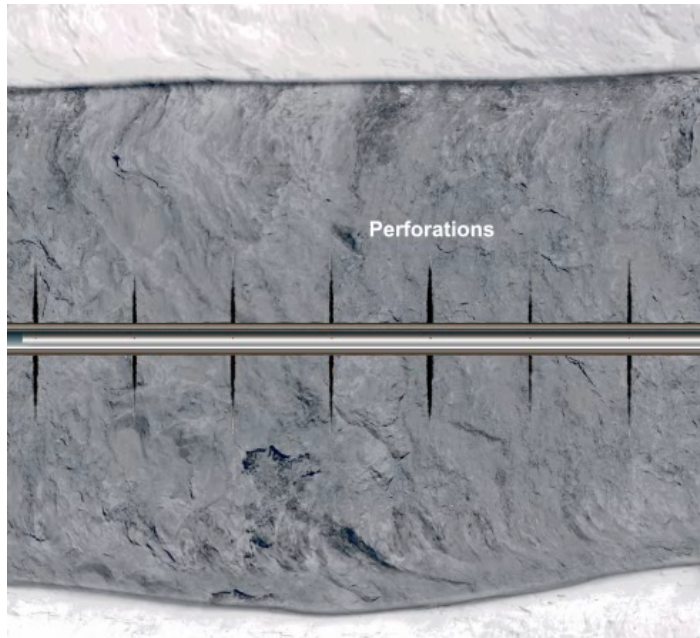
Movie



Hydraulic Fracturing Simulation

Current Focus: 3-D effects not captured by available simulators

- Initial stages of fracture propagation: Fracture re-orientation





Hydraulic Fracturing Regimes

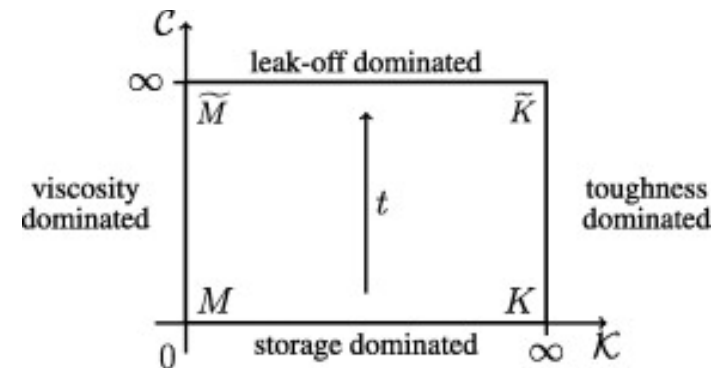
- Fracture propagation is governed by
 - two competing energy dissipation mechanisms: Viscous flow and fracturing process;
 - two competing storage mechanisms: In the fracture and in the porous matrix

Dimensionless toughness

$$\mathcal{K} = \frac{4K_{Ic}}{\sqrt{\pi}} \left(\frac{1}{3Q_0 E'^3 \mu} \right)^{1/4}$$

Leak-off coefficient

$$\mathcal{C} = 2C_L \left(\frac{E' t}{12\mu Q_0^3} \right)^{1/6}$$



Hydraulic fracture parametric space*

Current Focus: Storage-toughness dominated regime

- Low permeability reservoirs: Neglect flow of hydraulic fluid across crack faces
- High confining stress:
 - Fluid lag in frac. \ll frac. size \leftrightarrow const press. in frac. \leftrightarrow toughness dom.
- Brittle elastic material
- Early-time solution \rightarrow storage dominated

*[Carrier & Granet, EFM, 2013]



Hydraulic Fracturing Regimes

$$\mathcal{K} = \frac{4K_{Ic}}{\sqrt{\pi}} \left(\frac{1}{3Q_0 E'^3 \mu} \right)^{1/4} \quad \mathcal{C} = 2C_L \left(\frac{E't}{12\mu Q_0^3} \right)^{1/6}$$

\mathcal{K} = Dimensionless toughness

\mathcal{C} = Dimensionless leak-off coefficient

K_{Ic} = Mode-I fracture toughness

Q_0 = Injection rate

E' = Plane strain Young's modulus

μ = Fluid viscosity

C_L = Leak-off coefficient

t = time



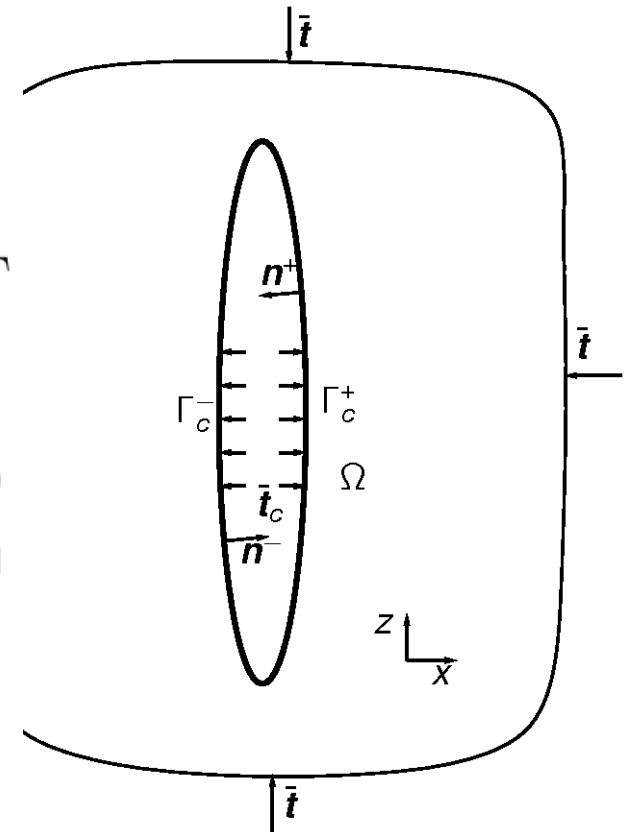
Weak Form at Propagation Step k

Find $\mathbf{u}^k \in H^1(\Omega)$, such that $\forall \mathbf{v}^k \in H^1(\Omega)$

$$\begin{aligned} & \int_{\Omega} \boldsymbol{\sigma}(\mathbf{u}^k) : \boldsymbol{\varepsilon}(\mathbf{v}^k) d\Omega \\ &= \int_{\Omega} \mathbf{b} \cdot \mathbf{v}^k d\Omega + \int_{\partial\Omega} \bar{\mathbf{t}} \cdot \mathbf{v}^k d\Gamma + \int_{\Gamma_c^{k+}} \bar{\mathbf{t}}_c^{k+} \cdot \llbracket \mathbf{v}^k \rrbracket d\Gamma \end{aligned}$$

where $\llbracket \mathbf{v}^k \rrbracket$ is the virtual displacement jump across the crack surface Γ^k at propagation step k and

$$\bar{\mathbf{t}}_c^{k+} = -p^k \mathbf{n}^{k+} = p^k \mathbf{n}^{k-}$$



Cross section of fracture



Outline

- Motivation and problem set up
- Generalized FEM for 3-D hydraulic fractures
- Examples
- Closing remarks





Early works on Generalized FEMs

- Babuska, Caloz and Osborn, 1994 (Special FEM).
- Duarte and Oden, 1995 (Hp Clouds).
- Babuska and Melenk, 1995 (PUFEM).
- Oden, Duarte and Zienkiewicz, 1996 (Hp Clouds/GFEM).
- Duarte, Babuska and Oden, 1998 (GFEM).
- Belytschko et al., 1999 (Extended FEM).
- Strouboulis, Babuska and Copps, 2000 (GFEM).

- Basic idea:
 - Use a partition of unity to build Finite Element shape functions

- Review paper

Belytschko T., Gracie R. and Ventura G. A review of extended/generalized finite element methods for material modeling, *Mod. Simul. Matl. Sci. Eng.*, 2009

“The XFEM and GFEM are basically identical methods: the name generalized finite element method was adopted by the Texas school in 1995–1996 and the name extended finite element method was coined by the Northwestern school in 1999.”



Generalized Finite Element Method

- GFEM can be interpreted as a FEM with shape functions built using the concept of a partition of unity:

GFEM shape function = FE shape function * enrichment function

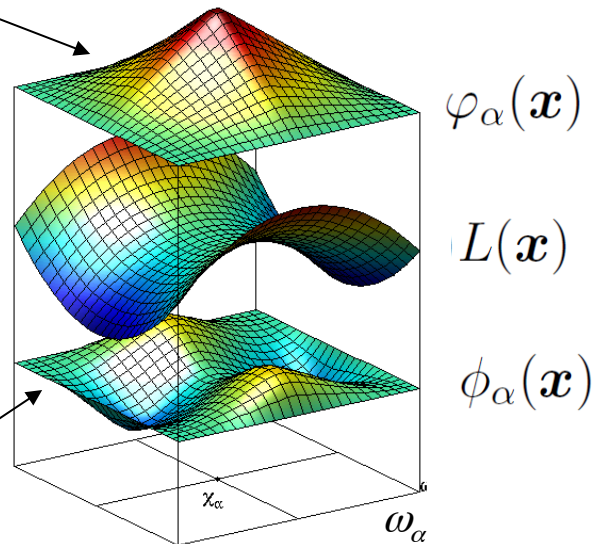
$$\phi_{\alpha}(\mathbf{x}) = \varphi_{\alpha}(\mathbf{x}) L(\mathbf{x})$$

- Allows construction of shape functions incorporating a-priori knowledge about solution

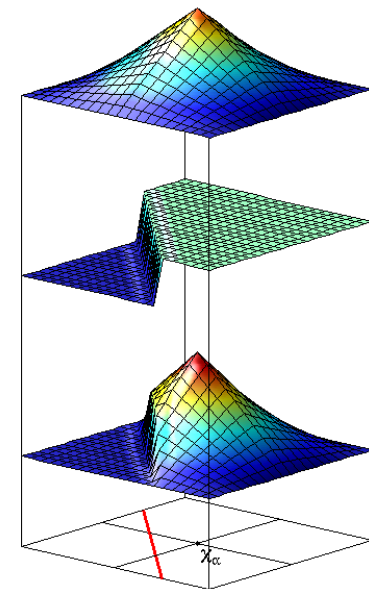
Linear FE shape function

Enrichment function

GFEM shape function



[Oden, Duarte & Zienkiewicz, 1996]

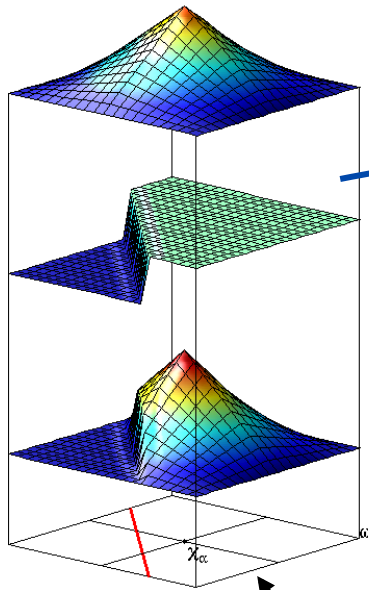


Discontinuous enrichment
[Moes et al.]



GFEM Approximation for 3-D Cracks

$$\mathbf{X}^{hp}(\Omega) = \left\{ \mathbf{u} = \sum_{\alpha=1}^N \underbrace{\varphi_{\alpha}(\mathbf{x})}_{\text{PoU}} \left[\underbrace{\hat{\mathbf{u}}_{\alpha}(\mathbf{x})}_{\text{polynomial}} + \underbrace{\mathcal{H}\tilde{\mathbf{u}}_{\alpha}(\mathbf{x})}_{\text{discontinuous}} + \underbrace{\check{\mathbf{u}}_{\alpha}(\mathbf{x})}_{\text{singular}} \right] \right\}$$



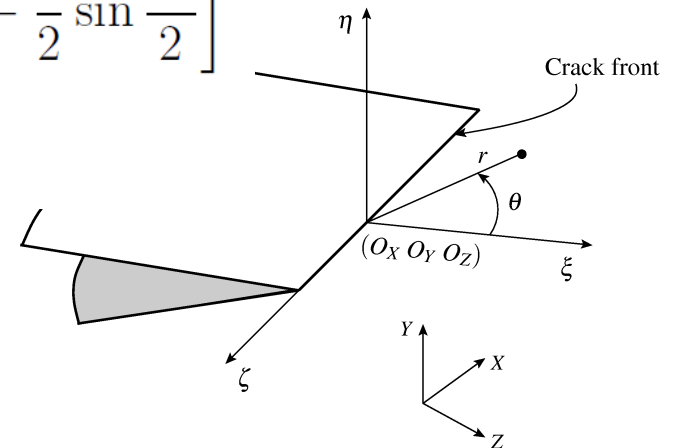
cloud or patch α

$$\check{L}_{\alpha 1}^{\xi}(r, \theta) = \sqrt{r} \left[\left(\kappa - \frac{1}{2} \right) \cos \frac{\theta}{2} - \frac{1}{2} \cos \frac{3\theta}{2} \right]$$

$$\check{L}_{\alpha 1}^{\eta}(r, \theta) = \sqrt{r} \left[\left(\kappa + \frac{1}{2} \right) \sin \frac{\theta}{2} - \frac{1}{2} \sin \frac{3\theta}{2} \right]$$

$$\check{L}_{\alpha 1}^{\zeta}(r, \theta) = \sqrt{r} \sin \frac{\theta}{2}$$

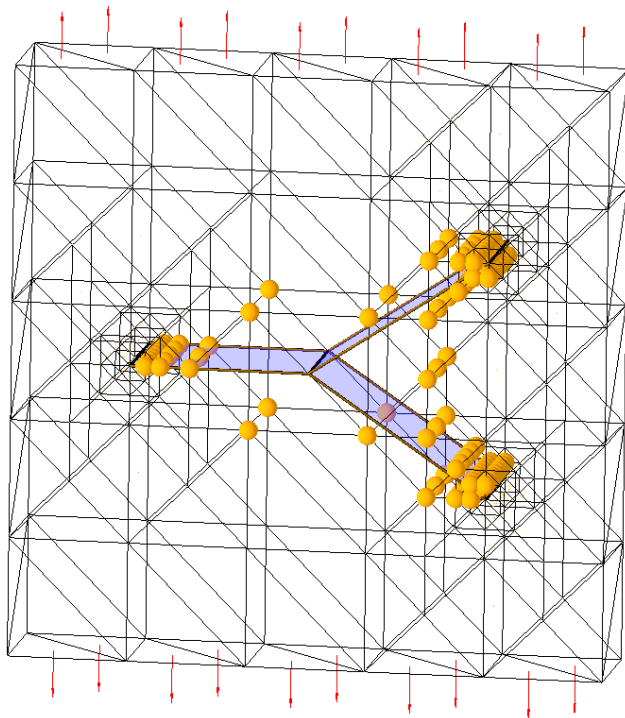
[Duarte and Oden 1996]





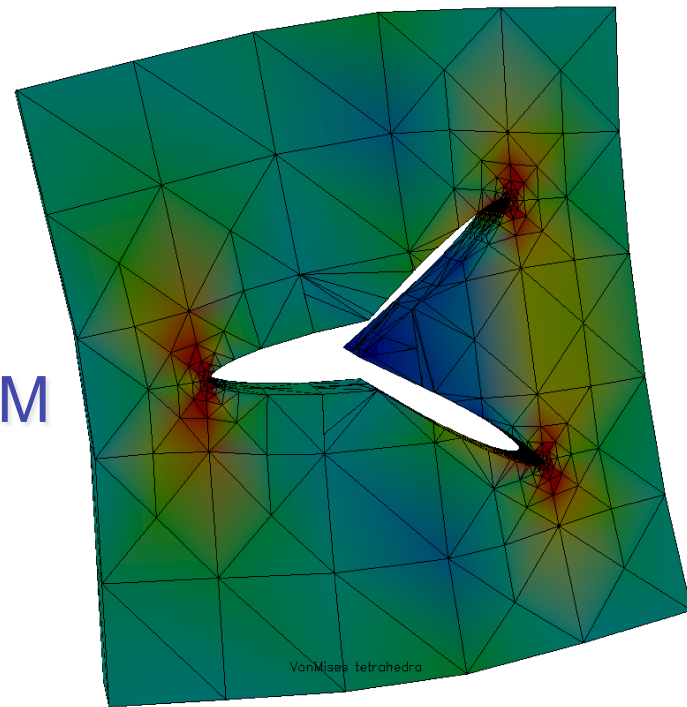
Modeling Cracks with hp-GFEM

- Discontinuities modeled via enrichment functions, *not* the FEM mesh
- Mesh refinement *still required* for acceptable accuracy



● = Nodes with discontinuous enrichments

hp-GFEM



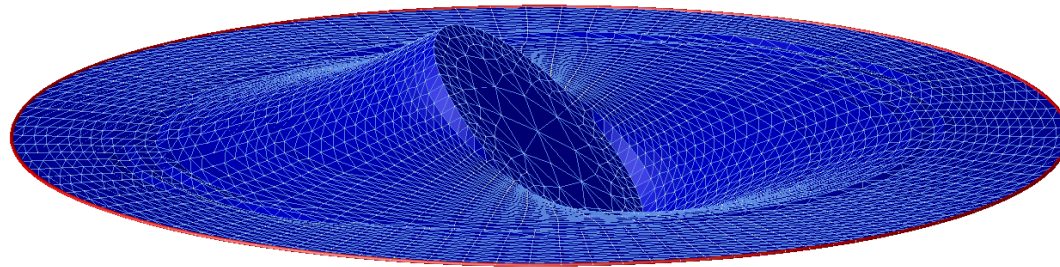
Von Mises stress

[Duarte et al., International Journal Numerical Methods in Engineering, 2007]

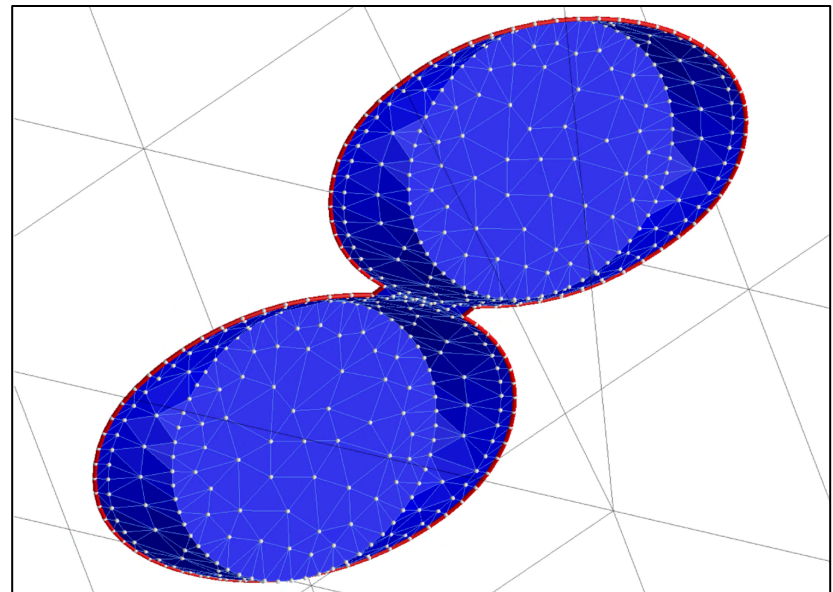
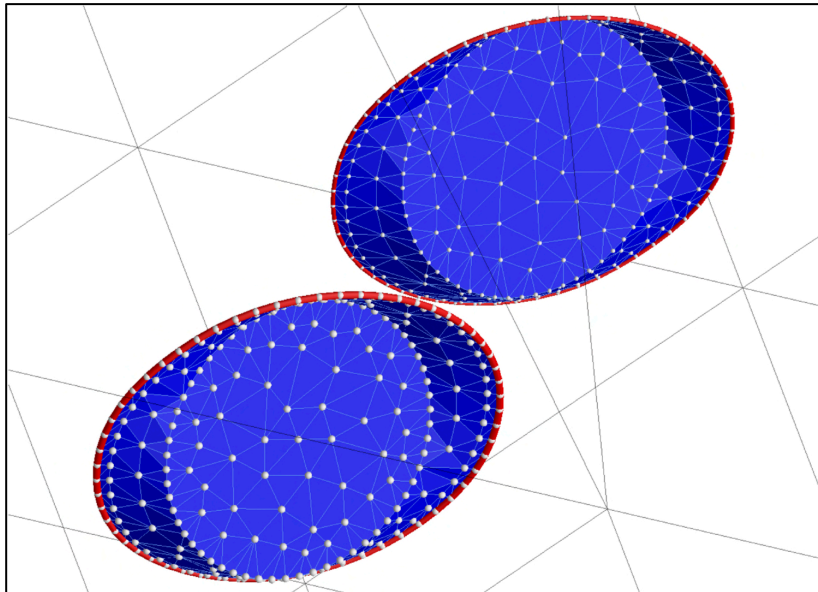


3-D Crack Surface Representation

- High-fidelity explicit representation of crack surfaces [Duarte et al., 2001, 2009]

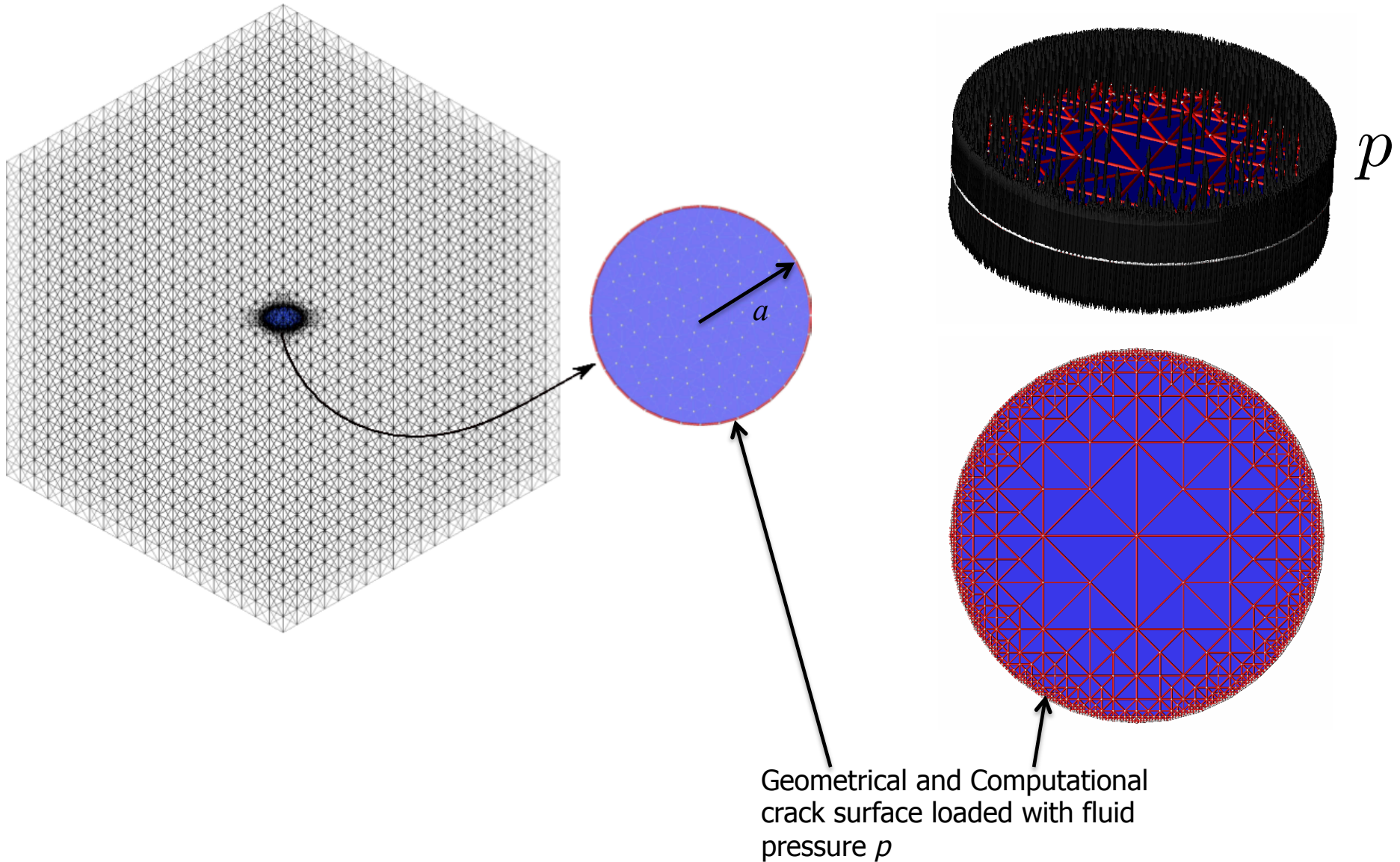


- Coalescence of fractures [Garzon et al., 2013]



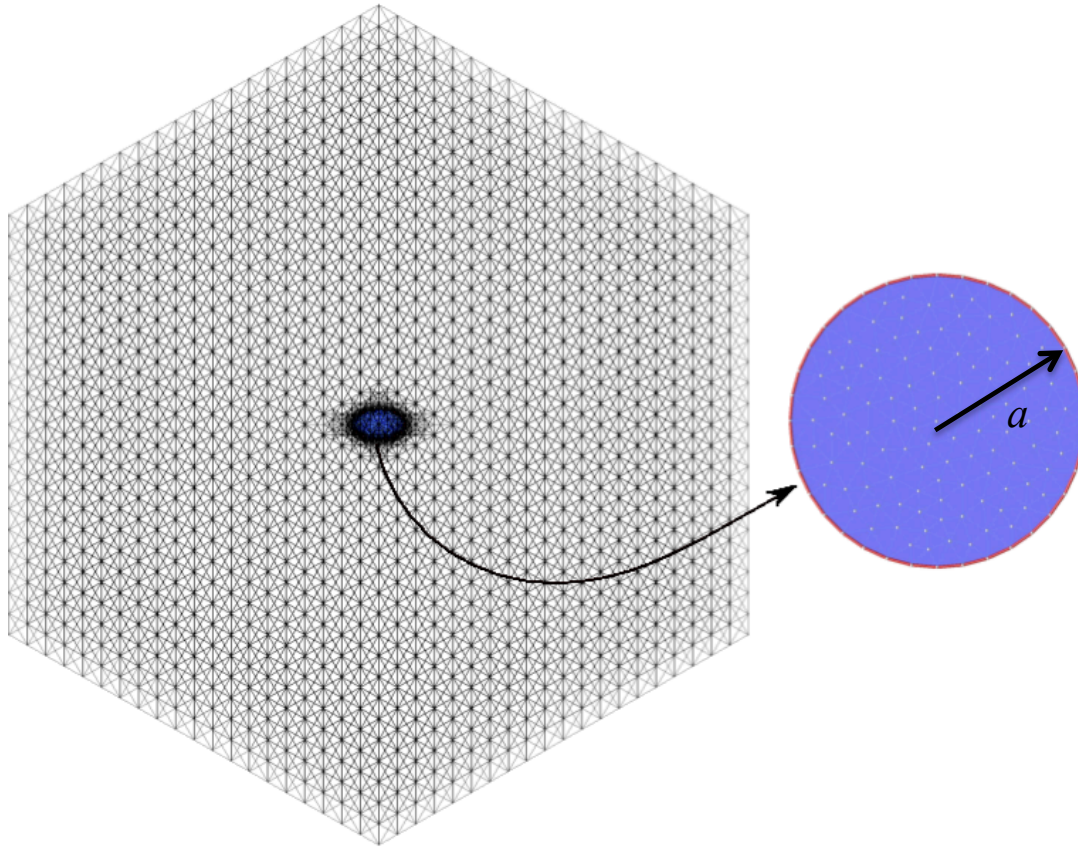


Verification: Propagation of Penny Shaped Crack





Verification: Propagation of Penny Shaped Crack



Critical pressure

$$p_c(a) = \left(\frac{E^* G_c \pi}{4a} \right)^{1/2}$$

Adopt [Bourdin et al. 2012]:

$$E^* = 1$$

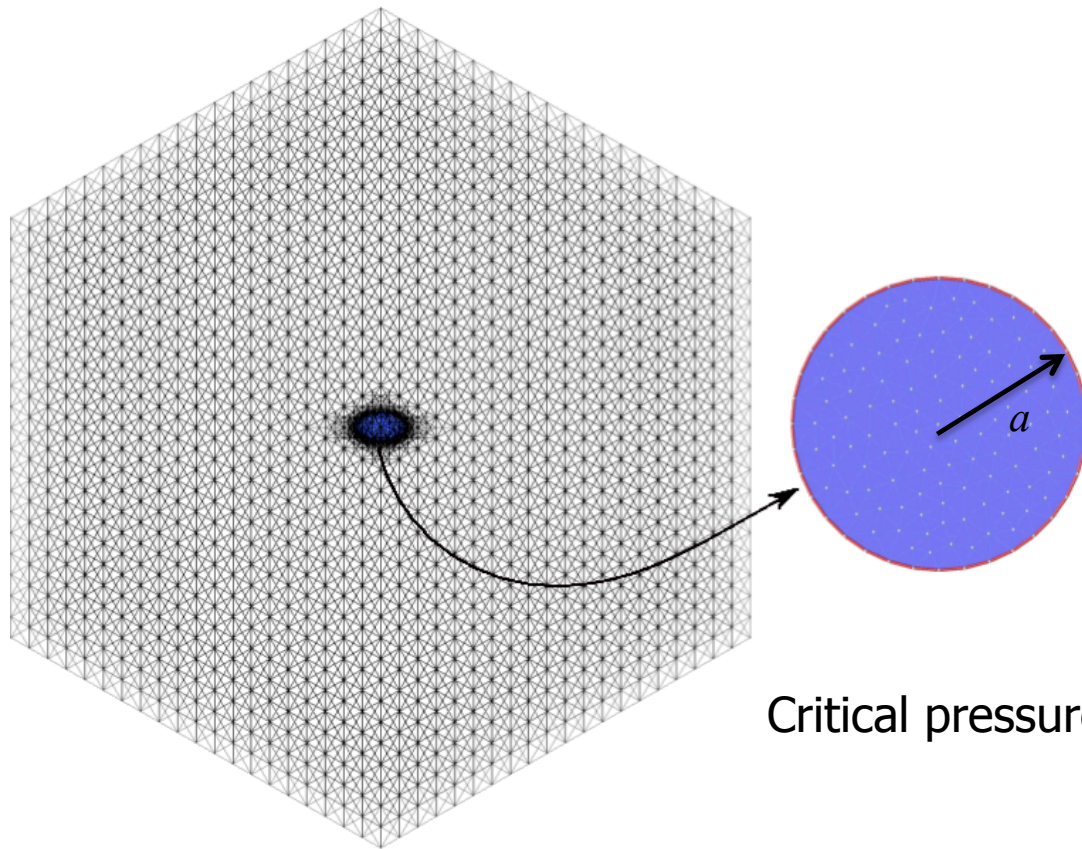
$$G_c = 1.91 \times 10^{-9}$$

$$a = 0.5$$

$$p_c(0.5) = 5.477 \times 10^{-5}$$



Propagation of Penny Shaped Crack



Critical pressure

GFEM Model

$$h_{\min}/a = 0.016$$

$$h_{\max}/a = 0.027$$

$$p\text{-order} = 2$$

$$N = 215\,376 \text{ } dofs$$

$$T = 5.25 \text{ } min$$

$$p_c^h(a) = \frac{K_c}{K(a)} p$$

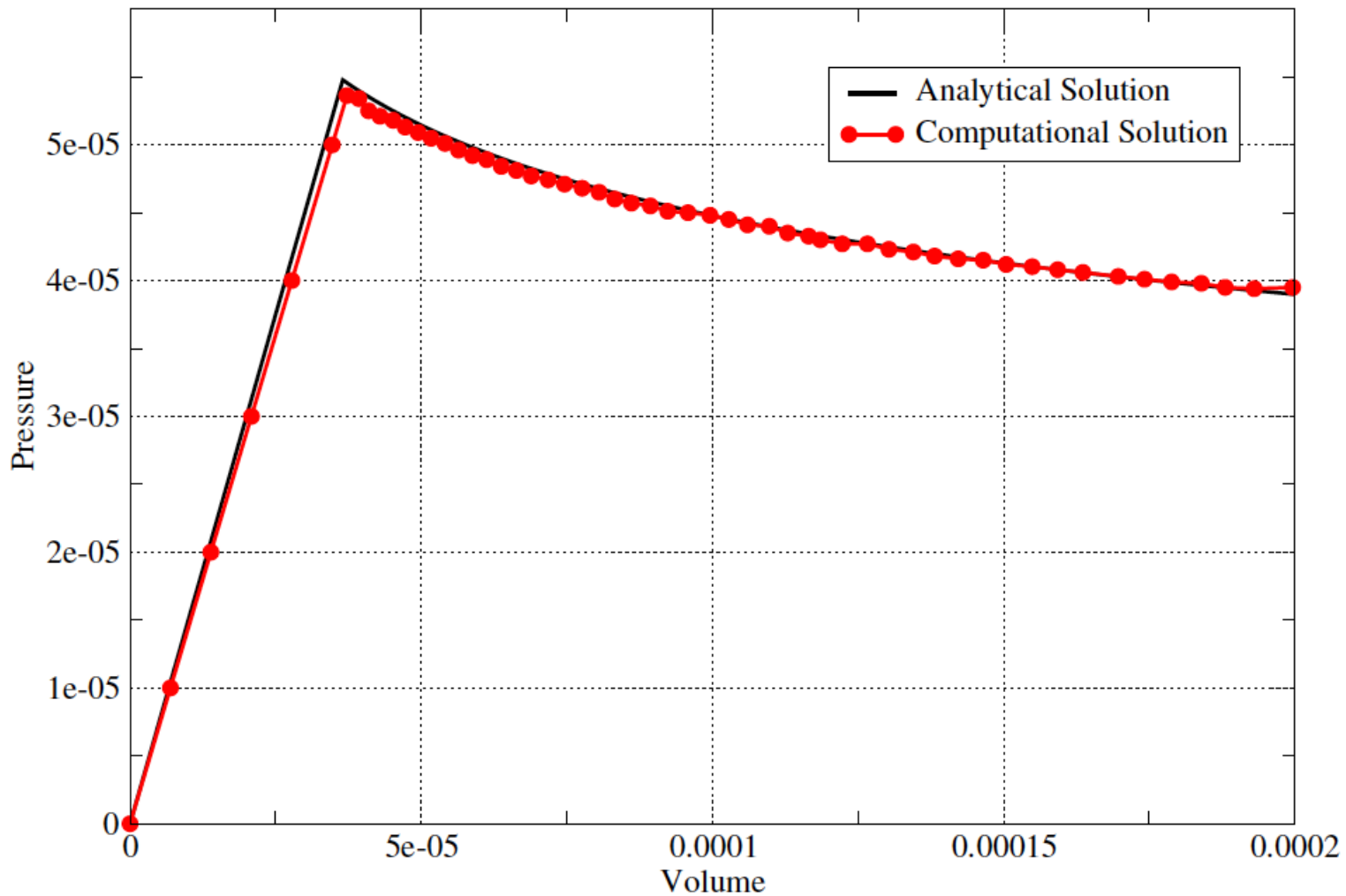
$$p_c^h(0.5) = 5.415 \times 10^{-5}$$

$$e_r(p_c) = 1.15\%$$



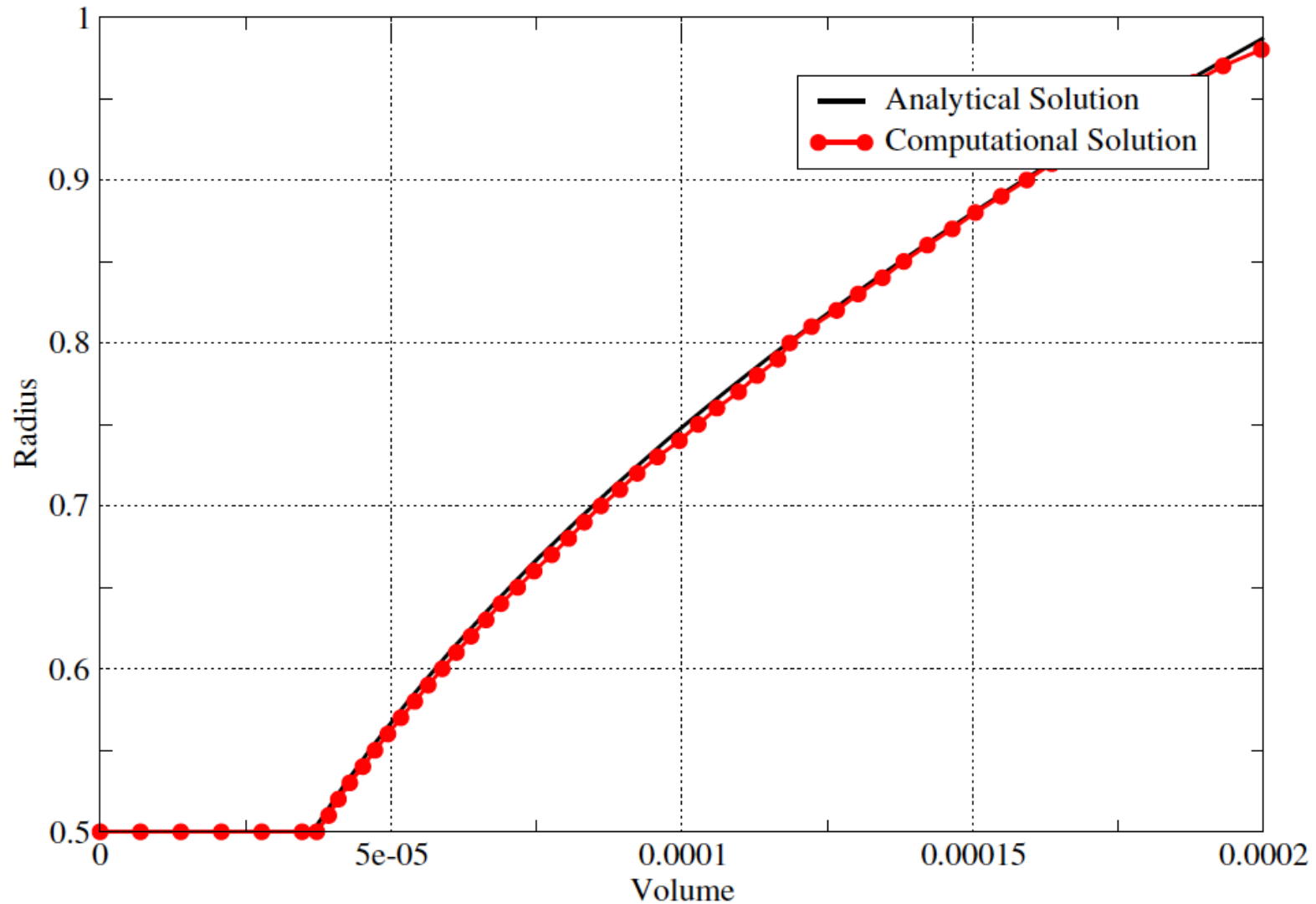
Propagation of Penny Shaped Crack

Repeating for each step of crack propagation



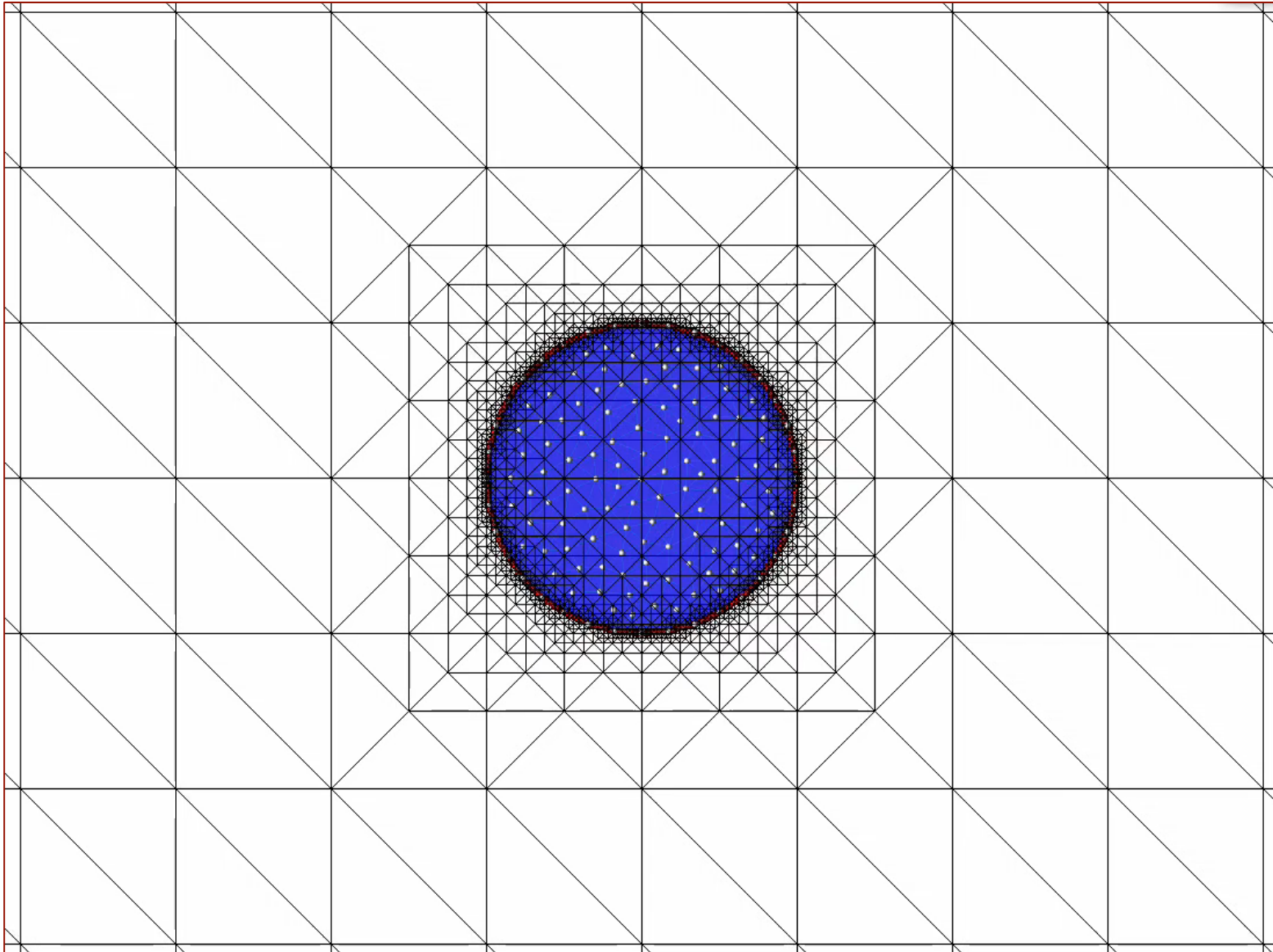


Propagation of Penny Shaped Crack





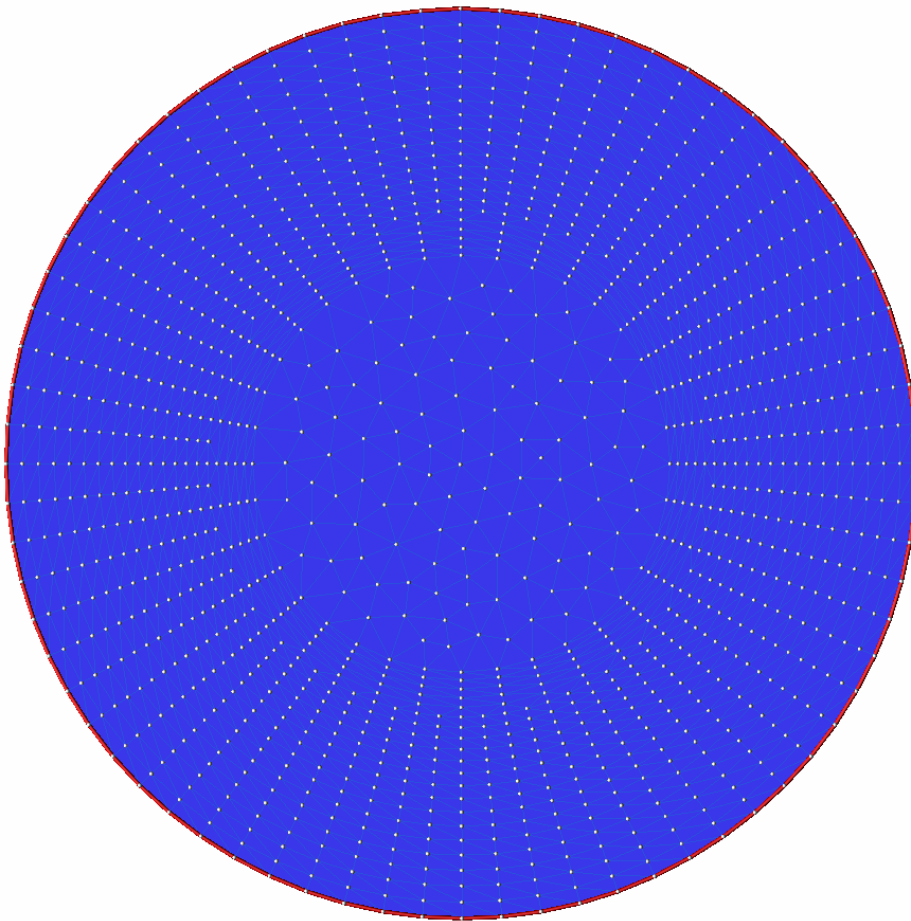
Adaptive mesh refinement follows crack front



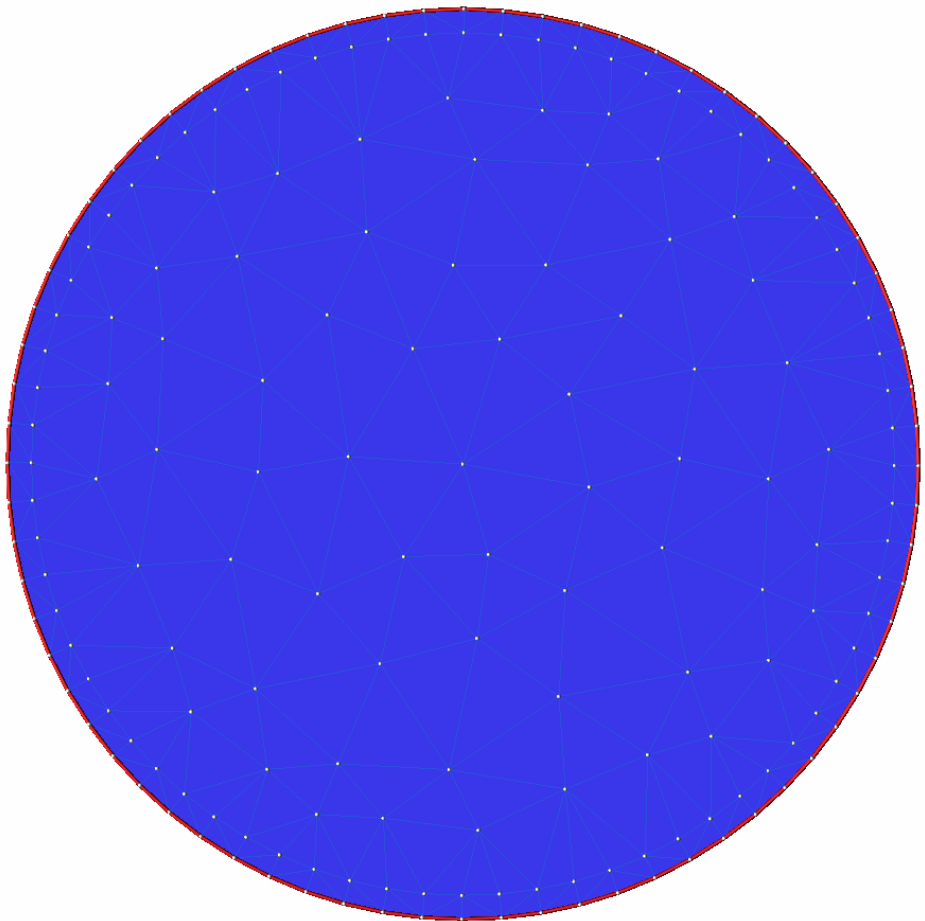


Propagation of Penny Shaped Crack

Crack surface at step 20



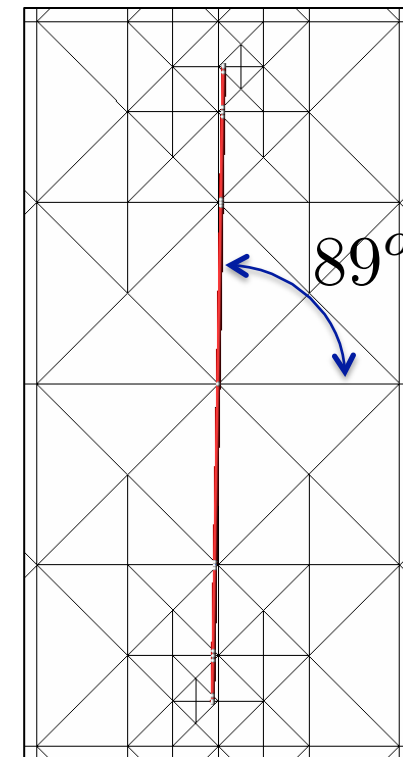
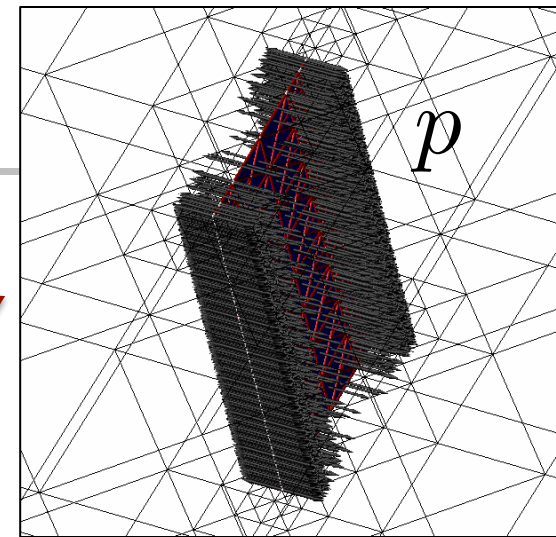
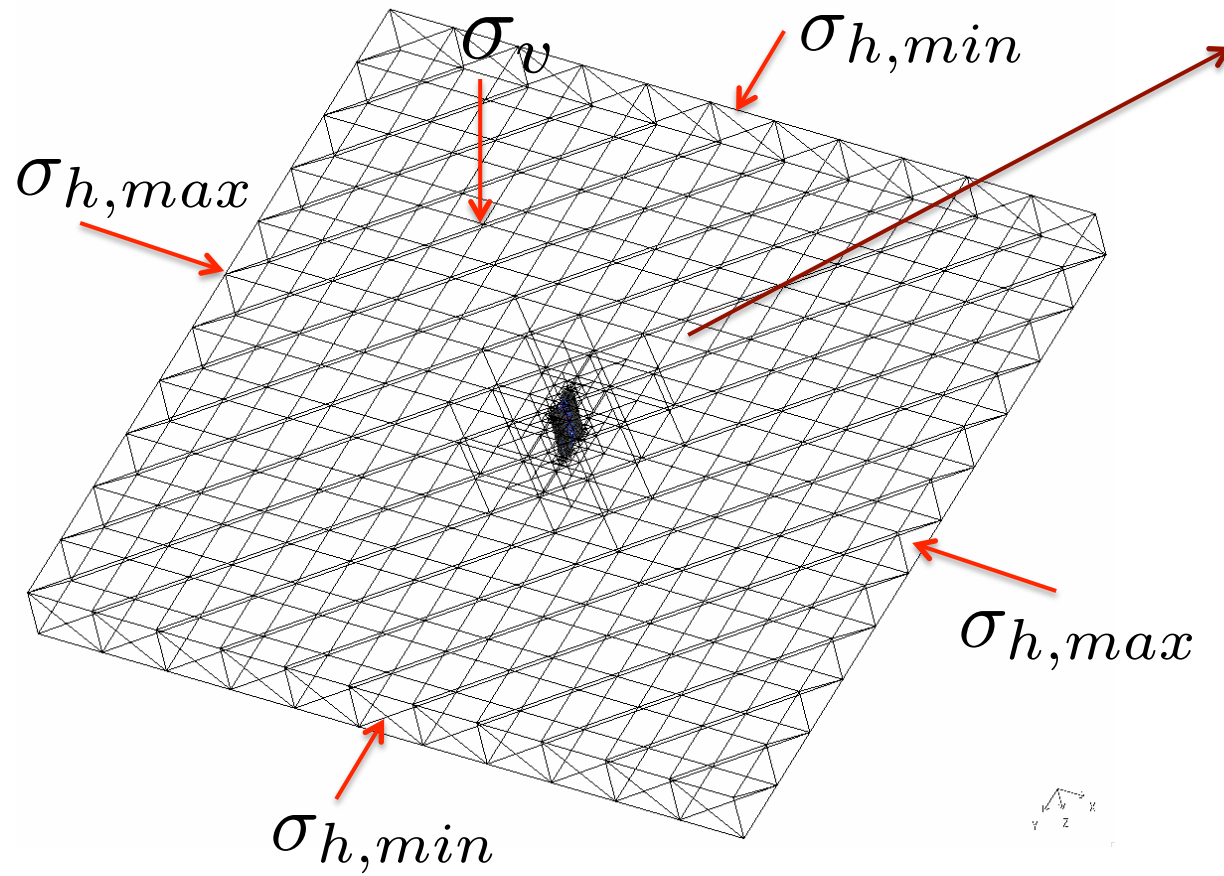
Adaptive update of crack surface



Remeshing of crack surface



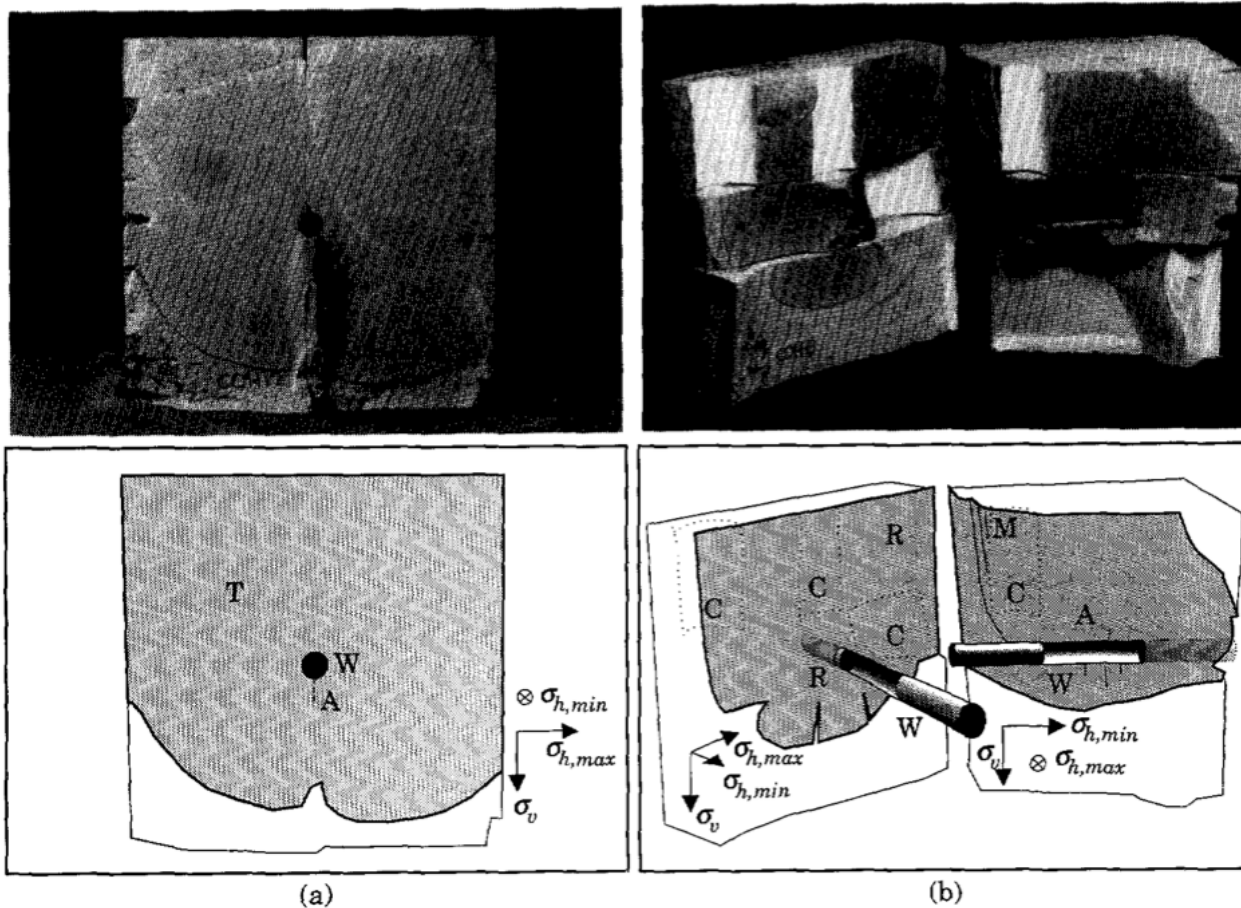
Verification: Crack Reorientation





Crack Reorientation

Same parameters as those used by Weijers [1] in experiment COH13

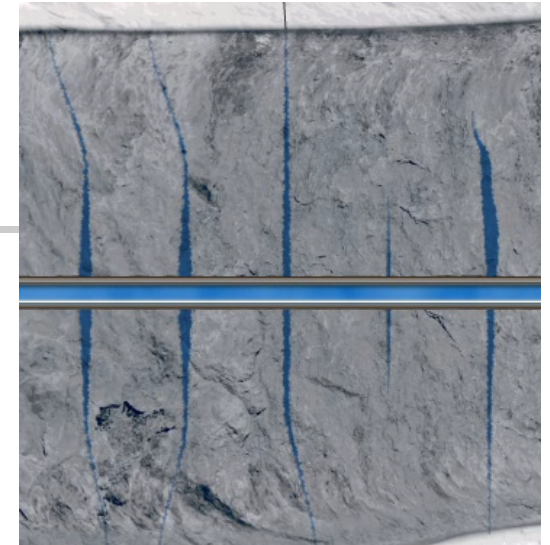
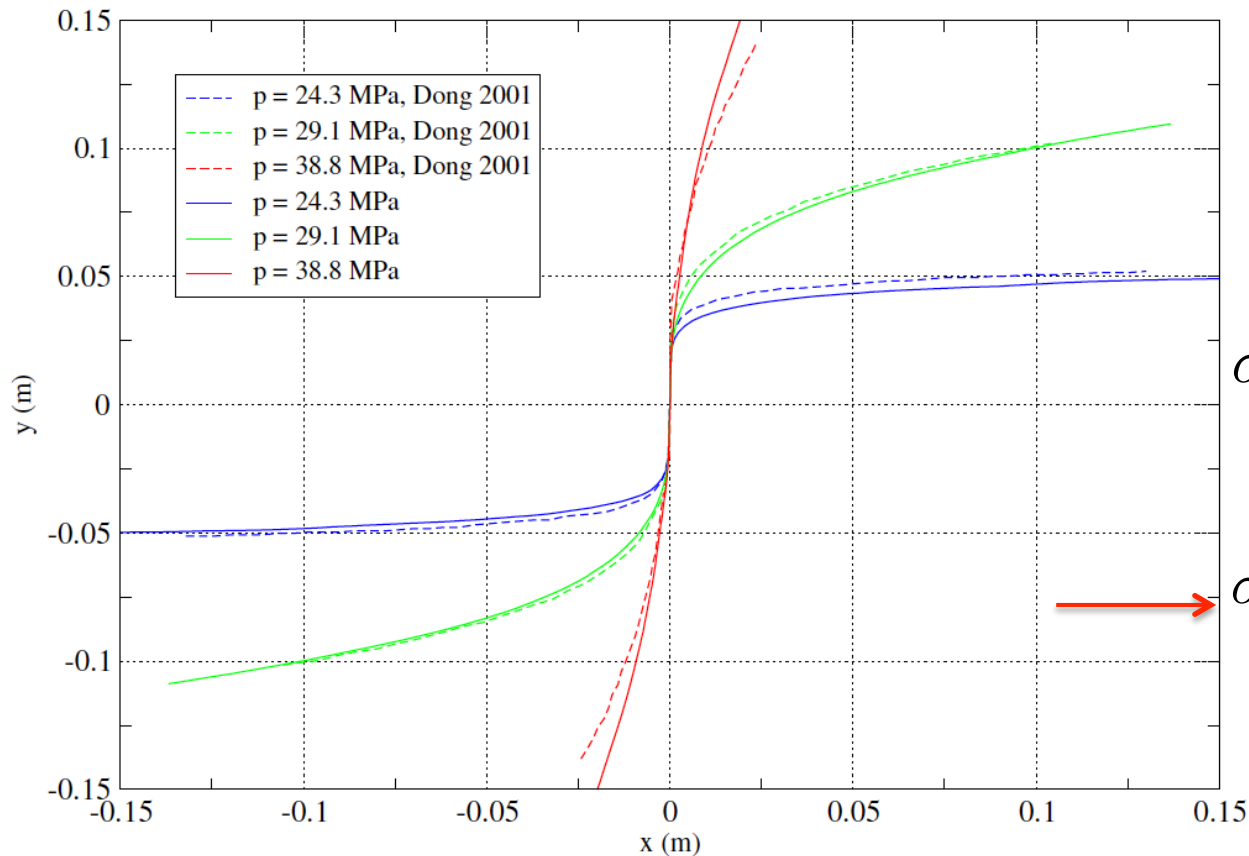


[1] Weijers L. The near-wellbore geometry of hydraulic fractures initiated from horizontal and deviated wells. Ph.D. Dissertation, Delft University of Technology, 1995.



Crack Reorientation

Crack paths for different pressures on crack



$\sigma_{h,min} = 9.7$ MPa

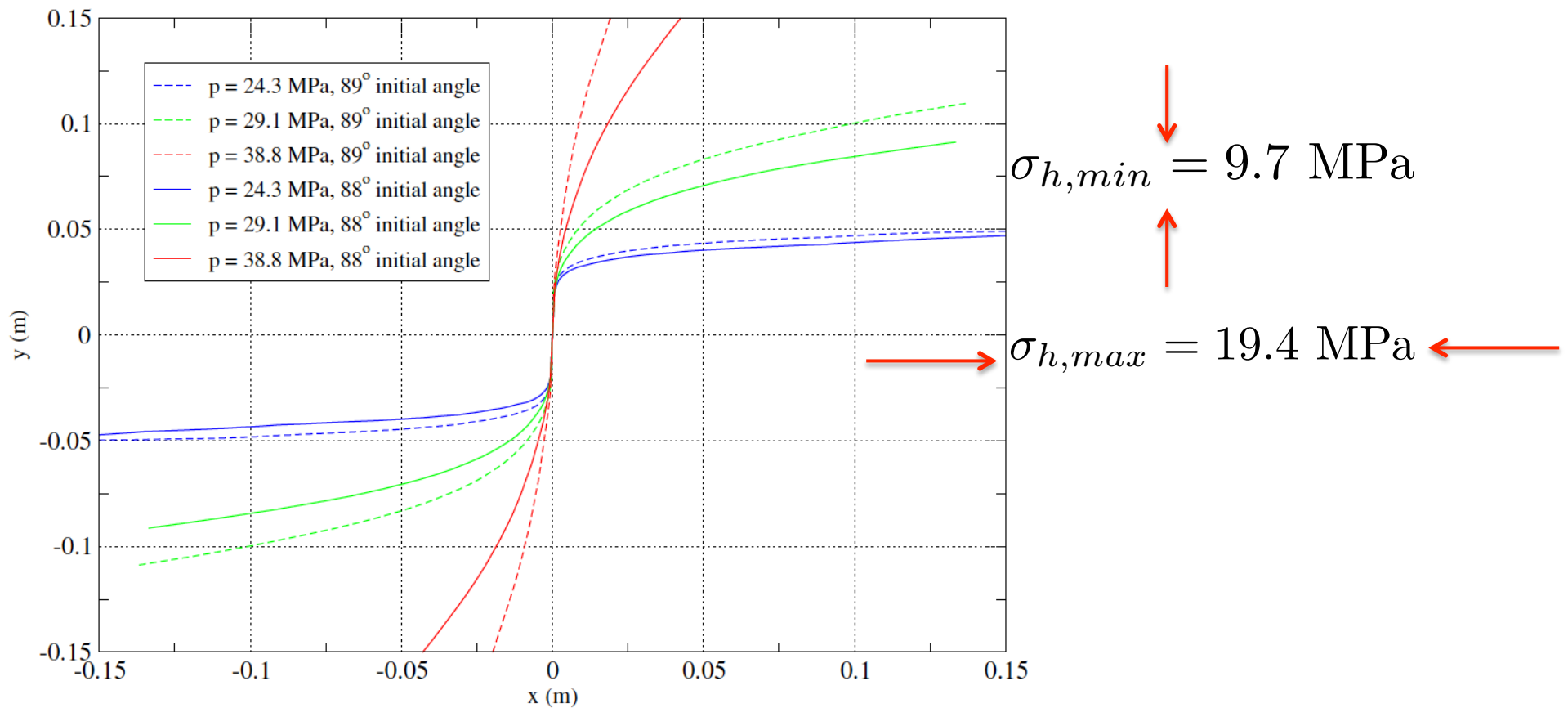
$\sigma_{h,max} = 19.4$ MPa

[2] C.Y. Dong and C.J. de Pater. Numerical implementation of displacement discontinuity method and its application in hydraulic fracturing. *Computer Methods in Applied Mechanics and Engineering*, 191:745–760, 2001.



Crack Reorientation

Crack paths for different pressures on crack and initial orientation

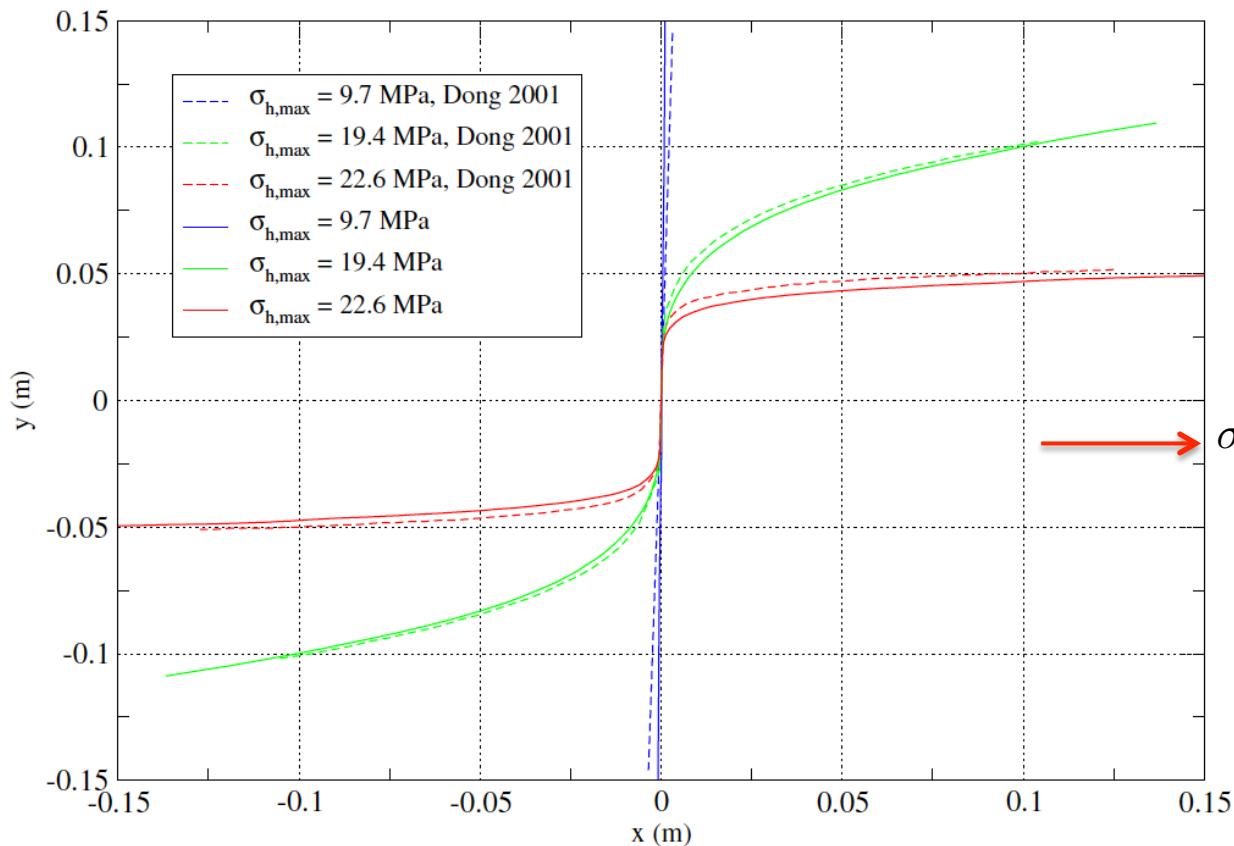


C.Y. Dong and C.J. de Pater. Numerical implementation of displacement discontinuity method and its application in hydraulic fracturing. *Computer Methods in Applied Mechanics and Engineering*, 191:745–760, 2001.



Crack Reorientation

Crack paths for different $\sigma_{h,max}$



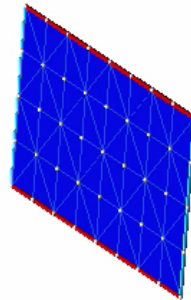
$\sigma_{h,min} = 9.7 \text{ MPa}$

$\sigma_{h,max} = 9.7 - 22.6 \text{ MPa}$

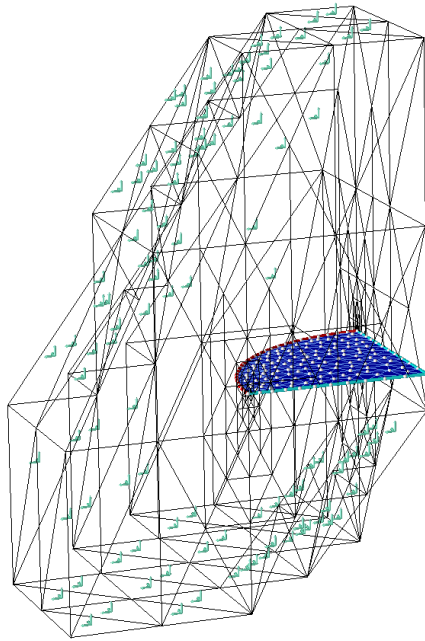
$p = 29.1 \text{ MPa}$



Crack Reorientation



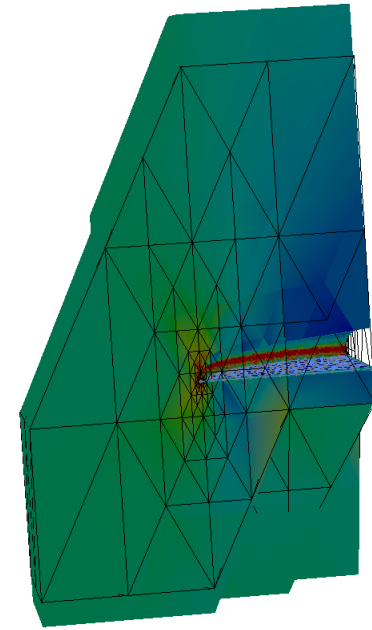
$$\sigma_{h,min} = 9.7 \text{ MPa} \quad \sigma_{h,max} = 19.4 \text{ MPa} \quad p = 24.3 \text{ MPa}$$



Questions?

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VonMises tetrahedra



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